

INTERNATIONAL STANDARD

**Adjustable speed electrical power drive systems –
Part 7-204: Generic interface and use of profiles for power drive systems –
Profile type 4 specification**



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INTERNATIONAL
ELECTROTECHNICAL
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PRICE CODE

CONTENTS

FOREWORD.....	35
INTRODUCTION.....	37
1 Scope.....	40
2 Normative references	40
3 Terms, definitions and abbreviated terms	40
3.1 Terms and definitions	40
3.2 Abbreviated terms	45
4 General	46
5 Data types.....	46
6 Short description of SERCOS data exchange	46
6.1 General.....	46
6.2 Synchronisation.....	47
7 Application function groups	47
7.1 General.....	47
7.2 Scaling of operation data.....	48
7.2.1 General	48
7.2.2 Scaling of position data	48
7.2.3 Scaling of velocity data.....	49
7.2.4 Scaling of torque/force data.....	51
7.2.5 Scaling of acceleration data and jerk data	53
7.2.6 Scaling of temperature data.....	55
7.3 Drive parameters.....	55
7.3.1 Velocity loop parameters	55
7.3.2 Position loop parameters	56
7.3.3 Current loop parameters.....	57
7.3.4 Drive limit values	57
7.3.5 General drive parameters	57
7.3.6 Spindle parameters	58
7.3.7 Spindle synchronous operation.....	58
7.4 Mechanics.....	59
7.4.1 Feedback systems.....	59
7.4.2 Feed constant.....	59
7.4.3 Gear train	60
7.4.4 Polarities	60
7.4.5 Parameter sets and gear ratios.....	61
7.4.6 Switching of parameter sets and gear ratio	62
7.5 Drive operation modes	62
7.5.1 General	62
7.5.2 Selection of the operation mode	63
7.5.3 Switching of the operation mode.....	64
7.6 Homing.....	66
7.6.1 General	66
7.6.2 Drive controlled homing procedure command	66
7.6.3 Control unit controlled homing procedure command	68
7.7 Measurements.....	71

7.8	Position spindle procedure command	72
7.8.1	General	72
7.8.2	Spindle Positioning when the function is started	73
7.8.3	New position values while the procedure command is active	74
7.8.4	Switching the positioning mode angle position/relative offset while the procedure command is active	74
7.9	Velocity window	75
7.10	Position switches	76
7.10.1	General	76
7.10.2	Position switch mode	77
7.10.3	Cam switch mode	77
7.11	PDS state machine control	78
7.11.1	Control and status word	78
7.11.2	Starting/stopping functions (State machine)	80
7.12	Park axis procedure command	83
7.13	Positive stop drive procedure command	83
7.14	Drive controlled synchronous operation procedure command	84
7.14.1	General	84
7.14.2	Synchronisation of the synchronous spindle to the lead spindle with a fixed angular offset	84
7.14.3	New synchronous position offset after synchronisation	85
7.14.4	New speed ratio after synchronisation	85
7.15	Drive controlled gear engaging procedure command	86
8	Identification numbers in numerical order	87
9	Description of identification numbers	100
9.1	IDN S-0-0005 Minimum feedback processing time (t_5)	100
9.1.1	Attributes	100
9.1.2	Description	101
9.2	IDN S-0-0007 Feedback acquisition capture point (t_4)	101
9.2.1	Attributes	101
9.2.2	Description	101
9.3	IDN S-0-0011 Class 1 diagnostic (C1D)	101
9.3.1	Attributes	101
9.3.2	Description	102
9.4	IDN S-0-0012 Class 2 diagnostic (C2D)	103
9.4.1	Attributes	103
9.4.2	Description	103
9.5	IDN S-0-0013 Class 3 diagnostic (C3D)	104
9.5.1	Attributes	104
9.5.2	Description	104
9.6	IDN S-0-0016 Configuration list of AT	105
9.6.1	Attributes	105
9.6.2	Description	105
9.7	IDN S-0-0017 IDN-list of all operation data	105
9.7.1	Attributes	105
9.7.2	Description	105
9.8	IDN S-0-0018 IDN-list of operation data for CP2	105
9.8.1	Attributes	105
9.8.2	Description	106

9.9	IDN S-0-0019 IDN-list of operation data for CP3.....	106
9.9.1	Attributes.....	106
9.9.2	Description	106
9.10	IDN S-0-0020 IDN-list of operation data for CP4.....	106
9.10.1	Attributes.....	106
9.10.2	Description	107
9.11	IDN S-0-0021 IDN-list of invalid operation data for CP2.....	107
9.11.1	Attributes.....	107
9.11.2	Description	107
9.12	IDN S-0-0022 IDN-list of invalid operation data for CP3.....	107
9.12.1	Attributes.....	107
9.12.2	Description	108
9.13	IDN S-0-0023 IDN-list of invalid operation data for CP4.....	108
9.13.1	Attributes.....	108
9.13.2	Description	108
9.14	IDN S-0-0025 IDN-list of all procedure commands.....	108
9.14.1	Attributes.....	108
9.14.2	Description	109
9.15	IDN S-0-0026 Configuration list for signal status word.....	109
9.15.1	Attributes.....	109
9.15.2	Description	109
9.16	IDN S-0-0027 Configuration list for signal control word.....	109
9.16.1	Attributes.....	109
9.16.2	Description	110
9.17	IDN S-0-0030 Manufacturer version.....	110
9.17.1	Attributes.....	110
9.17.2	Description	110
9.18	IDN S-0-0031 Hardware version	110
9.18.1	Attributes.....	110
9.18.2	Description	111
9.19	IDN S-0-0032 to S-0-0035 Primary operation mode, secondary operation modes 1 to 3	111
9.19.1	Attributes.....	111
9.19.2	Description	111
9.20	IDN S-0-0036 Velocity command value.....	111
9.20.1	Attributes.....	111
9.20.2	Description	112
9.21	IDN S-0-0037 Additive velocity command value.....	112
9.21.1	Attributes.....	112
9.21.2	Description	112
9.22	IDN S-0-0038 Positive velocity limit value	112
9.22.1	Attributes.....	112
9.22.2	Description	113
9.23	IDN S-0-0039 Negative velocity limit value	113
9.23.1	Attributes.....	113
9.23.2	Description	113
9.24	IDN S-0-0040 Velocity feedback value 1.....	113
9.24.1	Attributes.....	113
9.24.2	Description	114

9.25	IDN S-0-0041 Homing velocity.....	114
9.25.1	Attributes.....	114
9.25.2	Description.....	114
9.26	IDN S-0-0042 Homing acceleration.....	114
9.26.1	Attributes.....	114
9.26.2	Description.....	115
9.27	IDN S-0-0043 Velocity polarity parameter.....	115
9.27.1	Attributes.....	115
9.27.2	Description.....	115
9.28	IDN S-0-0044 Velocity data scaling type.....	116
9.28.1	Attributes.....	116
9.28.2	Description.....	116
9.29	IDN S-0-0045 Velocity data scaling factor.....	117
9.29.1	Attributes.....	117
9.29.2	Description.....	117
9.30	IDN S-0-0046 Velocity data scaling exponent.....	117
9.30.1	Attributes.....	117
9.30.2	Description.....	118
9.31	IDN S-0-0047 Position command value.....	118
9.31.1	Attributes.....	118
9.31.2	Description.....	118
9.32	IDN S-0-0048 Additive position command value.....	118
9.32.1	Attributes.....	118
9.32.2	Description.....	119
9.33	IDN S-0-0049 Positive position limit value.....	119
9.33.1	Attributes.....	119
9.33.2	Description.....	119
9.34	IDN S-0-0050 Negative position limit value.....	120
9.34.1	Attributes.....	120
9.34.2	Description.....	120
9.35	IDN S-0-0051 Position feedback value 1 (motor feedback).....	120
9.35.1	Attributes.....	120
9.35.2	Description.....	121
9.36	IDN S-0-0052 Reference distance 1.....	121
9.36.1	Attributes.....	121
9.36.2	Description.....	121
9.37	IDN S-0-0053 Position feedback value 2 (external feedback).....	121
9.37.1	Attributes.....	121
9.37.2	Description.....	122
9.38	IDN S-0-0054 Reference distance 2.....	122
9.38.1	Attributes.....	122
9.38.2	Description.....	122
9.39	IDN S-0-0055 Position polarity parameters.....	122
9.39.1	Attributes.....	122
9.39.2	Description.....	123
9.40	IDN S-0-0057 Position window.....	123
9.40.1	Attributes.....	123
9.40.2	Description.....	124
9.41	IDN S-0-0058 Reversal clearance.....	124

9.41.1	Attributes	124
9.41.2	Description	124
9.42	IDN S-0-0059 Position switch flag parameter	125
9.42.1	Attributes	125
9.42.2	Description	125
9.43	IDN S-0-0060 to S-0-0075 Position switch points on 1-16	125
9.43.1	Attributes	125
9.43.2	Description	126
9.44	IDN S-0-0076 Position data scaling type	126
9.44.1	Attributes	126
9.44.2	Description	126
9.45	IDN S-0-0077 Linear position data scaling factor	127
9.45.1	Attributes	127
9.45.2	Description	127
9.46	IDN S-0-0078 Linear position data scaling exponent	127
9.46.1	Attributes	127
9.46.2	Description	128
9.47	IDN S-0-0079 Rotational position resolution	128
9.47.1	Attributes	128
9.47.2	Description	128
9.48	IDN S-0-0080 Torque command value	129
9.48.1	Attributes	129
9.48.2	Description	129
9.49	IDN S-0-0082 Positive torque limit value	129
9.49.1	Attributes	129
9.49.2	Description	129
9.50	IDN S-0-0083 Negative torque limit value	130
9.50.1	Attributes	130
9.50.2	Description	130
9.51	IDN S-0-0084 Torque feedback value	130
9.51.1	Attributes	130
9.51.2	Description	130
9.52	IDN S-0-0085 Torque polarity parameter	131
9.52.1	Attributes	131
9.52.2	Description	131
9.53	IDN S-0-0086 Torque/force data scaling type	131
9.53.1	Attributes	131
9.53.2	Description	132
9.54	IDN S-0-0091 Bipolar velocity limit value	132
9.54.1	Attributes	132
9.54.2	Description	133
9.55	IDN S-0-0092 Bipolar torque limit value	133
9.55.1	Attributes	133
9.55.2	Description	133
9.56	IDN S-0-0093 Torque/force data scaling factor	133
9.56.1	Attributes	133
9.56.2	Description	134
9.57	IDN S-0-0094 Torque/force data scaling exponent	134
9.57.1	Attributes	134

