



Edition 2.1 2022-03 CONSOLIDATED VERSION

INTERNATIONAL STANDARD



Communication networks and systems for power utility automation – Part 5: Communication requirements for functions and device models





THIS PUBLICATION IS COPYRIGHT PROTECTED Copyright © 2022 IEC, Geneva, Switzerland

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from either IEC or IEC's member National Committee in the country of the requester. If you have any questions about IEC copyright or have an enquiry about obtaining additional rights to this publication, please contact the address below or your local IEC member National Committee for further information.

IEC Secretariat 3, rue de Varembé CH-1211 Geneva 20 Switzerland

Tel.: +41 22 919 02 11 info@iec.ch

www.iec.ch

About the IEC

The International Electrotechnical Commission (IEC) is the leading global organization that prepares and publishes International Standards for all electrical, electronic and related technologies.

The technical content of IEC publications is kept under constant review by the IEC. Please make sure that you have the latest edition, a corrigendum or an amendment might have been published.

IEC publications search - webstore.iec.ch/advsearchform

The advanced search enables to find IEC publications by a variety of criteria (reference number, text, technical committee, ...). It also gives information on projects, replaced and withdrawn publications.

IEC Just Published - webstore.iec.ch/justpublished
Stay up to date on all new IEC publications. Just Published details all new publications released. Available online and once a month by email.

IEC Customer Service Centre - webstore.iec.ch/csc

If you wish to give us your feedback on this publication or need further assistance, please contact the Customer Service Centre: sales@iec.ch.

IEC Products & Services Portal - products.iec.ch

Discover our powerful search engine and read freely all the publications previews. With a subscription you will always have access to up to date content tailored to your needs.

Electropedia - www.electropedia.org

The world's leading online dictionary on electrotechnology, containing more than 22 300 terminological entries in English and French, with equivalent terms in 19 additional languages. Also known as the International Electrotechnical Vocabulary (IEV) online.



Edition 2.1 2022-03 CONSOLIDATED VERSION

INTERNATIONAL STANDARD



Communication networks and systems for power utility automation – Part 5: Communication requirements for functions and device models

INTERNATIONAL ELECTROTECHNICAL COMMISSION

ICS 33.200 ISBN 978-2-8322-1095-7

Warning! Make sure that you obtained this publication from an authorized distributor.

CONTENTS

Н	JREWO	RD	9
ΙN	TRODU	CTION	11
1	Scop	• e	12
2	Norm	ative references	12
3		s and definitions	
•	3.1	General	
	3.2	Connections	
	3.3	Relations between IEDs	
	3.4	Substation structures	
	3.5	Power utility automation functions at different levels	
	3.6	Miscellaneous	
4	Abbre	eviations	20
5	Powe	er utility automation functions	21
	5.1	General	
	5.2	Example substation automation system.	
	5.2.1	General	
	5.2.2		
	5.2.3		
	5.2.4		
	5.3	Other application examples	24
	5.3.1	Substation – Substation	24
	5.3.2	Substation – Network Control Center	24
	5.3.3		
	5.3.4	Hydro	24
	5.3.5		
	5.3.6		
	5.3.7		
6	Goal	and requirements	
	6.1	Interoperability	
	6.2	Static design requirements	
	6.3	Dynamic interaction requirements	27
	6.4	Response behaviour requirements	
	6.5	Approach to interoperability	
	6.6	Conformance test requirements	
7	Cate	gories of application functions	
	7.1	General	
	7.2	System support functions	
	7.3	System configuration or maintenance functions	
	7.4	Operational or control functions	
	7.5	Bay local process automation functions	
_	7.6	Distributed process automation functions	
8		ription and requirements of application functions	
	8.1	Approach	
	8.2	Application function description	
	8.3	The PICOM description	31

