# **TECHNICAL REPORT**

ISO/TR 16158

> Second edition 2021-10

# Spame. Systèmes sp. Space systems — Avoiding collisions

Systèmes spatiaux — Évitement des collisions entre objets en orbite





© ISO 2021

mentation, no part of ral, including phory rd from either All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. de Blandonnet 8 CH-1214 Vernier, Geneva Phone: +41 22 749 01 11 Email: copyright@iso.org Website: www.iso.org

Published in Switzerland

Contents			Page
Forew	ord		v
Intro	luctio	n	vi
1	Scope	e	1
2		native references	
3	Terms and definitions		
4		sion avoidance workflow	
5	Perceiving close approaches		
	5.1	Orbit data	2 3 3
	5.3	5.2.1 All against all Eliminating infeasible conjunctions 5.3.1 General 5.3.2 Sieve 5.3.3 Toroidal elimination 5.3.4 Apogee-perigee filters 5.3.5 Statistical errors	3 3 4
6	Deter scree 6.1 6.2 6.3 6.4 6.5 6.6 6.7	rmining potential collisions for warning and further action (close approach ening)  General  Symmetric keepout  Bounding volume keepout  Probability techniques  Maximum probability  Bounding volume based on probability  Comparison of techniques	
7	Proba 7.1 7.2 7.3 7.4	ability of survival General Trending Cumulative probability Bayesian assessment	101111
8	Addit 8.1 8.2 8.3 8.4	tional information for judging courses of action  General  Manoeuvre capability  Spacecraft characteristics  Quality of underlying orbit data	13 13
9	9.1 9.2 9.3	equence assessment General Guidance for population risk Traffic impacts	13 13 14
10	Requ 10.1 10.2 10.3 10.4	General Orbit data Minimum data required for warning of and avoiding collisions Optional elements of information	14 14 15
11	Conjunction and collision assessment workflow and operational concept16		
Annex		nformative) Relationship between combined object size, combined positional r, and maximum probability	19

## ISO/TR 16158:2021(E)

Annex B (informative) Probability contour visualization	21
Bibliography	31
0.	
0.	
	<b>)</b>
	0
	6.
	//_

### **Foreword**

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see <a href="www.iso.org/directives">www.iso.org/directives</a>).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see <a href="https://www.iso.org/patents">www.iso.org/patents</a>).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see <a href="https://www.iso.org/iso/foreword.html">www.iso.org/iso/foreword.html</a>.

This document was prepared by Technical Committee ISO/TC 20, *Aircraft and space vehicles*, Subcommittee SC 14, *Space systems and operations*.

This second edition cancels and replaces the first edition (ISO/TR 16158:2013), which has been technically revised.

The main changes compared to the previous edition are as follows:

- improved figures for clarity;
- added plot of maximum probability;
- switched to "decimal comma" per ISO editorial rules;
- simplified operational concepts figures;
- added informative annexes containing collision probability relational nomograms;
- added collision probability topology in both graphical and tabular look-up formats;
- reordered the bibliography.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at <a href="https://www.iso.org/members.html">www.iso.org/members.html</a>.

### Introduction

This document describes the workflow for perceiving and avoiding collisions among orbiting objects, data requirements for these tasks, techniques that can be used to estimate the probability of collision and guidance for executing avoidance manoeuvres. Diligent collaboration is strongly encouraged among all who operate satellites.

The process begins with the best possible trajectory data, provided by satellite operators or sensor systems developed for this purpose. The orbits of satellites can be compared with each other to discern physically feasible approaches that can result in collisions. The trajectories so revealed can then be examined more closely to estimate the probability of collision. Where the possibility of a collision has been identified within the criteria established by each satellite operator, the spectrum of feasible manoeuvres is examined.

There are several different approaches to conjunction assessment. All have merits and deficiencies. Most focus on how closely satellites approach each other. This is often very uncertain since satellite orbits generally change more rapidly under the influence of non-conservative forces than observations of satellites in orbit can be acquired and employed to improve orbit estimates. Spacecraft operators require the fullness of orbit data to judge the credibility and quality of conjunction perception. This information includes the moment of time of the last elaboration of orbit (the epoch) and the standard time scale employed, state vector value or elements of orbit at this moment of time, the coordinate system description that presents the orbital data, the forces model description that was used for orbital plotting, and information about the estimation errors of the orbital parameters. Essential elements of information for this purpose are specified in ISO 26900.

There are also diverse approaches to estimating the probability that a close approach can really result in a collision. This is a statistical process very similar to weather forecasting. Meteorologists no longer make definitive predictions. They provide the probability of precipitation, not whether it will rain. All conjunction assessment approaches are in some way founded in probabilities. Probability of collision is also a highly desirable element of data. It can be accompanied by metadata that allows operators to interpret the information within their own operational procedures.

How near satellites can be to each other and the probability they can collide if they were that close are only two discriminants of potentially catastrophic events. Since the objective is that the satellite survives despite many potential close approaches, cumulative probability of survival is also important information. Responding precipitously to the close approach nearest at hand can only delay the demise of the satellite or even contribute to a subsequent more serious event. The evolution of close approaches and the cumulative probability that a satellite can survive are also important.

Finally, the state of each of the conjunction partners, their ability to manoeuvre or otherwise avoid contact, and the outcomes of past events that are similar guide courses of action.

# Space systems — Avoiding collisions among orbiting objects

### 1 Scope

This document is a guide for establishing essential collaborative enterprises to sustain the space environment and employ it effectively.

This document describes some widely used techniques for perceiving close approaches, estimating collision probability, estimating the cumulative probability of survival, and manoeuvring to avoid collisions.

NOTE Satellite operators accept that all conjunction and collision assessment techniques are statistical. All suffer false positives and/or missed detections. The degree of uncertainty in the estimated outcomes is not uniform across all satellite orbits or all assessment intervals. No comparison within a feasible number of test cases can reveal the set of techniques that is uniformly most appropriate for all.

### 2 Normative references

There are no normative references in this document.

### 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <a href="https://www.iso.org/obp">https://www.iso.org/obp</a>
- IEC Electropedia: available at <a href="https://www.electropedia.org/">https://www.electropedia.org/</a>

### 3.1

### collision

act of colliding; instance of one object striking another

### 3.2

### conjunction

apparent meeting or passing of two or more objects in space

### 3.3

### covariance

measure of how much variables change together

Note 1 to entry: For multiple dependent variables, a square, symmetric, positive definite matrix of dimensionality  $N \times N$ , where N is the number of variables.

### 3.4

### encounter plane

plane normal to the relative velocity at the time of closest approach

### 3.5

### ephemeris

time-ordered set of position and velocity within which one interpolates to estimate the position and velocity at intermediate times