9.57.2	Description	134
9.58	IDN S-0-0095 Diagnostic message	135
9.58.1	Attributes	135
9.58.2	Description	135
9.59	IDN S-0-0097 Mask class 2 diagnostic	135
9.59.1	Attributes	135
9.59.2	Description	135
9.60	IDN S-0-0098 Mask class 3 diagnostic	136
9.60.1	Attributes	136
9.60.2	Description	136
9.61	IDN S-0-0099 Reset class 1 diagnostic	136
9.61.1	Attributes	136
9.61.2	Description	137
9.62	IDN S-0-0100 Velocity loop proportional gain	137
9.62.1	Attributes	137
9.62.2	Description	137
9.63	IDN S-0-0101 Velocity loop integral action time	137
9.63.1	Attributes	137
9.63.2	Description	138
9.64	IDN S-0-0102 Velocity loop differential time	138
9.64.1	Attributes	138
9.64.2	Description	138
9.65	IDN S-0-0103 Modulo value	138
9.65.1	Attributes	138
9.65.2	Description	139
9.66	IDN S-0-0104 Position loop K_V -factor	139
9.66.1	Attributes	139
9.66.2	Description	140
9.67	IDN S-0-0105 Position loop integral action time	140
9.67.1	Attributes	140
9.67.2	Description	140
9.68	IDN S-0-0106 Current loop proportional gain 1	140
9.68.1	Attributes	140
9.68.2	Description	141
9.69	IDN S-0-0107 Current loop integral action time 1	141
9.69.1	Attributes	141
9.69.2	Description	141
9.70	IDN S-0-0108 Feedrate override	141
9.70.1	Attributes	141
9.70.2	Description	142
9.71	IDN S-0-0109 Motor peak current	142
9.71.1	Attributes	142
9.71.2	Description	142
9.72	IDN S-0-0110 Amplifier peak current	142
9.72.1	Attributes	142
9.72.2	Description	143
9.73	IDN S-0-0111 Motor continuous stall current	143
9.73.1	Attributes	143
9.73.2	Description	143

9.74	IDN S-0-0112 Amplifier rated current.....	143
9.74.1	Attributes.....	143
9.74.2	Description	144
9.75	IDN S-0-0113 Maximum motor speed	144
9.75.1	Attributes.....	144
9.75.2	Description	144
9.76	IDN S-0-0114 Load limit of the motor.....	144
9.76.1	Attributes.....	144
9.76.2	Description	145
9.77	IDN S-0-0115 Position feedback 2 type	145
9.77.1	Attributes.....	145
9.77.2	Description	145
9.78	IDN S-0-0116 Resolution of feedback 1	146
9.78.1	Attributes.....	146
9.78.2	Description	146
9.79	IDN S-0-0117 Resolution of feedback 2	146
9.79.1	Attributes.....	146
9.79.2	Description	147
9.80	IDN S-0-0118 Resolution of linear feedback	147
9.80.1	Attributes.....	147
9.80.2	Description	147
9.81	IDN S-0-0119 Current loop proportional gain 2	148
9.81.1	Attributes.....	148
9.81.2	Description	148
9.82	IDN S-0-0120 Current loop integral action time 2	148
9.82.1	Attributes.....	148
9.82.2	Description	149
9.83	IDN S-0-0121 Input revolutions of load gear	149
9.83.1	Attributes.....	149
9.83.2	Description	149
9.84	IDN S-0-0122 Output revolutions of load gear	149
9.84.1	Attributes.....	149
9.84.2	Description	150
9.85	IDN S-0-0123 Feed constant	150
9.85.1	Attributes.....	150
9.85.2	Description	150
9.86	IDN S-0-0124 Standstill window	150
9.86.1	Attributes.....	150
9.86.2	Description	151
9.87	IDN S-0-0125 Velocity threshold (n_x).....	151
9.87.1	Attributes.....	151
9.87.2	Description	151
9.88	IDN S-0-0126 Torque threshold (T_x).....	151
9.88.1	Attributes.....	151
9.88.2	Description	152
9.89	IDN S-0-0129 Manufacturer class 1 diagnostic	152
9.89.1	Attributes.....	152
9.89.2	Description	152
9.90	IDN S-0-0130 Probe value 1 positive edge	153

9.90.1	Attributes	153
9.90.2	Description	153
9.91	IDN S-0-0131 Probe value 1 negative edge	153
9.91.1	Attributes	153
9.91.2	Description	154
9.92	IDN S-0-0132 Probe value 2 positive edge	154
9.92.1	Attributes	154
9.92.2	Description	154
9.93	IDN S-0-0133 Probe value 2 negative edge	154
9.93.1	Attributes	154
9.93.2	Description	155
9.94	IDN S-0-0134 Master control word	155
9.94.1	Attributes	155
9.94.2	Description	155
9.95	IDN S-0-0135 Drive status word	155
9.95.1	Attributes	155
9.95.2	Description	156
9.96	IDN S-0-0136 Positive acceleration limit value	156
9.96.1	Attributes	156
9.96.2	Description	156
9.97	IDN S-0-0137 Negative acceleration limit value	156
9.97.1	Attributes	156
9.97.2	Description	157
9.98	IDN S-0-0138 Bipolar acceleration limit value	157
9.98.1	Attributes	157
9.98.2	Description	157
9.99	IDN S-0-0139 Park axis procedure command	157
9.99.1	Attributes	157
9.99.2	Description	158
9.100	IDN S-0-0140 Controller type	158
9.100.1	Attributes	158
9.100.2	Description	158
9.101	IDN S-0-0141 Motor type	158
9.101.1	Attributes	158
9.101.2	Description	159
9.102	IDN S-0-0142 Application type	159
9.102.1	Attributes	159
9.102.2	Description	159
9.103	IDN S-0-0144 Signal status word	159
9.103.1	Attributes	159
9.103.2	Description	160
9.104	IDN S-0-0145 Signal control word	160
9.104.1	Attributes	160
9.104.2	Description	160
9.105	IDN S-0-0146 Control unit controlled homing procedure command	160
9.105.1	Attributes	160
9.105.2	Description	161
9.106	IDN S-0-0148 Drive controlled homing procedure command	161
9.106.1	Attributes	161

9.106.2	Description.....	161
9.107	IDN S-0-0149 Positive drive stop procedure command	162
9.107.1	Attributes	162
9.107.2	Description.....	162
9.108	IDN S-0-0150 Reference offset 1	163
9.108.1	Attributes	163
9.108.2	Description.....	163
9.109	IDN S-0-0151 Reference offset 2	163
9.109.1	Attributes	163
9.109.2	Description.....	163
9.110	IDN S-0-0152 Position spindle procedure command	164
9.110.1	Attributes	164
9.110.2	Description.....	164
9.111	IDN S-0-0153 Spindle angle position	164
9.111.1	Attributes	164
9.111.2	Description.....	165
9.112	IDN S-0-0154 Spindle positioning parameter	165
9.112.1	Attributes	165
9.112.2	Description.....	165
9.113	IDN S-0-0155 Friction torque compensation.....	166
9.113.1	Attributes	166
9.113.2	Description.....	166
9.114	IDN S-0-0156 Velocity feedback value 2	166
9.114.1	Attributes	166
9.114.2	Description.....	167
9.115	IDN S-0-0157 Velocity window.....	167
9.115.1	Attributes	167
9.115.2	Description.....	167
9.116	IDN S-0-0158 Power threshold (P_x).....	167
9.116.1	Attributes	167
9.116.2	Description.....	168
9.117	IDN S-0-0159 Monitoring window.....	168
9.117.1	Attributes	168
9.117.2	Description.....	168
9.118	IDN S-0-0160 Acceleration data scaling type	168
9.118.1	Attributes	168
9.118.2	Description.....	169
9.119	IDN S-0-0161 Acceleration data scaling factor.....	169
9.119.1	Attributes	169
9.119.2	Description.....	170
9.120	IDN S-0-0162 Acceleration data scaling exponent	170
9.120.1	Attributes	170
9.120.2	Description.....	170
9.121	IDN S-0-0163 Weight counterbalance	171
9.121.1	Attributes	171
9.121.2	Description.....	171
9.122	IDN S-0-0164 Acceleration feedback value 1	171
9.122.1	Attributes	171
9.122.2	Description.....	171

9.123	IDN S-0-0165 and S-0-0166 Distance-coded reference marks A and B	172
9.123.1	Attributes	172
9.123.2	Description	172
9.124	IDN S-0-0167 Frequency limit of feedback 1/S-0-0168 Frequency limit of feedback 2	172
9.124.1	Attributes	172
9.124.2	Description	172
9.125	IDN S-0-0169 Probe control parameter	173
9.125.1	Attributes	173
9.125.2	Description	173
9.126	IDN S-0-0170 Probing cycle procedure command	173
9.126.1	Attributes	173
9.126.2	Description	174
9.127	IDN S-0-0171 Calculate displacement procedure command	174
9.127.1	Attributes	174
9.127.2	Description	174
9.128	IDN S-0-0172 Displacement to the referenced system procedure command	175
9.128.1	Attributes	175
9.128.2	Description	175
9.129	IDN S-0-0173 Marker position A	176
9.129.1	Attributes	176
9.129.2	Description	176
9.130	IDN S-0-0174 Marker position B	176
9.130.1	Attributes	176
9.130.2	Description	177
9.131	IDN S-0-0176 Displacement parameter 2	177
9.131.1	Attributes	177
9.131.2	Description	177
9.132	IDN S-0-0177 Absolute distance 1	178
9.132.1	Attributes	178
9.132.2	Description	178
9.133	IDN S-0-0178 Absolute distance 2	178
9.133.1	Attributes	178
9.133.2	Description	178
9.134	IDN S-0-0179 Probe status	179
9.134.1	Attributes	179
9.134.2	Description	179
9.135	IDN S-0-0180 Spindle relative offset	180
9.135.1	Attributes	180
9.135.2	Description	180
9.136	IDN S-0-0181 Manufacturer class 2 diagnostic	180
9.136.1	Attributes	180
9.136.2	Description	180
9.137	IDN S-0-0182 Manufacturer class 3 diagnostic	181
9.137.1	Attributes	181
9.137.2	Description	181
9.138	IDN S-0-0183 Synchronisation velocity window	181
9.138.1	Attributes	181
9.138.2	Description	182