	8.3.1	The PICOM approach	31
	8.3.2	The content of PICOM description	31
	8.3.3	Attributes of PICOMs	32
	8.3.4	PICOM attributes to be covered by any message	32
	8.3.5	PICOM attributes to be covered at configuration time only	32
	8.3.6	PICOM attributes to be used for data flow calculations only	32
	8.4	Logical node description	
	8.4.1	The logical node concept	
	8.4.2	Logical nodes and logical connections	
	8.4.3	Examples for decomposition of common functions into logical nodes	34
	8.5	List of logical nodes	
	8.5.1	Logical Node allocation and distributed application functions	
	8.5.2	Explanation of tables	36
	8.5.3	Defining and modelling of protection functions	
	8.5.4	Defining and modelling of protection related functions	43
	8.5.5	Defining and modelling control functions	45
	8.5.6	Definition and modelling Interfaces, logging and archiving functions	46
	8.5.7	Defining and modelling automatic process control functions	47
	8.5.8	Defining and modelling functional block functions	48
	8.5.9	Defining and modelling metering and measurement functions	49
	8.5.1		
	8.5.1	3	
	8.5.1		
	8.5.1	3	
	8.5.1	5 1	
	8.5.1	3	
	8.5.1		
	8.5.1	3	
	8.5.1		
	8.5.1		
	8.5.2	V 1	
	8.5.2		
	8.5.2	3 3 1	
	8.6	Definition and modelling of mechanical non-electrical process equipment	
9	The a	application concept for Logical Nodes	
	9.1	Example out of the substation automation domain	
	9.2	Typical allocation and use of Logical Nodes	
	9.2.1	Free allocation of Logical Nodes	
	9.2.2	Station level	60
	9.2.3	Bay level	
	9.2.4	Process/switchgear level	61
	9.2.5	The use of generic Logical Nodes	
	9.3	Basic examples	
	9.4	Additional examples	
	9.5	Modelling	
	9.5.1	Important remarks	
	9.5.2	Object classes and instances	
	9.5.3	Requirements and modelling	
	9.5.4	Logical Nodes and modelling	64

9.5.5 Use of Logical Nodes for applications	65
10 System description and system requirements	65
10.1 Need for a formal system description	65
10.2 Requirements for Logical Node behaviour in the system	
11 Performance requirements	66
11.1 Time synchronisation	66
11.1.1 Basics	66
11.2 Message performance requirements	70
11.2.1 Basic definitions and requirements	70
11.2.2 Concepts of message types and performance classes	
11.2.3 Definition of transfer time and synchronization classes	
11.3 Definition of messages types and performances classes	
11.3.1 Type 1 – Fast messages ("Protection")	
11.3.2 Type 2 – Medium speed messages ("Automatics")	
11.3.3 Type 3 – Low speed messages ("Operator")	
11.3.4 Type 4 – Raw data messages ("Samples")	
11.3.5 Type 5 – File transfer functions	
11.3.6 Type 6 – Command messages and file transfer with access control	
11.4 Requirements for data and communication quality	
11.4.1 General remarks	
11.4.2 Data integrity	
11.4.3 Reliability	
11.5 Requirements concerning the communication system	
11.5.1 Communication failures	
11.5.2 Requirements for station and bay level communication	
11.5.3 Requirements for process level communication	
11.5.4 Requirements for recovery delay	
11.5.5 Requirements for communication redundancy	
11.6 System performance requirements	
12 Additional requirements for the data model	
12.1 Semantics	
12.2 Logical and physical identification and addressing	
12.3 Self-description	
12.4 Administrative issues	84
Annex A (informative) Logical nodes and related PICOMs	
Annex B (informative) PICOM identification and message classification	
B.1 General	
B.2 Identification and type allocation of PICOMs	
Annex C (informative) Communication optimization	
Annex D (informative) Rules for function definition	110
D.1 Function definition	110
D.2 Function description	110
D.2.1 Task of the function	110
D.2.2 Starting criteria for the function	110
D.2.3 Result or impact of the function	
D.2.4 Performance of the function	110
D.2.5 Function decomposition	110
D.2.6 Interaction with other functions	110

D.3 Log	gical node description	111
D.3.1	General	111
D.3.2	Starting criteria	111
D.4 PIC	COM description	111
D.4.1	Input and outputs by PICOMs	111
D.4.2	Operation modes	111
D.4.3	Performance	111
Annex E (info	rmative) Interaction of functions and logical nodes	112
Annex F (info	rmative) Functions	113
F.1 Sys	stem support functions	113
F.1.1	Network management	113
F.1.2	Time synchronization	114
F.1.3	Physical device self-checking	114
F.1.4	Software management	115
F.1.5	Configuration management	116
F.1.6	Operative mode control of logical nodes	117
F.1.7	Setting	118
F.1.8	Test mode	119
F.1.9	System security management	120
F.2 Ope	erational or control functions	120
F.2.1	Access security management	120
F.2.2	Control	122
F.2.3	Operational use of spontaneous change of indications	123
F.2.4	Synchronized switching (point-on-wave switching)	124
F.2.5	Parameter set switching	
F.2.6	Alarm management	125
F.2.7	Event management (SER)	126
F.2.8	Data retrieval of configuration data and settings	127
F.2.9	Disturbance/fault record retrieval	128
F.2.10	Log management	128
F.3 Loc	cal process automation functions	128
F.3.1	Protection function (generic)	128
F.3.2	Distance protection (example of protection function)	129
F.3.3	Bay interlocking	130
F.4 Dis	tributed automatic functions	130
F.4.1	Station-wide interlocking	130
F.4.2	Distributed synchrocheck	131
F.4.3	Breaker failure	132
F.4.4	Automatic protection adaptation (generic)	133
F.4.5	Reverse blocking function (example for automatic protection adaptation)	133
F.4.6	Load shedding	. 134
F.4.7	Load restoration	134
F.4.8	Voltage and reactive power control	135
F.4.9	Infeed switchover and transformer change	
F.4.10	Automatic switching sequences	
Anney G (info	rmative) Pacults from function description	138

