

**Industrial communication networks - High availability
automation networks - Part 6: Distributed Redundancy
Protocol (DRP)**

EESTI STANDARDI EESSÕNA

NATIONAL FOREWORD

Käesolev Eesti standard EVS-EN 62439-6:2010 sisaldb Euroopa standardi EN 62439-6:2010 ingliskeelset teksti.	This Estonian standard EVS-EN 62439-6:2010 consists of the English text of the European standard EN 62439-6:2010.
Standard on kinnitatud Eesti Standardikeskuse 30.04.2010 käskkirjaga ja jõustub sellekohase teate avaldamisel EVS Teatajas.	This standard is ratified with the order of Estonian Centre for Standardisation dated 30.04.2010 and is endorsed with the notification published in the official bulletin of the Estonian national standardisation organisation.
Euroopa standardimisorganisatsioonide poolt rahvuslikele liikmetele Euroopa standardi teksti kätesaadavaks tegemise kuupäev on 19.03.2010.	Date of Availability of the European standard text 19.03.2010.
Standard on kätesaadav Eesti standardiorganisatsionist.	The standard is available from Estonian standardisation organisation.

ICS 25.040, 35.040

Standardite reproduutseerimis- ja levitamisõigus kuulub Eesti Standardikeskusele

Andmete paljundamine, taastekitamine, kopeerimine, salvestamine elektroonilisse süsteemi või edastamine ükskõik millises vormis või millisel teel on keelatud ilma Eesti Standardikeskuse poolt antud kirjaliku loata.

Kui Teil on küsimusi standardite autorikaitse kohta, palun võtke ühendust Eesti Standardikeskusega:
Aru 10 Tallinn 10317 Estonia; www.evs.ee; Telefon: 605 5050; E-post: info@evs.ee

Right to reproduce and distribute Estonian Standards belongs to the Estonian Centre for Standardisation

No part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying, without permission in writing from Estonian Centre for Standardisation.

If you have any questions about standards copyright, please contact Estonian Centre for Standardisation:
Aru str 10 Tallinn 10317 Estonia; www.evs.ee; Phone: +372 605 5050; E-mail: info@evs.ee

EUROPEAN STANDARD
NORME EUROPÉENNE
EUROPÄISCHE NORM

EN 62439-6

March 2010

ICS 25.040; 35.040

Supersedes EN 62439:2008 (partially)

English version

Industrial communication networks -
High availability automation networks -
Part 6: Distributed Redundancy Protocol (DRP)
(IEC 62439-6:2010)

Réseaux de communication industrielle -
Réseaux d'automatisme à haute
disponibilité -
Partie 6 :Protocole de redondance
distribuée (DRP)
(CEI 62439-6:2010)

Industrielle Kommunikationsnetze -
Hochverfügbare Automatisierungsnetze -
Teil 6: Protokoll für verteilte Redundanz
(DRP)
(IEC 62439-6:2010)

This European Standard was approved by CENELEC on 2010-03-01. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

Up-to-date lists and bibliographical references concerning such national standards may be obtained on application to the Central Secretariat or to any CENELEC member.

This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CENELEC member into its own language and notified to the Central Secretariat has the same status as the official versions.

CENELEC members are the national electrotechnical committees of Austria, Belgium, Bulgaria, Croatia, Cyprus, the Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, the Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and the United Kingdom.

CENELEC

European Committee for Electrotechnical Standardization
Comité Européen de Normalisation Electrotechnique
Europäisches Komitee für Elektrotechnische Normung

Central Secretariat: Avenue Marnix 17, B - 1000 Brussels

Foreword

The text of document 65C/583/FDIS, future edition 1 of IEC 62439-6, prepared by SC 65C, Industrial networks, of IEC TC 65, Industrial-process measurement, control and automation, was submitted to the IEC-CENELEC parallel vote and was approved by CENELEC as EN 62439-6 on 2010-03-01.

This EN 62439-6 together with EN 62439-1, EN 62439-2, EN 62439-3, EN 62439-4 and EN 62439-5 supersedes EN 62439:2008.