9.139	IDN S-0-0184 Synchronisation velocity error limit	182
9.139.1	Attributes	182
9.139.2	Description.....	182
9.140	IDN S-0-0189 Following distance.....	183
9.140.1	Attributes	183
9.140.2	Description.....	183
9.141	IDN S-0-0190 Drive controlled gear engaging procedure command	183
9.141.1	Attributes	183
9.141.2	Description.....	183
9.142	IDN S-0-0191 Cancel reference point procedure command.....	184
9.142.1	Attributes	184
9.142.2	Description.....	184
9.143	IDN S-0-0192 IDN-list of all backup operation data	184
9.143.1	Attributes	184
9.143.2	Description.....	185
9.144	IDN S-0-0193 Positioning jerk.....	185
9.144.1	Attributes	185
9.144.2	Description.....	185
9.145	IDN S-0-0194 Acceleration command value	185
9.145.1	Attributes	185
9.145.2	Description.....	186
9.146	IDN S-0-0195 Acceleration feedback value 2	186
9.146.1	Attributes	186
9.146.2	Description.....	186
9.147	IDN S-0-0196 Motor rated current.....	186
9.147.1	Attributes	186
9.147.2	Description.....	187
9.148	IDN S-0-0197 Set coordinate system procedure command	187
9.148.1	Attributes	187
9.148.2	Description.....	187
9.149	IDN S-0-0198 Initial coordinate value.....	187
9.149.1	Attributes	187
9.149.2	Description.....	188
9.150	IDN S-0-0199 Shift coordinate system procedure command.....	188
9.150.1	Attributes	188
9.150.2	Description.....	188
9.151	IDN S-0-0200 Amplifier warning temperature	189
9.151.1	Attributes	189
9.151.2	Description.....	189
9.152	IDN S-0-0201 Motor warning temperature	189
9.152.1	Attributes	189
9.152.2	Description.....	189
9.153	IDN S-0-0202 Cooling error warning temperature	190
9.153.1	Attributes	190
9.153.2	Description.....	190
9.154	IDN S-0-0203 Amplifier shut-down temperature	190
9.154.1	Attributes	190
9.154.2	Description.....	190
9.155	IDN S-0-0204 Motor shut-down temperature	190

9.155.1	Attributes	190
9.155.2	Description.....	191
9.156	IDN S-0-0205 Cooling error shut-down temperature.....	191
9.156.1	Attributes	191
9.156.2	Description.....	191
9.157	IDN S-0-0206 Drive on delay time.....	191
9.157.1	Attributes	191
9.157.2	Description.....	192
9.158	IDN S-0-0207 Drive off delay time.....	192
9.158.1	Attributes	192
9.158.2	Description.....	192
9.159	IDN S-0-0208 Temperature data scaling type	192
9.159.1	Attributes	192
9.159.2	Description.....	193
9.160	IDN S-0-0209 Lower adaptation limit	193
9.160.1	Attributes	193
9.160.2	Description.....	193
9.161	IDN S-0-0210 Upper adaptation limit	194
9.161.1	Attributes	194
9.161.2	Description.....	194
9.162	IDN S-0-0211 Adaptation proportional gain.....	194
9.162.1	Attributes	194
9.162.2	Description.....	195
9.163	IDN S-0-0212 Adaptation integral action time	195
9.163.1	Attributes	195
9.163.2	Description.....	195
9.164	IDN S-0-0213 Engaging dither amplitude.....	195
9.164.1	Attributes	195
9.164.2	Description.....	196
9.165	IDN S-0-0214 Average engaging speed	196
9.165.1	Attributes	196
9.165.2	Description.....	196
9.166	IDN S-0-0215 Engaging dither period	196
9.166.1	Attributes	196
9.166.2	Description.....	196
9.167	IDN S-0-0216 Switch parameter set procedure command.....	197
9.167.1	Attributes	197
9.167.2	Description.....	197
9.168	IDN S-0-0217 Parameter set preselection	197
9.168.1	Attributes	197
9.168.2	Description.....	197
9.169	IDN S-0-0218 Gear ratio preselection	198
9.169.1	Attributes	198
9.169.2	Description.....	198
9.170	IDN S-0-0219 IDN-list of parameter set.....	199
9.170.1	Attributes	199
9.170.2	Description.....	199
9.171	IDN S-0-0220 Minimum spindle speed	199
9.171.1	Attributes	199

9.171.2	Description.....	200
9.172	IDN S-0-0221 Maximum spindle speed	200
9.172.1	Attributes	200
9.172.2	Description.....	200
9.173	IDN S-0-0222 Spindle positioning speed.....	200
9.173.1	Attributes	200
9.173.2	Description.....	200
9.174	IDN S-0-0223 Drive controlled synchronous operation procedure command	201
9.174.1	Attributes	201
9.174.2	Description.....	201
9.175	IDN S-0-0224 Lead spindle address	201
9.175.1	Attributes	201
9.175.2	Description.....	202
9.176	IDN S-0-0225 Synchronous operation parameter	202
9.176.1	Attributes	202
9.176.2	Description.....	202
9.177	IDN S-0-0226 Lead spindle revolutions	203
9.177.1	Attributes	203
9.177.2	Description.....	203
9.178	IDN S-0-0227 Synchronous spindle revolutions	203
9.178.1	Attributes	203
9.178.2	Description.....	203
9.179	IDN S-0-0228 Synchronisation position window	204
9.179.1	Attributes	204
9.179.2	Description.....	204
9.180	IDN S-0-0229 Synchronisation position error limit.....	204
9.180.1	Attributes	204
9.180.2	Description.....	205
9.181	IDN S-0-0230 Synchronous position offset.....	205
9.181.1	Attributes	205
9.181.2	Description.....	205
9.182	IDN S-0-0254 Actual parameter set	205
9.182.1	Attributes	205
9.182.2	Description.....	206
9.183	IDN S-0-0255 Actual gear ratio	206
9.183.1	Attributes	206
9.183.2	Description.....	206
9.184	IDN S-0-0256 Multiplication factor 1	207
9.184.1	Attributes	207
9.184.2	Description.....	207
9.185	IDN S-0-0257 Multiplication factor 2	207
9.185.1	Attributes	207
9.185.2	Description.....	208
9.186	IDN S-0-0258 Target position	208
9.186.1	Attributes	208
9.186.2	Description.....	208
9.187	IDN S-0-0259 Positioning velocity.....	209
9.187.1	Attributes	209
9.187.2	Description.....	209

9.188	IDN S-0-0260 Positioning acceleration.....	209
9.188.1	Attributes	209
9.188.2	Description	209
9.189	IDN S-0-0261 Coarse position window	210
9.189.1	Attributes	210
9.189.2	Description	210
9.190	IDN S-0-0262 Load defaults procedure command	210
9.190.1	Attributes	210
9.190.2	Description	210
9.191	IDN S-0-0263 Load working memory procedure command	211
9.191.1	Attributes	211
9.191.2	Description	211
9.192	IDN S-0-0264 Backup working memory procedure command	211
9.192.1	Attributes	211
9.192.2	Description	212
9.193	IDN S-0-0265 Language selection	212
9.193.1	Attributes	212
9.193.2	Description	212
9.194	IDN S-0-0266 List of available languages	213
9.194.1	Attributes	213
9.194.2	Description	213
9.195	IDN S-0-0267 Password	214
9.195.1	Attributes	214
9.195.2	Description	214
9.196	IDN S-0-0268 Angular setting	215
9.196.1	Attributes	215
9.196.2	Description	216
9.197	IDN S-0-0269 Storage mode	216
9.197.1	Attributes	216
9.197.2	Description	216
9.198	IDN S-0-0270 IDN list of selected backup operation data	216
9.198.1	Attributes	216
9.198.2	Description	217
9.199	IDN S-0-0271 Drive ID	217
9.199.1	Attributes	217
9.199.2	Description	217
9.200	IDN S-0-0272 Velocity window percentage	217
9.200.1	Attributes	217
9.200.2	Description	218
9.201	IDN S-0-0273 Maximum drive off delay time	218
9.201.1	Attributes	218
9.201.2	Description	218
9.202	IDN S-0-0275 Coordinate offset value	218
9.202.1	Attributes	218
9.202.2	Description	219
9.203	IDN S-0-0276 Return to Modulo range procedure command	219
9.203.1	Attributes	219
9.203.2	Description	219
9.204	IDN S-0-0277 Position feedback 1 type	220

9.204.1	Attributes	220
9.204.2	Description.....	220
9.205	IDN S-0-0278 Maximum travel range	221
9.205.1	Attributes	221
9.205.2	Description.....	221
9.206	IDN S-0-0279 IDN list of password protected data	222
9.206.1	Attributes	222
9.206.2	Description.....	222
9.207	IDN S-0-0280, S-0-0281 Underflow threshold	222
9.207.1	Attributes	222
9.207.2	Description.....	222
9.208	IDN S-0-0283 Current coordinate offset	223
9.208.1	Attributes	223
9.208.2	Description.....	223
9.209	IDN S-0-0284 to S-0-0287 Secondary operation mode 4 to 7	223
9.209.1	Attributes	223
9.209.2	Description.....	224
9.210	IDN S-0-0292 List of supported operation modes	224
9.210.1	Attributes	224
9.210.2	Description.....	224
9.211	IDN S-0-0293 Selectively backup working memory procedure command.....	224
9.211.1	Attributes	224
9.211.2	Description.....	225
9.212	IDN S-0-0294 Divider modulo value	225
9.212.1	Attributes	225
9.212.2	Description.....	225
9.213	IDN S-0-0295 Drive enable delay time	225
9.213.1	Attributes	225
9.213.2	Description.....	226
9.214	IDN S-0-0296 Velocity feed forward gain	226
9.214.1	Attributes	226
9.214.2	Description.....	226
9.215	IDN S-0-0297 Homing distance.....	226
9.215.1	Attributes	226
9.215.2	Description.....	227
9.216	IDN S-0-0298 Suggest home switch distance.....	227
9.216.1	Attributes	227
9.216.2	Description.....	227
9.217	IDN S-0-0299 Home switch offset 1	228
9.217.1	Attributes	228
9.217.2	Description.....	228
9.218	IDN S-0-0300 Real-time control bit 1	228
9.218.1	Attributes	228
9.218.2	Description.....	229
9.219	IDN S-0-0301 Allocation of real-time control bit 1	229
9.219.1	Attributes	229
9.219.2	Description.....	229
9.220	IDN S-0-0302 Real-time control bit 2	229
9.220.1	Attributes	229