0.120	
Annex H (informative) Substation configurations	144
H.1 Selected substations and associated layouts	144
H.2 Assigned protection and control functions	
H.2.1 General	
H.2.2 Substation T1-1	
H.2.3 Substation D2-1 H.2.4 Substation T1-2	
H.2.5 Substation T2-2	
Annex I (informative) Examples for protection functions in compensated networks	
I.1 The Transient Earth Fault (PTEF)	
I.2 Short term bypass (YPSH)	
I.3 The double earth fault (PTOC)	
Bibliography	151
Figure 2 – Levels and logical interfaces in substation automation systems	22
Figure 3 – The logical node and link concept (explanation see text)	34
Figure 4 – Examples of the application of the logical node concept (explanation see text	35
Figure 5 – Protection function consisting of three Logical Nodes	36
Figure 6 – The basic communication links of a logical node of main protection type	43
Figure 7 – Decomposition of functions into interacting LNs on different levels: Examples for generic automatic function, breaker control function and voltage control function	61
Figure 8 – Decomposition of functions into interacting LN on different levels: Examples for generic function with telecontrol interface, protection function and measuring/metering function	
Figure 9 – Example for control and protection LNs of a transformer bay combined in one physical device (some kind of maximum allocation)	
Figure 10 – Example for interaction of LNs for switchgear control, interlocking, synchrocheck, autoreclosure and protection (Abbreviation for LN see above)	63
Figure 11 – Example for sequential interacting of LNs (local and remote) in a complex function like point-on-wave switching (Abbreviations for LN see above) – Sequence view	63
Figure 12 – Circuit breaker controllable per phase (XCBR instances per phase) and instrument transformers with measuring units per phase (TCTR or TVTR per phase)	64
Figure 14 – Transfer time for binary signal with conventional output and input delays	71
Figure 15 – Definition of transfer time <i>t</i> for binary signals in case of line protection	72
Figure 16 – Definition of transfer time t over serial link in case of line protection	73
Figure H.1 – T1-1 Small size transmission substation (single busbar 132 kV with infeed from 220 kV)	144
Figure H.2 – D2-1 Medium size distribution substation (double busbar 22 kV with infeed from 69 kV)	144
Figure H.3 – T1-2 Small size transmission substation (1 1/2 breaker busbar at 110 kV)	144
Figure H.4 – T2-2 Large size transmission substation (ring bus at 526 kV, double busbar at 138 kV)	145
Figure H.5 – Substation of type T1-1 with allocation functions	146
Figure H.6 – Substation of type D2-1 with allocated functions	147
Figure H.7 – Substation of type T1-2 $$ (functions allocated same as for T2-2 in Figure H.8)	3).147
Figure H.8 – Substation of type T2-2 with allocated functions	148
Figure I.1 – The transient earth fault in a compensated network	149

Figure I.2 – Short term bypass for single earth fault in compensated networks	150
Figure I.3 – Double earth fault in compensated networks	150
Table 8 – Logical Nodes for protection functions	37
Table 9 – Logical Nodes for protection related functions	43
Table 10 – Logical Nodes for control functions	45
Table 11 – Logical Nodes for interface functions	46
Table 12 – Logical Nodes for automatic process control functions	47
Table 13 – Logical Nodes for functional block functions	49
Table 14 – Logical Nodes for metering and measurement functions	50
Table 15 – Logical Nodes for power quality functions	51
Table 16 – Logical Nodes for physical device functions and common data	52
Table 17 – Logical Nodes for time, supervision and testing	53
Table 18 – Logical Nodes for system and device security	53
Table 19 – Logical Nodes for switching devices	54
Table 20 – Logical Nodes for supervision and monitoring functions	54
Table 21 – Logical Nodes for instrument transformers functions	
Table 22 – Logical Nodes for position sensor functions	56
Table 23 – Logical Nodes for material status sensor functions	
Table 24 – Logical Nodes for flow status sensor functions	
Table 25 – Logical Nodes for Generic Sensor Functions	
Table 26 – Logical Nodes for power transformer functions	
Table 27 – Logical Nodes for further power system equipment	
Table 28 – Logical Nodes for generic process I/O	59
Table 29 – Logical Nodes for mechanical non-electrical process equipment	
Table 2 – Time synchronization classes for AC applications synchronization	
Table 3 – Time synchronization classes for time tagging or sampling	68
Table 30 – Classes for transfer times	75
Table 31 Data integrity classes	
Table 32 – Security classes	
Table 33 – Dependability classes	
Table 34 – Requirements for recovery time (examples)	
Table A.1 – PICOM groups	
Table A.2 – Logical node list	
Table B.1 – PICOM identification (Part 1)	
Table B.2 – PICOM identification (Part 2)	
Table B.3 – PICOM allocation (Part 1)	
Table B.4 – PICOM allocation (Part 2)	
Table B.5 – PICOM types	
Table G.1 – Function-function interaction (Part 1)	
Table G.2 – Function-function interaction (Part 2)	
Table G.3 – Function decomposition into logical nodes (Part 1)	
Table G.4 – Function decomposition into logical nodes (Part 2)	