EN 62439-6:2010 includes the following significant technical changes with respect to EN 62439:2008:

- adding a calculation method for RSTP (rapid spanning tree protocol, IEEE 802.1Q),
- adding two new redundancy protocols: HSR (High-availability Seamless Redundancy) and DRP (Distributed Redundancy Protocol),
- moving former Clauses 1 to 4 (introduction, definitions, general aspects) and the Annexes (taxonomy, availability calculation) to EN 62439-1, which serves now as a base for the other documents,
- moving Clause 5 (MRP) to EN 62439-2 with minor editorial changes,
- moving Clause 6 (PRP) was to EN 62439-3 with minor editorial changes,
- moving Clause 7 (CRP) was to EN 62439-4 with minor editorial changes, and
- moving Clause 8 (BRP) was to EN 62439-5 with minor editorial changes,
- adding a method to calculate the maximum recovery time of RSTP in a restricted configuration (ring) to EN 62439-1 as Clause 8,
- adding specifications of the HSR (High-availability Seamless Redundancy) protocol, which shares the principles of PRP to EN 62439-3 as Clause 5, and
- introducing the DRP protocol as EN 62439-6.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN and CENELEC shall not be held responsible for identifying any or all such patent rights.

The following dates were fixed:

- latest date by which the EN has to be implemented at national level by publication of an identical national standard or by endorsement
- latest date by which the national standards conflicting with the EN have to be withdrawn

(dop) 2010-12-01

(dow) 2013-03-01

Annex ZA has been added by CENELEC.

Endorsement notice

The text of the International Standard IEC 62439-6:2010 was approved by CENELEC as a European Standard without any modification.

In the official version, for Bibliography, the following notes have to be added for the standards indicated:

- | | |
|-------------|--------------------------------|
| IEC 62439-2 | NOTE Harmonized as EN 62439-2. |
| IEC 62439-3 | NOTE Harmonized as EN 62439-3. |
| IEC 62439-4 | NOTE Harmonized as EN 62439-4. |
| IEC 62439-5 | NOTE Harmonized as EN 62439-5. |
-

This document is a preview generated by EVS

Annex ZA
(normative)

**Normative references to international publications
with their corresponding European publications**

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE When an international publication has been modified by common modifications, indicated by (mod), the relevant EN/HD applies.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 60050-191	-	International Electrotechnical Vocabulary (IEV) - Chapter 191: Dependability and quality of service	-	-
IEC 61158	Series	Fieldbus standard for use in industrial control systems	EN 61158	Series
IEC 61588	2009	Precision clock synchronization protocol for networked measurement and control systems	-	-
IEC 62439-1	2010	Industrial communication networks - High availability automation networks - Part 1: General concepts and calculation methods	EN 62439-1	2010
ISO/IEC/TR 8802-1	-	Information technology - Telecommunications - and information exchange between systems - Local and metropolitan area networks - Specific requirements - Part 1: Overview of Local Area Network Standards	-	-
ISO/IEC 8802-3	2000	Information technology - Telecommunications - and information exchange between systems - Local and metropolitan area networks - Specific requirements - Part 3: Carrier sense multiple access with collision detection (CSMA/CD) access method and physical layer specifications	-	-
IEEE 802.1D	2004	IEEE Standard for Local and Metropolitan Area Networks - Media Access Control (MAC) Bridges	-	-
IEEE 802.1Q	-	IEEE Standard for Local and Metropolitan Area Networks - Virtual Bridged Local Area Networks	-	-

CONTENTS

FOREWORD	5
INTRODUCTION	7
1 Scope	8
2 Normative references	8
3 Terms, definitions, abbreviations, acronyms, and conventions	8
3.1 Terms and definitions	8
3.2 Abbreviations and acronyms	9
3.3 Conventions	9
4 Overview	9
4.1 Principles	9
4.2 Ring ports	10
4.3 DRP switch node	10
4.4 Single ring topology redundancy	11
4.5 Double ring topology redundancy	11
4.6 Configuration	12
4.6.1 Overview	12
4.6.2 Manufacturer configuration	12
4.6.3 Communication configuration	12
4.6.4 Application configuration	13
4.7 Start up	13
5 DRP communications	13
5.1 Overview	13
5.2 Communication procedure	15
5.3 Fault detection and recovery	18
5.3.1 General	18
5.3.2 Handling in a single ring network	19
5.3.3 Handling in a double ring network	20
5.4 Repairing the inter-switch link fault	21
5.5 Repairing time synchronization fault	21
5.6 Inserting a repaired switch node	22
5.7 Inserting a new switch node	23
6 DRP class specification	23
7 DRP attributes	24
8 DRP services	27
8.1 Read	27
8.2 Write	30
9 DRP protocol specification	32
9.1 Basic types encoding	32
9.2 ErrorDescription encoding	32
9.3 Encoding of DRP Class	33
9.4 PDU description	34
9.4.1 Encoding of DRP DLPDU	34
9.4.2 Encoding of DLSDU	35
9.4.3 Encoding of VLAN	35
9.4.4 Ethertype	35