9.220.2	Description.....	230
9.221	IDN S-0-0303 Allocation of real-time control bit 2	230
9.221.1	Attributes	230
9.221.2	Description.....	230
9.222	IDN S-0-0304 Real-time status bit 1.....	231
9.222.1	Attributes	231
9.222.2	Description.....	231
9.223	IDN S-0-0305 Allocation of real-time status bit 1.....	231
9.223.1	Attributes	231
9.223.2	Description.....	232
9.224	IDN S-0-0306 Real-time status bit 2.....	232
9.224.1	Attributes	232
9.224.2	Description.....	232
9.225	IDN S-0-0307 Allocation of real-time status bit 2.....	232
9.225.1	Attributes	232
9.225.2	Description.....	233
9.226	IDN S-0-0308 Synchronisation operation status.....	233
9.226.1	Attributes	233
9.226.2	Description.....	233
9.227	IDN S-0-0309 Synchronisation error status.....	234
9.227.1	Attributes	234
9.227.2	Description.....	234
9.228	IDN S-0-0310 Overload warning.....	235
9.228.1	Attributes	235
9.228.2	Description.....	235
9.229	IDN S-0-0311 Amplifier overtemperature warning	235
9.229.1	Attributes	235
9.229.2	Description.....	236
9.230	IDN S-0-0312 Motor overtemperature warning.....	236
9.230.1	Attributes	236
9.230.2	Description.....	236
9.231	IDN S-0-0313 Cooling error warning	237
9.231.1	Attributes	237
9.231.2	Description.....	237
9.232	IDN S-0-0323 Target position outside of travel range.....	237
9.232.1	Attributes	237
9.232.2	Description.....	238
9.233	IDN S-0-0328 Bit number allocation list for signal status word	238
9.233.1	Attributes	238
9.233.2	Description.....	239
9.234	IDN S-0-0329 Bit number allocation list for signal control word	239
9.234.1	Attributes	239
9.234.2	Description.....	239
9.235	IDN S-0-0330 Status ' $n_{\text{feedback}} = n_{\text{command}}$ '	239
9.235.1	Attributes	239
9.235.2	Description.....	240
9.236	IDN S-0-0331 Status ' $n_{\text{feedback}} = 0$ '	240
9.236.1	Attributes	240
9.236.2	Description.....	240

9.237	IDN S-0-0332 Status ' $n_{\text{feedback}} < n_x$ '	241
9.237.1	Attributes	241
9.237.2	Description	241
9.238	IDN S-0-0333 Status ' $T \geq T_x$ '	241
9.238.1	Attributes	241
9.238.2	Description	242
9.239	IDN S-0-0334 Status ' $T \geq T_{\text{limit}}$ '	242
9.239.1	Attributes	242
9.239.2	Description	242
9.240	IDN S-0-0335 Status ' $n_{\text{command}} > n_{\text{limit}}$ '	243
9.240.1	Attributes	243
9.240.2	Description	243
9.241	IDN S-0-0336 Status 'In position'	244
9.241.1	Attributes	244
9.241.2	Description	244
9.242	IDN S-0-0337 Status ' $P \geq P_x$ '	244
9.242.1	Attributes	244
9.242.2	Description	245
9.243	IDN S-0-0338 Status "Position feedback = active target position"	245
9.243.1	Attributes	245
9.243.2	Description	245
9.244	IDN S-0-0339 Status ' $n_{\text{feedback}} \leq \text{minimum spindle speed}$ '	246
9.244.1	Attributes	246
9.244.2	Description	246
9.245	IDN S-0-0340 Status ' $n_{\text{feedback}} \geq \text{maximum spindle speed}$ '	246
9.245.1	Attributes	246
9.245.2	Description	247
9.246	IDN S-0-0341 Status "In coarse position"	247
9.246.1	Attributes	247
9.246.2	Description	248
9.247	IDN S-0-0342 Status "Target position attained"	248
9.247.1	Attributes	248
9.247.2	Description	248
9.248	IDN S-0-0343 Status "Interpolator halted"	249
9.248.1	Attributes	249
9.248.2	Description	249
9.249	IDN S-0-0347 Velocity error	249
9.249.1	Attributes	249
9.249.2	Description	250
9.250	IDN S-0-0348 Acceleration feed forward gain	250
9.250.1	Attributes	250
9.250.2	Description	250
9.251	IDN S-0-0349 Bipolar jerk limit	250
9.251.1	Attributes	250
9.251.2	Description	251
9.252	IDN S-0-0356 Distance home switch – marker pulse	251
9.252.1	Attributes	251
9.252.2	Description	251
9.253	IDN S-0-0357 Marker pulse distance	251

9.253.1	Attributes	251
9.253.2	Description.....	252
9.254	IDN S-0-0358 Home switch offset 2	252
9.254.1	Attributes	252
9.254.2	Description.....	252
9.255	IDN S-0-0359 Positioning deceleration	252
9.255.1	Attributes	252
9.255.2	Description.....	253
9.256	IDN S-0-0360 and IDN S-0-0361 MDT data containers A1 (4 byte) and B (4 byte).....	253
9.256.1	Attributes	253
9.256.2	Description.....	253
9.257	IDN S-0-0362 and IDN S-0-0363 MDT data container A and B list indexes	254
9.257.1	Attributes	254
9.257.2	Description.....	254
9.258	IDN S-0-0364 and IDN S-0-0365 AT data containers A1 (4 byte) and B (4 byte).....	255
9.258.1	Attributes	255
9.258.2	Description.....	255
9.259	IDN S-0-0366 and IDN S-0-0367 AT data container A and B list indexes	256
9.259.1	Attributes	256
9.259.2	Description.....	256
9.260	IDN S-0-0368 and IDN S-0-0369 Data container A and B pointers	257
9.260.1	Attributes	257
9.260.2	Description.....	257
9.261	IDN S-0-0370 MDT data container configuration list.....	258
9.261.1	Attributes	258
9.261.2	Description.....	259
9.262	IDN S-0-0371 AT data container configuration list.....	259
9.262.1	Attributes	259
9.262.2	Description.....	259
9.263	IDN S-0-0372 Drive Halt acceleration bipolar.....	259
9.263.1	Attributes	259
9.263.2	Description.....	260
9.264	IDN S-0-0373 Service channel error list.....	260
9.264.1	Attributes	260
9.264.2	Description.....	260
9.265	IDN S-0-0374 Procedure command error list.....	261
9.265.1	Attributes	261
9.265.2	Description.....	261
9.266	IDN S-0-0375 Diagnostic numbers list	261
9.266.1	Attributes	261
9.266.2	Description.....	262
9.267	IDN S-0-0376 Baud rate	262
9.267.1	Attributes	262
9.267.2	Description.....	262
9.268	IDN S-0-0377 Velocity feedback monitoring window	263
9.268.1	Attributes	263
9.268.2	Description.....	263

9.269	IDN S-0-0378 Absolute encoder range 1	263
9.269.1	Attributes	263
9.269.2	Description	264
9.270	IDN S-0-0379 Absolute encoder range 2	264
9.270.1	Attributes	264
9.270.2	Description	264
9.271	IDN S-0-0380 DC bus voltage	264
9.271.1	Attributes	264
9.271.2	Description	264
9.272	IDN S-0-0381 DC bus current	265
9.272.1	Attributes	265
9.272.2	Description	265
9.273	IDN S-0-0382 DC bus power	265
9.273.1	Attributes	265
9.273.2	Description	265
9.274	IDN S-0-0383 Motor temperature	265
9.274.1	Attributes	265
9.274.2	Description	266
9.275	IDN S-0-0384 Amplifier temperature	266
9.275.1	Attributes	266
9.275.2	Description	266
9.276	IDN S-0-0385 Active power	266
9.276.1	Attributes	266
9.276.2	Description	267
9.277	IDN S-0-0386 Active position feedback value	267
9.277.1	Attributes	267
9.277.2	Description	267
9.278	IDN S-0-0387 Power overload	267
9.278.1	Attributes	267
9.278.2	Description	268
9.279	IDN S-0-0388 Braking current limit	268
9.279.1	Attributes	268
9.279.2	Description	268
9.280	IDN S-0-0389 Effective current	268
9.280.1	Attributes	268
9.280.2	Description	269
9.281	IDN S-0-0390 Diagnostic number	269
9.281.1	Attributes	269
9.281.2	Description	269
9.282	IDN S-0-0391 Position feedback monitoring window	269
9.282.1	Attributes	269
9.282.2	Description	270
9.283	IDN S-0-0392 Velocity feedback filter	270
9.283.1	Attributes	270
9.283.2	Description	270
9.284	IDN S-0-0393 Command value mode	270
9.284.1	Attributes	270
9.284.2	Description	271
9.285	IDN S-0-0394 List IDN	271

9.285.1	Attributes	271
9.285.2	Description	271
9.286	IDN S-0-0395 List index	271
9.286.1	Attributes	271
9.286.2	Description	272
9.287	IDN S-0-0396 Number of list elements	272
9.287.1	Attributes	272
9.287.2	Description	272
9.288	IDN S-0-0397 List segment	272
9.288.1	Attributes	272
9.288.2	Description	273
9.289	IDN S-0-0398 IDN list of configurable data in the signal status word	273
9.289.1	Attributes	273
9.289.2	Description	274
9.290	IDN S-0-0399 IDN list of configurable data in the signal control word	274
9.290.1	Attributes	274
9.290.2	Description	274
9.291	IDN S-0-0400 Home switch	274
9.291.1	Attributes	274
9.291.2	Description	274
9.292	IDN S-0-0401 Probe 1	275
9.292.1	Attributes	275
9.292.2	Description	275
9.293	IDN S-0-0402 Probe 2	276
9.293.1	Attributes	276
9.293.2	Description	276
9.294	IDN S-0-0403 Position feedback value status	276
9.294.1	Attributes	276
9.294.2	Description	277
9.295	IDN S-0-0404 Position command value status	277
9.295.1	Attributes	277
9.295.2	Description	278
9.296	IDN S-0-0405 Probe 1 enable	278
9.296.1	Attributes	278
9.296.2	Description	278
9.297	IDN S-0-0406 Probe 2 enable	279
9.297.1	Attributes	279
9.297.2	Description	279
9.298	IDN S-0-0407 Homing enable	279
9.298.1	Attributes	279
9.298.2	Description	280
9.299	IDN S-0-0408 Reference marker pulse registered	280
9.299.1	Attributes	280
9.299.2	Description	280
9.300	IDN S-0-0409 Probe 1 positive latched	281
9.300.1	Attributes	281
9.300.2	Description	281
9.301	IDN S-0-0410 Probe 1 negative latched	282
9.301.1	Attributes	282