	– 8 – IEC 61850-5:201	13+AMD1:2022 CSV ⊚ IEC 2022
Table G.5 – Function decomposition into lo		
Table G.6 – Function decomposition into lo		
Table G.6 – Function decomposition into local Table H.1 – Definition of the configuration of	gical nodes (Part 4)	143
		5 TS

INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMUNICATION NETWORKS AND SYSTEMS FOR POWER UTILITY AUTOMATION –

Part 5: Communication requirements for functions and device models

FOREWORD

- 1) The International Electrotechnical Commission (IEC) is a worldwide organization for standardization comprising all national Electrotechnical Committees (IEC National Committees). The object of IEC is to promote international co-operation on all questions concerning standardization in the electrical and electronic fields. To this end and in addition to other activities, IEC publishes International Standards, Technical Specifications, Technical Reports, Publicly Available Specifications (PAS) and Guides (hereafter referred to as "IEC Publication(s)"). Their preparation is entrusted to technical committees; any IEC National Committee interested in the subject dealt with may participate in this preparatory work. International, governmental and non-governmental organizations liaising with the IEC also participate in this preparation. IEC collaborates closely with the International Organization for Standardization (ISO) in accordance with conditions determined by agreement between the two organizations.
- 2) The formal decisions or agreements of IEC on technical matters express, as nearly as possible, an international consensus of opinion on the relevant subjects since each technical committee has representation from all interested IEC National Committees.
- 3) IEC Publications have the form of recommendations for international use and are accepted by IEC National Committees in that sense. While all reasonable efforts are made to ensure that the technical content of IEC Publications is accurate, IEC cannot be held responsible for the way in which they are used or for any misinterpretation by any end user.
- 4) In order to promote international uniformity, IEC National Committees undertake to apply IEC Publications transparently to the maximum extent possible in their national and regional publications. Any divergence between any IEC Publication and the corresponding national or regional publication shall be clearly indicated in the latter.
- 5) IEC itself does not provide any attestation of conformity. Independent certification bodies provide conformity assessment services and, in some areas, access to IEC marks of conformity. IEC is not responsible for any services carried out by independent certification bodies.
- 6) All users should ensure that they have the latest edition of this publication.
- 7) No liability shall attach to IEC or its directors, employees, servants or agents including individual experts and members of its technical committees and IEC National Committees for any personal injury, property damage or other damage of any nature whatsoever, whether direct or indirect, or for costs (including legal fees) and expenses arising out of the publication, use of, or reliance upon, this IEC Publication or any other IEC Publications.
- 8) Attention is drawn to the normative references cited in this publication. Use of the referenced publications is indispensable for the correct application of this publication.
- 9) Attention is drawn to the possibility that some of the elements of this IEC Publication may be the subject of patent rights. IEC shall not be held responsible for identifying any or all such patent rights.

This consolidated version of the official IEC Standard and its amendment has been prepared for user convenience.

IEC 61850-5 edition 2.1 contains the second edition (2013-01) [documents 57/1286/FDIS and 57/1309/RVD] and its amendment 1 (2022-03) [documents 57/2448/FDIS and 57/2467/RVD].

International Standard IEC 61850-5 has been prepared by IEC technical committee 57: Power systems management and associated information exchange.

The changes, corrections and updates have been made mainly according to the comments received.