9.4.5 Encoding of DRP PDU	35
9.4.6 Encoding of DRP_DATA	36
9.4.7 Encoding of Read Service	40
9.4.8 Encoding of Write Service primitives.....	42
9.5 Protocol machine.....	44
9.5.1 Switch node states description	44
9.5.2 Protocol State Machine description.....	44
9.5.3 State transitions	45
9.5.4 Function descriptions.....	52
Bibliography.....	64
Figure 1 – DRP communication model	10
Figure 2 – Single ring topology redundancy	11
Figure 3 – Double ring topology redundancy	12
Figure 4 – DRP communication procedure	14
Figure 5 – Inserting a new switch node into the DRP system	14
Figure 6 – Fault detection and recovery	15
Figure 7 – Fault detection and recovery of single ring topology redundancy	19
Figure 8 – Single inter-switch link fault detection and recovery of double ring topology redundancy.....	20
Figure 9 – Double inter-switch link fault detection and recovery of double ring topology redundancy.....	21
Figure 10 – Inserting a repaired switch node.....	22
Figure 11 – DRP protocol state machine	45
Table 1 – Relationship between required recovery time and the TargetTimeSyncClass	22
Table 2 – Parameters of Read service	27
Table 3 – Parameters of Write service	30
Table 4 – Error Type definition.....	32
Table 5 – Error Code definition	33
Table 6 – Definition of DRP Class	33
Table 7 – DRP OUI	34
Table 8 – DRP MulticastMACAddress	35
Table 9 – Encoding of DLSDU	35
Table 10 – Encoding of DRP PDU.....	35
Table 11 – DRP_Type definition	35
Table 12 – Encoding of RingCheck frame	36
Table 13 – Encoding of DeviceAnnunciation frame.....	37
Table 14 – Encoding of RingChange frame	39
Table 15 – Encoding of LinkCheck frame	39
Table 16 – Encoding of LinkAlarm frame.....	40
Table 17 – Encoding of LinkChange frame.....	40
Table 18 – Encoding of Read Request	41
Table 19 – Encoding of Read Service Positive Response	41
Table 20 – Encoding of Read Service Negative Response	42

Table 21 – Encoding of Write Request	43
Table 22 – Encoding of Write Service Positive Response.....	43
Table 23 – Encoding of Write Service Negative Response	43
Table 24 – DRP state transitions.....	46
Table 25 – SetRingPortState() descriptions	52
Table 26 – LoadRingPortState() descriptions	52
Table 27 – WriteSucceed() descriptions	52
Table 28 – SynchronizationFinished() descriptions	53
Table 29 – ActivePortLinkState() descriptions	53
Table 30 – StandbyPortLinkState() descriptions.....	53
Table 31 – ConfigureInfo() descriptions	53
Table 32 – DRPSendTimer() descriptions	54
Table 33 – SendRingChange() descriptions	54
Table 34 – ForwardingRingCheck() descriptions	54
Table 35 – AnnunciationBlockingPort() descriptions.....	54
Table 36 – LocalDRPSequenceIDSmaller() descriptions	55
Table 37 – RecvAnnunciationWithinTimeLimit() descriptions.....	55
Table 38 – RecvLinkCheckWithinTimeLimit() descriptions.....	55
Table 39 – NoLocalLinkFault() descriptions	55
Table 40 – RecvLinkAlarm() descriptions	56
Table 41 – Clear_FDB() descriptions	56
Table 42 – ChangeRingState() descriptions	56
Table 43 – BlockingPortSelect() descriptions	56
Table 44 – SendLinkChange() descriptions	57
Table 45 – DRPSequenceIDCompare() descriptions	57
Table 46 – ChangePortState() descriptions	57
Table 47 – ChangeDoublePortState() descriptions	57
Table 48 – LocalSendRingCheck() descriptions	58
Table 49 – DRPKeyParaConfigure() descriptions	58
Table 50 – CheckMACAddress() descriptions	58
Table 51 – SetDRPKeyPara() descriptions	58
Table 52 – SendDeviceAnnunciation() descriptions.....	59
Table 53 – FaultRecvRingCheck() descriptions	59
Table 54 – RecordDeviceState() descriptions	59
Table 55 – DrpRecvMsg() descriptions	59
Table 56 – SendLinkAlarm() descriptions	60
Table 57 – TimeUnsynchronization() descriptions	60
Table 58 – PassiveMasterState() descriptions	60
Table 59 – SearchDeviceState() descriptions.....	60
Table A.1 – An example of parameters setting for DRP Class	62
Table A.2 – Parameters for calculation of recovery time.....	63