9.301.2	Description.....	282
9.302	IDN S-0-0411 Probe 2 positive latched	282
9.302.1	Attributes	282
9.302.2	Description.....	283
9.303	IDN S-0-0412 Probe 2 negative latched	283
9.303.1	Attributes	283
9.303.2	Description.....	284
9.304	IDN S-0-0413 Bit number allocation of real-time control bit 1	284
9.304.1	Attributes	284
9.304.2	Description.....	284
9.305	IDN S-0-0414 Bit number allocation of real-time control bit 2	284
9.305.1	Attributes	284
9.305.2	Description.....	285
9.306	IDN S-0-0415 Bit number allocation of real-time status bit 1	285
9.306.1	Attributes	285
9.306.2	Description.....	285
9.307	IDN S-0-0416 Bit number allocation of real-time status bit 2	285
9.307.1	Attributes	285
9.307.2	Description.....	286
9.308	IDN S-0-0429 Emergency stop deceleration.....	286
9.308.1	Attributes	286
9.308.2	Description.....	286
9.309	IDN S-0-0430 Active target position.....	286
9.309.1	Attributes	286
9.309.2	Description.....	287
9.310	IDN S-0-0431 Spindle positioning acceleration bipolar.....	287
9.310.1	Attributes	287
9.310.2	Description.....	288
9.311	IDN S-0-0432 Serial number drive control.....	288
9.311.1	Attributes	288
9.311.2	Description.....	288
9.312	IDN S-0-0433 Serial number power stage.....	288
9.312.1	Attributes	288
9.312.2	Description.....	288
9.313	IDN S-0-0434 Serial number motor.....	289
9.313.1	Attributes	289
9.313.2	Description.....	289
9.314	IDN S-0-0435 Operating time drive control.....	289
9.314.1	Attributes	289
9.314.2	Description.....	289
9.315	IDN S-0-0436 Operating time power stage.....	289
9.315.1	Attributes	289
9.315.2	Description.....	290
9.316	IDN S-0-0446 Ramp reference velocity	290
9.316.1	Attributes	290
9.316.2	Description.....	290
9.317	IDN S-0-0460 to S-0-0475 Position switches (position switch points off 1-16) ...	290
9.317.1	Attributes	290
9.317.2	Description.....	291

9.318 IDN S-0-0476 Position switch control	291
9.318.1 Attributes	291
9.318.2 Description	291
9.319 IDN S-0-0477 Position switch hysteresis	292
9.319.1 Attributes	292
9.319.2 Description	292
Bibliography	293
Figure 1 – Structure of IEC 61800-7	39
Figure 2 – Position data scaling type diagram	49
Figure 3 – Velocity data scaling type diagram	51
Figure 4 – Torque/force data scaling type diagram	53
Figure 5 – Acceleration/jerk data scaling type diagram	55
Figure 6 – Adaptation of the velocity loop proportional gain	56
Figure 7 – Adaptation of the velocity loop integral action time	56
Figure 8 – Synchronous spindle operation diagram	59
Figure 9 – Polarity parameter	61
Figure 10 – Bit sequence for switching parameter sets and/or gear ratio	62
Figure 11 – Operation modes	63
Figure 12 – Block diagram of operation modes	66
Figure 13 – Bit sequence for drive controlled homing	67
Figure 14 – Drive controlled homing diagram	67
Figure 15 – Bit sequence for control unit controlled homing (case 1)	69
Figure 16 – Bit sequence for control unit controlled homing (case 2.1)	69
Figure 17 – Bit sequence for control unit controlled homing (case 2.2)	69
Figure 18 – Incremental feedback system	70
Figure 19 – Distance-coded feedback system	71
Figure 20 – Bit sequence to activate the displacement to the referenced system	71
Figure 21 – Bit sequence for measuring	72
Figure 22 – Velocity diagram for spindle positioning (1)	73
Figure 23 – Velocity diagram for spindle positioning (2)	73
Figure 24 – Velocity diagram for spindle positioning (3)	74
Figure 25 – Bit sequence while writing new position values (S-0-0153 or S-0-0180)	74
Figure 26 – Bit sequence for switching spindle positioning mode	75
Figure 27 – Velocity window	75
Figure 28 – $n_{\text{feedback}} = n_{\text{command}}$ depiction	76
Figure 29 – Position switch mode	77
Figure 30 – Cam switch mode	78
Figure 31 – Bit sequence during start-up	81
Figure 32 – Bit sequence during shut-down	82
Figure 33 – Bit sequence for C1D error	83
Figure 34 – Bit sequence for park axis	83
Figure 35 – Bit sequence for positive stop drive	84

Figure 36 – Velocity diagram for lead and synchronous spindle	85
Figure 37 – Position feedback diagram for lead and synchronous spindle	86
Figure 38 – Drive controlled gear engaging procedure command	87
Figure 39 – General IDN structure	88
Figure 40 – Password modification	215
Table 1 – Data types	46
Table 2 – Elements of an IDN	47
Table 3 – Scaling of position data IDNs	48
Table 4 – Scaling of linear position data	49
Table 5 – Scaling of rotational position data	49
Table 6 – Scaling of velocity data IDNs	50
Table 7 – Linear scaling of velocity data	50
Table 8 – Scaling of rotational velocity data	51
Table 9 – Scaling of torque/force IDNs	51
Table 10 – Scaling of force data	52
Table 11 – Scaling of torque data	52
Table 12 – Scaling of acceleration and jerk data IDNs	53
Table 13 – Scaling of linear acceleration/jerk data	54
Table 14 – Scaling of rotational acceleration/jerk data	54
Table 15 – Scaling of ramp time	54
Table 16 – Scaling of temperature data IDN	55
Table 17 – Velocity loop IDNs	55
Table 18 – Adaptation of the velocity loop IDNs	56
Table 19 – Position loop parameters IDNs	57
Table 20 – Current loop parameters IDNs	57
Table 21 – Drive limit values IDNs	57
Table 22 – General drive parameters IDNs	58
Table 23 – Spindle parameters IDNs	58
Table 24 – Spindle synchronous operation IDNs	58
Table 25 – Feedback systems IDNs	59
Table 26 – Feed constant IDN	60
Table 27 – Gear train IDNs	60
Table 28 – Polarities IDNs	60
Table 29 – Parameter sets and gear ratios IDNs	61
Table 30 – Switching operation mode IDNs	64
Table 31 – Structure of drive operation modes	65
Table 32 – Velocity window IDNs	75
Table 33 – Position switches IDN	77
Table 34 – Control word	79
Table 35 – Status word	80
Table 36 – Detailed IDN structure	87
Table 37 – IDN list in numerical order	88

Table 38 – Attributes of IDN S-0-0005	100
Table 39 – Attributes for IDN S-0-0007	101
Table 40 – Attributes of IDN S-0-0011	102
Table 41 – Structure of C1D	102
Table 42 – Attributes of IDN S-0-0012	103
Table 43 – Structure of C2D	103
Table 44 – Attributes of IDN S-0-0013	104
Table 45 – Structure of C3D	104
Table 46 – Attributes of IDN S-0-0016	105
Table 47 – Attributes of IDN S-0-0017	105
Table 48 – Attributes for IDN S-0-0018	106
Table 49 – Attributes for IDN S-0-0019	106
Table 50 – Attributes for IDN S-0-0020	107
Table 51 – Attributes for IDN S-0-0021	107
Table 52 – Attributes for IDN S-0-0022	108
Table 53 – Attributes for IDN S-0-0023	108
Table 54 – Attributes for IDN S-0-0025	109
Table 55 – Attributes for IDN S-0-0026	109
Table 56 – Attributes for IDN S-0-0027	110
Table 57 – Attributes for IDN S-0-0030	110
Table 58 – Attributes for IDN S-0-0031	111
Table 59 – Attributes for IDN S-0-0032	111
Table 60 – Attributes for IDN S-0-0036	112
Table 61 – Attributes for IDN S-0-0037	112
Table 62 – Attributes for IDN S-0-0038	113
Table 63 – Attributes for IDN S-0-0039	113
Table 64 – Attributes for IDN S-0-0040	114
Table 65 – Attributes for IDN S-0-0041	114
Table 66 – Attributes for IDN S-0-0042	115
Table 67 – Attributes for IDN S-0-0043	115
Table 68 – Structure of velocity polarity parameter	116
Table 69 – Attributes for IDN S-0-0044	116
Table 70 – Structure of velocity data scaling type	116
Table 71 – Attributes for IDN S-0-0045	117
Table 72 – Attributes for IDN S-0-0046	117
Table 73 – Structure of the scaling exponent	118
Table 74 – Attributes for IDN S-0-0047	118
Table 75 – Attributes for IDN S-0-0048	119
Table 76 – Attributes for IDN S-0-0049	119
Table 77 – Attributes for IDN S-0-0050	120
Table 78 – Attributes for IDN S-0-0051	120
Table 79 – Attributes for IDN S-0-0052	121
Table 80 – Attributes for IDN S-0-0053	121

Table 81 – Attributes for IDN S-0-0053	122
Table 82 – Attributes for IDN S-0-0055	123
Table 83 – Structure of velocity polarity parameter	123
Table 84 – Attributes for IDN S-0-0057	124
Table 85 – Attributes for IDN S-0-0058	124
Table 86 – Attributes for IDN S-0-0059	125
Table 87 – Structure of the position switch flag parameter	125
Table 88 – Attributes of IDN S-0-0060 to S-0-0075	126
Table 89 – Attributes for IDN S-0-0076	126
Table 90 – Structure of position data scaling type	126
Table 91 – Attributes for IDN S-0-0077	127
Table 92 – Attributes for IDN S-0-0078	128
Table 93 – Structure of position data scaling type	128
Table 94 – Attributes for IDN S-0-0079	128
Table 95 – Attributes for IDN S-0-0080	129
Table 96 – Attributes for IDN S-0-0082	129
Table 97 – Attributes for IDN S-0-0083	130
Table 98 – Attributes for IDN S-0-0084	130
Table 99 – Attributes for IDN S-0-0085	131
Table 100 – Structure of torque polarity parameter	131
Table 101 – Attributes for IDN S-0-0086	132
Table 102 – Structure of torque/force data scaling type	132
Table 103 – Attributes for IDN S-0-0091	133
Table 104 – Attributes for IDN S-0-0092	133
Table 105 – Attributes for IDN S-0-0093	134
Table 106 – Attributes for IDN S-0-0094	134
Table 107 – Structure of the Torque/Force Data Scaling Exponent	134
Table 108 – Attributes for IDN S-0-0095	135
Table 109 – Attributes for IDN S-0-0097	135
Table 110 – Structure of Mask C2D	136
Table 111 – Attributes for IDN S-0-0098	136
Table 112 – Structure of Mask C3D	136
Table 113 – Attributes for IDN S-0-0099	136
Table 114 – Attributes for IDN S-0-0100	137
Table 115 – Attributes for IDN S-0-0101	137
Table 116 – Attributes for IDN S-0-0102	138
Table 117 – Attributes for IDN S-0-0103	138
Table 118 – Attributes for IDN S-0-0104	140
Table 119 – Attributes for IDN S-0-0105	140
Table 120 – Attributes for IDN S-0-0106	141
Table 121 – Attributes for IDN S-0-0107	141
Table 122 – Attributes for IDN S-0-0108	142
Table 123 – Attributes for IDN S-0-0109	142

Table 124 – Attributes for IDN S-0-0110	143
Table 125 – Attributes for IDN S-0-0111	143
Table 126 – Attributes for IDN S-0-0112	144
Table 127 – Attributes for IDN S-0-0113	144
Table 128 – Attributes for IDN S-0-0114	144
Table 129 – Attributes for IDN S-0-0115	145
Table 130 – Structure of Position Feedback 2 Type	145
Table 131 – Attributes for IDN S-0-0116	146
Table 132 – Attributes for IDN S-0-0117	147
Table 133 – Attributes for IDN S-0-0118	147
Table 134 – Attributes for IDN S-0-0119	148
Table 135 – Attributes for IDN S-0-0120	149
Table 136 – Attributes for IDN S-0-0121	149
Table 137 – Attributes for IDN S-0-0122	150
Table 138 – Attributes for IDN S-0-0123	150
Table 139 – Attributes for IDN S-0-0124	151
Table 140 – Attributes for IDN S-0-0125	151
Table 141 – Attributes for IDN S-0-0126	152
Table 142 – Attributes for IDN S-0-0129	152
Table 143 – Structure of manufacturer Class 1 diagnostic	153
Table 144 – Attributes for IDN S-0-0130	153
Table 145 – Attributes for IDN S-0-0131	153
Table 146 – Attributes for IDN S-0-0132	154
Table 147 – Attributes for IDN S-0-0133	154
Table 148 – Attributes for IDN S-0-0134	155
Table 149 – Attributes for IDN S-0-0135	155
Table 150 – Attributes for IDN S-0-0136	156
Table 151 – Attributes for IDN S-0-0137	156
Table 152 – Attributes for IDN S-0-0138	157
Table 153 – Attributes for IDN S-0-0139	157
Table 154 – Attributes for IDN S-0-0140	158
Table 155 – Attributes for IDN S-0-0141	159
Table 156 – Attributes for IDN S-0-0142	159
Table 157 – Attributes for IDN S-0-0144	160
Table 158 – Attributes for IDN S-0-0145	160
Table 159 – Attributes for IDN S-0-0146	161
Table 160 – Attributes for IDN S-0-0148	161
Table 161 – Attributes for IDN S-0-0149	162
Table 162 – Attributes for IDN S-0-0150	163
Table 163 – Attributes for IDN S-0-0151	163
Table 164 – Attributes for IDN S-0-0152	164
Table 165 – Attributes for IDN S-0-0153	164
Table 166 – Attributes for IDN S-0-0154	165

Table 167 – Structure of Spindle Position Parameter	165
Table 168 – Attributes for IDN S-0-0155	166
Table 169 – Attributes for IDN S-0-0156	167
Table 170 – Attributes for IDN S-0-0157	167
Table 171 – Attributes for IDN S-0-0158	168
Table 172 – Attributes for IDN S-0-0159	168
Table 173 – Attributes for IDN S-0-0160	169
Table 174 – Structure of the Acceleration Data Scaling Type	169
Table 175 – Attributes for IDN S-0-0161	170
Table 176 – Attributes for IDN S-0-0162	170
Table 177 – Structure of the Scaling Exponent	170
Table 178 – Attributes for IDN S-0-0163	171
Table 179 – Attributes for IDN S-0-0164	171
Table 180 – Attributes for IDN S-0-0165	172
Table 181 – Attributes for IDN S-0-0167, S-0-0168	172
Table 182 – Attributes for IDN S-0-0169	173
Table 183 – Structure of the Probe Control Parameter	173
Table 184 – Attributes for IDN S-0-0170	174
Table 185 – Attributes for IDN S-0-0171	174
Table 186 – Attributes for IDN S-0-0172	175
Table 187 – Attributes for IDN S-0-0173	176
Table 188 – Attributes for IDN S-0-0174	177
Table 189 – Attributes for IDN S-0-0176	177
Table 190 – Attributes for IDN S-0-0177	178
Table 191 – Attributes for IDN S-0-0178	178
Table 192 – Attributes for IDN S-0-0179	179
Table 193 – Structure of Probe Status	179
Table 194 – Attributes for IDN S-0-0180	180
Table 195 – Attributes for IDN S-0-0181	180
Table 196 – Structure of Manufacturer C2D	181
Table 197 – Attributes for IDN S-0-0182	181
Table 198 – Structure of Manufacturer C3D	181
Table 199 – Attributes for IDN S-0-0183	182
Table 200 – Attributes for IDN S-0-0184	182
Table 201 – Attributes for IDN S-0-0189	183
Table 202 – Attributes for IDN S-0-0190	183
Table 203 – Attributes for IDN S-0-0191	184
Table 204 – Attributes for IDN S-0-0192	184
Table 205 – Attributes for IDN S-0-0193	185
Table 206 – Attributes for IDN S-0-0194	185
Table 207 – Attributes for IDN S-0-0195	186
Table 208 – Attributes for IDN S-0-0196	186
Table 209 – Attributes for IDN S-0-0197	187

Table 210 – Attributes for IDN S-0-0198	188
Table 211 – Attributes for IDN S-0-0199	188
Table 212 – Attributes for IDN S-0-0200	189
Table 213 – Attributes for IDN S-0-0201	189
Table 214 – Attributes for IDN S-0-0202	190
Table 215 – Attributes for IDN S-0-0203	190
Table 216 – Attributes for IDN S-0-0204	191
Table 217 – Attributes for IDN S-0-0205	191
Table 218 – Attributes for IDN S-0-0206	192
Table 219 – Attributes for IDN S-0-0207	192
Table 220 – Attributes for IDN S-0-0208	193
Table 221 – Structure of Temperature Data Scaling Type	193
Table 222 – Attributes for IDN S-0-0209	193
Table 223 – Attributes for IDN S-0-0210	194
Table 224 – Attributes for IDN S-0-0211	194
Table 225 – Attributes for IDN S-0-0212	195
Table 226 – Attributes for IDN S-0-0213	195
Table 227 – Attributes for IDN S-0-0214	196
Table 228 – Attributes for IDN S-0-0215	196
Table 229 – Attributes for IDN S-0-0216	197
Table 230 – Attributes for IDN S-0-0217	197
Table 231 – Structure of Parameter set preselection	198
Table 232 – Attributes for IDN S-0-0218	198
Table 233 – Structure of the Gear ratio preselection	198
Table 234 – Attributes for IDN S-0-0219	199
Table 235 – Attributes for IDN S-0-0220	199
Table 236 – Attributes for IDN S-0-0221	200
Table 237 – Attributes for IDN S-0-0222	200
Table 238 – Attributes for IDN S-0-0223	201
Table 239 – Attributes for IDN S-0-0224	201
Table 240 – Attributes for IDN S-0-0225	202
Table 241 – Structure of the Synchronous Operation Parameter	202
Table 242 – Attributes for IDN S-0-0226	203
Table 243 – Attributes for IDN S-0-0227	203
Table 244 – Attributes for IDN S-0-0228	204
Table 245 – Attributes for IDN S-0-0229	204
Table 246 – Attributes for IDN S-0-0230	205
Table 247 – Attributes for IDN S-0-0254	205
Table 248 – Structure of the Actual Parameter Set	206
Table 249 – Attributes for IDN S-0-0255	206
Table 250 – Structure of the Actual Gear Ratio	207
Table 251 – Attributes for IDN S-0-0256	207
Table 252 – Attributes for IDN S-0-0257	208

Table 253 – Attributes for IDN S-0-0258	208
Table 254 – Attributes for IDN S-0-0259	209
Table 255 – Attributes for IDN S-0-0260	209
Table 256 – Attributes for IDN S-0-0261	210
Table 257 – Attributes for IDN S-0-0262	210
Table 258 – Attributes for IDN S-0-0263	211
Table 259 – Attributes for IDN S-0-0264	211
Table 260 – Attributes for IDN S-0-0265	212
Table 261 – Structure of the Language Selection: Language Codes.....	213
Table 262 – Attributes for IDN S-0-0266	213
Table 263 – Attributes for IDN S-0-0267	214
Table 264 – Attributes for IDN S-0-0268	215
Table 265 – Attributes for IDN S-0-0269	216
Table 266 – Structure of Storage Mode.....	216
Table 267 – Attributes for IDN S-0-0270	216
Table 268 – Attributes for IDN S-0-0271	217
Table 269 – Attributes for IDN S-0-0272	218
Table 270 – Attributes for IDN S-0-0273	218
Table 271 – Attributes for IDN S-0-0275	219
Table 272 – Attributes for IDN S-0-0276	219
Table 273 – Attributes for IDN S-0-0277	220
Table 274 – Structure of the Position Feedback 1 Type	220
Table 275 – Attributes for IDN S-0-0278	221
Table 276 – Attributes for IDN S-0-0279	222
Table 277 – Attributes for IDN S-0-0280, S-0-0281	222
Table 278 – Attributes for IDN S-0-0283	223
Table 279 – Attributes for IDN S-0-0284 to IDN S-0-0287	223
Table 280 – Attributes for IDN S-0-0292	224
Table 281 – Attributes for IDN S-0-0293	224
Table 282 – Attributes for IDN S-0-0294	225
Table 283 – Attributes for IDN S-0-0295	225
Table 284 – Attributes for IDN S-0-0296	226
Table 285 – Attributes for IDN S-0-0297	226
Table 286 – Attributes for IDN S-0-0298	227
Table 287 – Attributes for IDN S-0-0299	228
Table 288 – Attributes for IDN S-0-0300	228
Table 289 – Structure of real-time control bit 1	229
Table 290 – Attributes for IDN S-0-0301	229
Table 291 – Attributes for IDN S-0-0302	230
Table 292 – Structure of the Real-Time Control Bit 2	230
Table 293 – Attributes for IDN S-0-0303	230
Table 294 – Attributes for IDN S-0-0304	231
Table 295 – Structure of Real-Time Status Bit 1	231