INTRODUCTION

The IEC 62439 series specifies relevant principles for high availability networks that meet the requirements for industrial automation networks.

In the fault-free state of the network, the protocols of the IEC 62439 series provide ISO/IEC 8802-3 (IEEE 802.3) compatible, reliable data communication, and preserve determinism of real-time data communication. In cases of fault, removal, and insertion of a component, they provide deterministic recovery times.

These protocols retain fully the typical Ethernet communication capabilities as used in the office world, so that the software involved remains applicable.

The market is in need of several network solutions, each with different performance characteristics and functional capabilities, matching diverse application requirements. These solutions support different redundancy topologies and mechanisms which are introduced in IEC 62439-1 and specified in the other Parts of the IEC 62439 series. IEC 62439-1 also distinguishes between the different solutions, giving guidance to the user.

The IEC 62439 series follows the general structure and terms of IEC 61158 series.

The International Electrotechnical Commission (IEC) draws attention to the fact that it is claimed that compliance with this document may involve the use of a patent concerning about the communication procedure and fault detection and recovery for DRP given in 5.2 and 5.3.

IEC takes no position concerning the evidence, validity and scope of this patent right.

The holder of this patent right has assured the IEC that he/she is willing to negotiate licences either free of charge or under reasonable and non-discriminatory terms and conditions with applicants throughout the world. In this respect, the statement of the holder of this patent right is registered with IEC. Information may be obtained from:

SUPCON Group Co., Ltd & Zhejiang University
Hangzhou
China

Beijing Kyland Technology Co. LTD
No 95 Building
Southeast Corner of Xisanqi Bridge
Haidian
Beijing
China

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights other than those identified above. IEC shall not be held responsible for identifying any or all such patent rights.

ISO (www.iso.org/patents) and IEC (http://www.iec.ch/tctools/patent_decl.htm) maintain on-line data bases of patents relevant to their standards. Users are encouraged to consult the data bases for the most up to date information concerning patents.

INDUSTRIAL COMMUNICATION NETWORKS – HIGH AVAILABILITY AUTOMATION NETWORKS –

Part 6: Distributed Redundancy Protocol (DRP)

1 Scope

The IEC 62439 series is applicable to high-availability automation networks based on the ISO/IEC 8802-3 (IEEE 802.3) (Ethernet) technology.

This part of the IEC 62439 series specifies a recovery protocol based on a ring topology, designed to react deterministically on a single failure of an inter-switch link or switch in the network. Each switch has equal management role in the network. Double rings are supported.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60050-191, *International Electrotechnical Vocabulary – Chapter 191: Dependability and quality of service*

IEC 61158 (all parts), *Industrial communication networks – Fieldbus specifications*

IEC 61588:2009, *Precision clock synchronization protocol for networked measurement and control systems* (IEEE 1588)

IEC 62439-1:2010, *Industrial communication networks – High availability automation networks – Part 1: General concepts and calculation methods*

ISO/IEC/TR 8802-1, *Information technology – Telecommunications and information exchange between systems – Local and metropolitan area networks – Specific requirements – Part 1: Overview of Local Area Network Standards Technologies de* (IEEE 802.1)

ISO/IEC 8802-3:2000, *Information technology – Telecommunications and information exchange between systems – Local and metropolitan area networks – Specific requirements – Part 3: Carrier sense multiple access with collision detection (CSMA/CD) access method and physical layer specifications*

IEEE 802.1D:2004, *IEEE standard for local and metropolitan area networks Media Access Control (MAC) Bridges*

IEEE 802.1Q, *IEEE standards for local and metropolitan area network. Virtual bridged local area networks*

3 Terms, definitions, abbreviations, acronyms, and conventions

3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC 60050-191, as well as in IEC 62439-1, apply, in addition to the following.