Table 296 – Attributes for IDN S-0-0305	231
Table 297 – Attributes for IDN S-0-0306	232
Table 298 – Structure of Real-Time Status Bit 2	232
Table 299 – Attributes for IDN S-0-0307	233
Table 300 – Attributes for IDN S-0-0308	233
Table 301 – Structure of the Synchronisation Operation Status	234
Table 302 – Attributes for IDN S-0-0309	234
Table 303 – Structure of the Synchronisation Error Status	235
Table 304 – Attributes for IDN S-0-0310	235
Table 305 – Structure of Overload Warning	235
Table 306 – Attributes for IDN S-0-0311	236
Table 307 – Structure of amplifier overtemperature warning	236
Table 308 – Attributes for IDN S-0-0312	236
Table 309 – Structure of Motor Overtemperature Warning	237
Table 310 – Attributes for IDN S-0-0313	237
Table 311 – Cooling error warning	237
Table 312 – Attributes for IDN S-0-0323	238
Table 313 – Structure of the Warning Target Position Outside of Travel Range	238
Table 314 – Attributes for IDN S-0-0328	238
Table 315 – Attributes for IDN S-0-0329	239
Table 316 – Attributes for IDN S-0-0330	239
Table 317 – Structure of status ' $n_{\text{feedback}} = n_{\text{command}}$ '	240
Table 318 – Attributes for IDN S-0-0331	240
Table 319 – Structure of Status ' $n_{\text{feedback}} = 0$ '	241
Table 320 – Attributes for IDN S-0-0332	241
Table 321 – Structure of status ' $n_{\text{feedback}} < n_x$ '	241
Table 322 – Attributes for IDN S-0-0333	242
Table 323 – Structure of Status ' $T \geq T_x$ '	242
Table 324 – Attributes for IDN S-0-0334	242
Table 325 – Structure of Status ' $T \geq T_{\text{limit}}$ '	243
Table 326 – Attributes for IDN S-0-0335	243
Table 327 – Structure of Status ' $n_{\text{command}} > n_{\text{limit}}$ '	243
Table 328 – Attributes for IDN S-0-0336	244
Table 329 – Structure of Status 'in position'	244
Table 330 – Attributes for IDN S-0-0337	244
Table 331 – Structure of Status ' $P \geq P_x$ '	245
Table 332 – Attributes for IDN S-0-0338	245
Table 333 – Structure of Position Feedback = active target position	246
Table 334 – Attributes for IDN S-0-0339	246
Table 335 – Structure of ' $n_{\text{feedback}} \leq \text{minimum spindle speed}$ '	246
Table 336 – Attributes for IDN S-0-0340	247
Table 337 – Structure of ' $n_{\text{feedback}} \geq \text{maximum spindle speed}$ '	247
Table 338 – Attributes for IDN S-0-0341	247

Table 339 – Structure of Status 'in position'	248
Table 340 – Attributes for IDN S-0-0342	248
Table 341 – Structure of status 'target position attained'	248
Table 342 – Attributes for IDN S-0-0343	249
Table 343 – Structure of Status 'Interpolator Halted'	249
Table 344 – Attributes for IDN S-0-0347	249
Table 345 – Attributes for IDN S-0-0348	250
Table 346 – Attributes for IDN S-0-0349	250
Table 347 – Attributes for IDN S-0-0356	251
Table 348 – Attributes for IDN S-0-0357	251
Table 349 – Attributes for IDN S-0-0358	252
Table 350 – Attributes for IDN S-0-0359	253
Table 351 – Attributes for IDN S-0-0360, IDN S-0-0361	253
Table 352 – Attributes for IDN S-0-0362, S-0-0363	254
Table 353 – MDT Data Container A List Index Structure	255
Table 354 – MDT Data Container B List Index Structure	255
Table 355 – Attributes for IDN S-0-0364, IDN S-0-0365	255
Table 356 – Attributes for IDN S-0-0366, IDN S-0-0367	256
Table 357 – AT Data Container A List Index Structure	257
Table 358 – AT Data Container B List Index Structure	257
Table 359 – Attributes for IDN S-0-0368, S-0-0369	257
Table 360 – Data Container A Pointer Structure	258
Table 361 – Data Container B Pointer Structure	258
Table 362 – Attributes for IDN S-0-0370	259
Table 363 – Attributes for IDN S-0-0371	259
Table 364 – Attributes for IDN S-0-0372	260
Table 365 – Attributes for IDN S-0-0373	260
Table 366 – Service channel error list structure	260
Table 367 – Attributes for IDN S-0-0374	261
Table 368 – Procedure Command Error List Structure	261
Table 369 – Attributes for IDN S-0-0375	261
Table 370 – Attributes for IDN S-0-0376	262
Table 371 – Baud Rate Structure	262
Table 372 – Attributes for IDN S-0-0377	263
Table 373 – Attributes for IDN S-0-0378	263
Table 374 – Attributes for IDN S-0-0379	264
Table 375 – Attributes for IDN S-0-0380	264
Table 376 – Attributes for IDN S-0-0381	265
Table 377 – Attributes for IDN S-0-0382	265
Table 378 – Attributes for IDN S-0-0383	265
Table 379 – Attributes for IDN S-0-0384	266
Table 380 – Attributes for IDN S-0-0385	266
Table 381 – Attributes for IDN S-0-0386	267

Table 382 – Attributes for IDN S-0-0387	267
Table 383 – Attributes for IDN S-0-0388	268
Table 384 – Attributes for IDN S-0-0389	268
Table 385 – Attributes for IDN S-0-0390	269
Table 386 – Attributes for IDN S-0-0391	269
Table 387 – Attributes for IDN S-0-0392	270
Table 388 – Attributes for IDN S-0-0393	270
Table 389 – Command Value Mode Structure	271
Table 390 – Attributes for IDN S-0-0394	271
Table 391 – Attributes for IDN S-0-0395	272
Table 392 – Attributes for IDN S-0-0396	272
Table 393 – Attributes for IDN S-0-0397	273
Table 394 – Attributes for IDN S-0-0398	273
Table 395 – Attributes for IDN S-0-0399	274
Table 396 – Attributes for IDN S-0-0400	274
Table 397 – Structure of Home Switch	275
Table 398 – Attributes for IDN S-0-0401	275
Table 399 – Structure of Probe 1	275
Table 400 – Attributes for IDN S-0-0402	276
Table 401 – Structure of Probe 2	276
Table 402 – Attributes for IDN S-0-0403	276
Table 403 – Structure of Position Feedback Values Status	277
Table 404 – Attributes for IDN S-0-0404	277
Table 405 – Structure of position command value status	278
Table 406 – Attributes for IDN S-0-0405	278
Table 407 – Structure of Probe 1 Enable	279
Table 408 – Attributes for IDN S-0-0406	279
Table 409 – Structure of Probe 2 Enable	279
Table 410 – Attributes for IDN S-0-0407	280
Table 411 – Structure of Homing Enable	280
Table 412 – Attributes for IDN S-0-0408	280
Table 413 – Structure of Reference Marker Pulse Registered	281
Table 414 – Attributes for IDN S-0-0409	281
Table 415 – Structure of Probe 1 Positive Latched	282
Table 416 – Attributes for IDN S-0-0410	282
Table 417 – Structure of Probe 1 Negative Latched	282
Table 418 – Attributes for IDN S-0-0411	283
Table 419 – Structure of Probe 2 Positive Latched	283
Table 420 – Attributes for IDN S-0-0412	283
Table 421 – Structure of Probe 2 Negative Latched	284
Table 422 – Attributes for IDN S-0-0413	284
Table 423 – Attributes for IDN S-0-0414	285
Table 424 – Attributes for IDN S-0-0415	285

Table 425 – Attributes for IDN S-0-0416	286
Table 426 – Attributes for IDN S-0-0429	286
Table 427 – Attributes for IDN S-0-0430	287
Table 428 – Attributes for IDN S-0-0431	287
Table 429 – Attributes for IDN S-0-0432	288
Table 430 – Attributes for IDN S-0-0433	288
Table 431 – Attributes for IDN S-0-0434	289
Table 432 – Attributes for IDN S-0-0435	289
Table 433 – Attributes for IDN S-0-0436	290
Table 434 – Attributes for IDN S-0-0446	290
Table 435 – Attributes for IDN S-0-0460 to S-0-0475	291
Table 436 – Attributes for IDN S-0-0476	291
Table 437 – Structure of the Position Switch Control	292
Table 438 – Attributes for IDN S-0-0476	292

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –**Part 7-204: Generic interface and use
of profiles for power drive systems –
Profile type 4 specification**

FOREWORD

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The International Standard IEC 61800-7-204 has been prepared by subcommittee SC 22G: Adjustable speed electric drive systems incorporating semiconductor power converters, of IEC technical committee TC 22: Power electronic systems and equipment.

The text of this standard is based on the following documents:

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Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 61800 series, under the general title *Adjustable speed electrical power drive systems*, can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to the specific publication. At this date, the publication will be

- reconfirmed;
- withdrawn;
- replaced by a revised edition, or
- amended.

A bilingual version of this publication may be issued at a later date.

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INTRODUCTION

The IEC 61800 series is intended to provide a common set of specifications for adjustable speed electrical power drive systems.

IEC 61800-7 describes a generic interface between control systems and power drive systems. This interface can be embedded in the control system. The control system itself can also be located in the drive (sometimes known as "smart drive" or "intelligent drive").

A variety of physical interfaces is available (analogue and digital inputs and outputs, serial and parallel interfaces, fieldbuses and networks). Profiles based on specific physical interfaces are already defined for some application areas (e.g. motion control) and some device classes (e.g. standard drives, positioner). The implementations of the associated drivers and application programmers interfaces are proprietary and vary widely.

IEC 61800-7 defines a set of common drive control functions, parameters, and state machines or description of sequences of operation to be mapped to the profiles.

IEC 61800-7 provides a way to access functions and data of a drive that is independent of the used drive profile and communication interface. The objective is a common drive model with generic functions and objects suitable to be mapped on different communication interfaces. This makes it possible to provide common implementations of motion control (or velocity control or drive control applications) in controllers without any specific knowledge of the drive implementation.

There are several reasons to define a generic interface:

For a drive device manufacturer

- Less effort to support system integrators
- Less effort to describe drive functions because of common terminology
- The selection of drives does not depend on availability of specific support

For a control device manufacturer

- No influence of bus technology
- Easy device integration
- Independent of a drive supplier

For a system integrator (builds modules, machines, plants etc.)

- Less integration effort for devices
- Only one understandable way of modeling
- Independent of bus technology

Much effort is needed to design a motion control application with several different drives and a specific control system. The tasks to implement the system software and to understand the functional description of the individual components may exhaust the project resources. In some cases, the drives do not share the same physical interface. Some control devices just support a single interface which will not be supported by a specific drive. On the other hand, the functions and data structures are specified with incompatibilities. It is up to the systems integrator to write interfaces to the application software to handle that which should not be his responsibility.

Some applications need device exchangeability or integration of new devices in an existing configuration. They are faced with different incompatible solutions. The efforts to adopt a solution to a drive profile and to manufacturer specific extensions may be unacceptable. This will reduce the degree of freedom to select a device best suited for this application to the selection of the unit which will be available for a specific physical interface and supported by the controller.

IEC 61800-7-1 is divided into a generic part and several annexes as shown in Figure 1. The drive profile types for CiA 402¹, CIP Motion^{TM2}, PROFIdrive³ and SERCOS Interface^{TM4} are mapped to the generic interface in the corresponding annex. The annexes have been submitted by open international network or fieldbus organizations which are responsible for the content of the related annex and use of the related trademarks.

This part of IEC 61800-7 specifies the profile type 4 (SERCOS).

The profile types 1, 2 and 3 are specified in IEC 61800-7-201, IEC 61800-7-202 and IEC 61800-7-203.

IEC 61800-7-301, IEC 61800-7-302, IEC 61800-7-303 and IEC 61800-7-304 specify how the profile types 1, 2, 3 and 4 are mapped to different network technologies (such as CANopen⁵, EtherCAT^{TM6}, Ethernet Powerlink^{TM7}, DeviceNet^{TM8}, ControlNet^{TM9}, EtherNet/IP^{TM10}, PROFIBUS¹¹, PROFINET¹² and SERCOS Interface).

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- 1 CiA 402 is a trade name of CAN in Automation, e.V. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name CiA 402.
 - 2 CIP MotionTM is a trade name of Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name CIP MotionTM. Use of the trade name CIP MotionTM requires permission of Open DeviceNet Vendor Association, Inc.
 - 3 PROFIdrive is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFIdrive. Use of the trade name PROFIdrive requires permission of PROFIBUS International.
 - 4 SERCOSTM and SERCOS InterfaceTM are trade names of SERCOS International e.V. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name SERCOS and SERCOS interface. Use of the trade name SERCOS and SERCOS interface requires permission of the trade name holder.
 - 5 CANopen is an acronym for Controller Area Network *open* and is used to refer to EN 50325-4.
 - 6 EtherCATTM is a trade name of Beckhoff, Verl. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name EtherCATTM. Use of the trade name EtherCATTM requires permission of the trade name holder.
 - 7 Ethernet PowerlinkTM is a trade name of B&R, control of trade name use is given to the non profit organisation EPSG. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name Ethernet PowerlinkTM. Use of the trade name Ethernet PowerlinkTM requires permission of the trade name holder.
 - 8 DeviceNetTM is a trade name of Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name DeviceNetTM. Use of the trade name DeviceNetTM requires permission of Open DeviceNet Vendor Association, Inc.
 - 9 ControlNetTM is a trade name of ControlNet International, Ltd. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name ControlNetTM. Use of the trade name ControlNetTM requires permission of ControlNet International, Ltd.
 - 10 EtherNet/IPTM is a trade name of ControlNet International, Ltd. and Open DeviceNet Vendor Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name EtherNet/IPTM. Use of the trade name EtherNet/IPTM requires permission of either ControlNet International, Ltd. or Open DeviceNet Vendor Association, Inc.
 - 11 PROFIBUS is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFIBUS. Use of the trade name PROFIBUS requires permission of PROFIBUS International.
 - 12 PROFINET is a trade name of PROFIBUS International. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trade name holder or any of its products. Compliance to this profile does not require use of the trade name PROFINET. Use of the trade name PROFINET requires permission of PROFIBUS International.

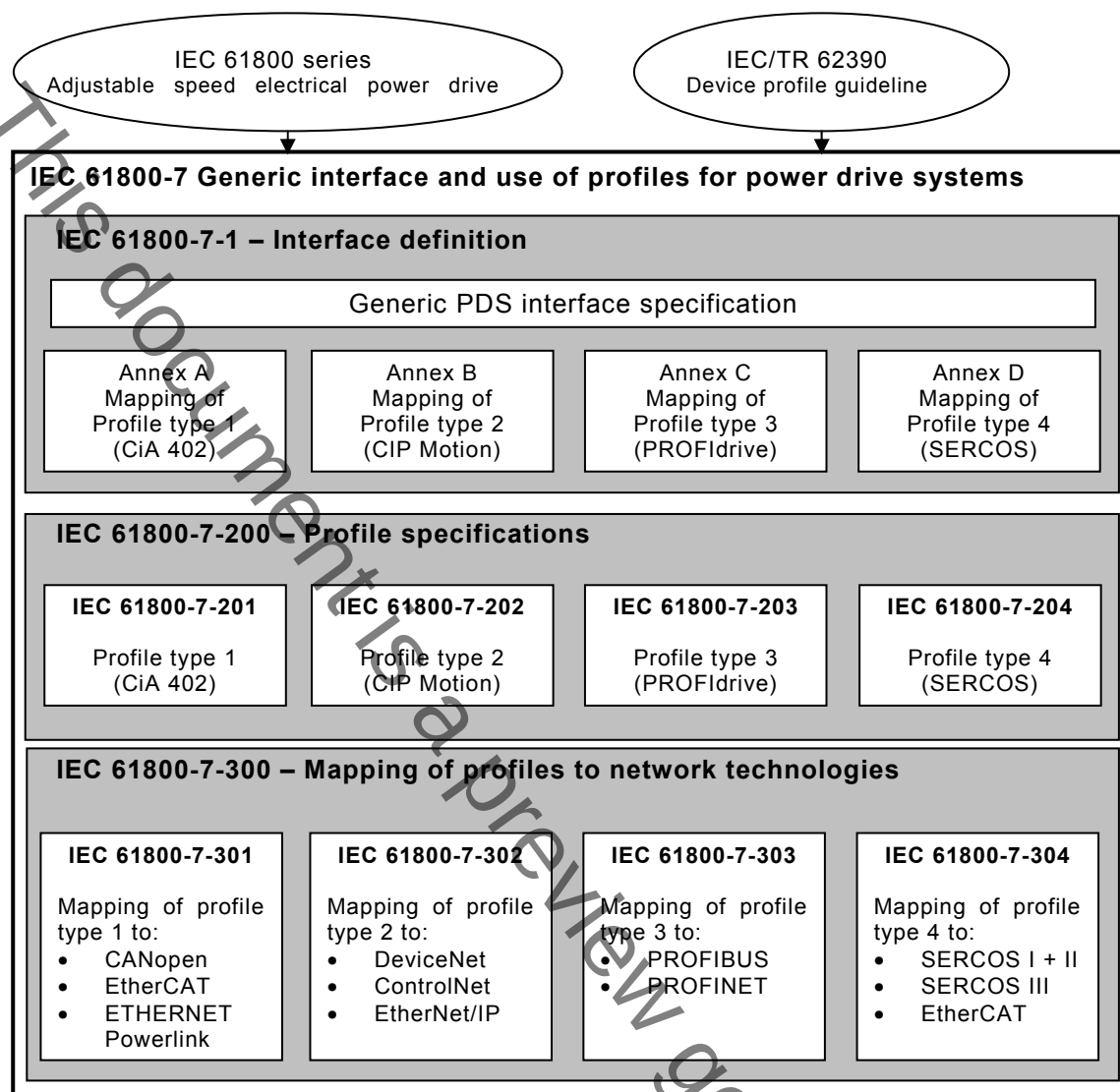


Figure 1 – Structure of IEC 61800-7

ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

Part 7-204: Generic interface and use of profiles for power drive systems – Profile type 4 specification

1 Scope

IEC 61800-7 specifies profiles for Power Drive Systems (PDS) and their mapping to existing communication systems by use of a generic interface model.

The functions specified in this part of IEC 61800-7 are not intended to ensure functional safety. This requires additional measures according to the relevant standards, agreements and laws.

This part of IEC 61800-7 specifies profile type 4 for Power Drive Systems (PDS). Profile type 4 can be mapped onto different communication network technologies.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61158-4-16, *Industrial communication networks – Fieldbus specifications – Part 4-16 (Ed.1.0): Data-link layer protocol specification – Type 16 elements*

IEC 61158-5-16, *Industrial communication networks – Fieldbus specifications – Part 5-16 (Ed.1.0): Application layer service definition – Type 16 elements*

IEC 61158-6-16, *Industrial communication networks – Fieldbus specifications – Part 6-16 (Ed.1.0): Application layer protocol specification – Type 16 elements*

IEC 61800-7 (all parts), *Adjustable speed electrical power drive systems – Generic interface and use of profiles for power drive systems*

IEC 61800-7-304, *Adjustable speed electrical power drive systems – Part 7-304: Generic interface and use of profiles for power drive systems – Mapping of profile type 4 to network technologies*

3 Terms, definitions and abbreviated terms

3.1 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

3.1.1

acknowledge telegram (AT)

telegram, in which each slave inserts its data