The major changes of this consolidated version with regard to the edition 2 are as follows:

- a) extensions of the requirements with some Logical Nodes
- b) errors and typos have been corrected
- c) harmonization of all Logical Node descriptions (impact on all Logical Node tables)
- d) re-organization of selected clause structures
- e) updating of headlines
- f) re-ordering subclauses in the chapter about performances

to provide

- ease of reading and understanding of the requirements for the IEC 61850 series
- consistent and updated requirement references for the data model and communication service parts

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all the parts in the IEC 61850 series, published under the general title *Communication* networks and systems for power utility automation, can be found on the IEC website.

Future standards in this series will carry the new general title as cited above. Titles of existing standards in this series will be updated at the time of the next edition.

The committee has decided that the contents of the base publication and its amendment will remain unchanged until the stability date indicated on the IEC web site under webstore.iec.ch in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- · replaced by a revised edition, or
- amended.

IMPORTANT – The 'colour inside' logo on the cover page of this publication indicates that it contains colours which are considered to be useful for the correct understanding of its contents. Users should therefore print this document using a colour printer.

INTRODUCTION

This part of IEC 61850 is part of a set of standards, the IEC 61850 series. The IEC 61850 series is intended to provide interoperability between all devices in power utility automation systems. Therefore, it defines communication networks and systems for power utility automation, and more specially the communication architecture for subsystems like substation automation systems. The sum of all subsystems may result also in the description of the communication architecture for the overall power system management.

Communication between these devices in subsystems and between the subsystems within the overall power utility automation system fulfils a lot of requirements imposed by all the functions to be performed in power utility automation systems starting from the core requirements in substations. These requirements are stated both for the data to be organized in a data model and for the data exchange resulting in services. Performance of the data exchange means not only transfer times but also the quality of the data exchange avoiding losses of information in the communication.

Depending on the philosophy both of the manufacturer and the user and on the state-of-the-art in technology, the allocation of functions to devices and control levels is not commonly fixed. Therefore, the standard shall support any allocation of functions. This results in different requirements for the different communication interfaces within the substation or plant, at its border and beyond.

The IEC 61850 series shall be long living but allow following the fast changes in communication technology by both its technical approach and its document structure. The IEC 61850 series has been organized so that at least minor changes to one part do not require a significant rewriting of another part. For example, the derived data models in subsequent parts (IEC 61850-7-x) and mappings to dedicated stacks (IEC 61850-8-x and IEC 61850-9-x) based on the communication requirements in IEC 61850-5 will not change the requirements defined in IEC 61850-5. In addition, the general parts, the requirement specification and the modelling parts are independent from any implementation. The implementation needed for the use of the standard is defined in some few dedicated parts referring to main stream communication means thus supporting the long living of the standard and its potential for later technical changes.

This consolidated version of IEC 61850-5:2013 and its Amendment 1 defines the communication requirements for functions and device models for power utility automation systems.

The modelling of communication requires the definition of objects (e.g., data objects, data sets, report control, log control) and services accessing the objects (e.g., get, set, report, create, delete). This is defined in IEC 61850-7 with a clear interface to implementation. To use the benefits of communication technology, in this standard no new protocol stacks are defined but a standardized mapping on existing stacks is given in IEC 61850-8 and IEC 61850-9. A System configuration language (IEC 61850-6) for strong formal description of the system usable for software tools and a standardized conformance testing (IEC 61850-10) complement the standard.

NOTE 1 To keep the layered approach of the standard not mixing application and implementation requirements, terms like client, server, data objects, etc. are normally not used in IEC 61850-5 (requirements). In IEC 61850-7 (modelling), -8 and -9 (specific communication service mapping) terms belonging to application requirements like PICOM are normally not used.

NOTE 2 Specific requirements concerning extensions of part 8 are covered in separate technical reports, e.g. IEC TR 61850-80-3.

COMMUNICATION NETWORKS AND SYSTEMS FOR POWER UTILITY AUTOMATION –

Part 5: Communication requirements for functions and device models

1 Scope

The specifications of this document refer to general, respectively core, communication requirements of the application functions in all domains of power utility automation systems. Dedicated communication requirements and most examples of application functions in this document are from the domain substation automation but may be reused in or extended to other domains within power utility automation systems. Note that sometimes instead of the term substation automation domain the term substation domain is used, especially if both the switchyard devices (primary system) and the automation system (secondary system) are regarded.

The description of the application functions is not used to standardize these functions, but to identify communication requirements between Intelligent Electronic Devices (IEDs) hosting these functions within plants and substations in the power system, between such stations (e.g. between substation for line protection) and between the plant or substation and higher-level remote operating places (e.g. network control centres) and maintenance places. In addition interfaces to remote technical services (e.g. maintenance centres) are considered. The general scope is the communication requirements for power utility automation systems. The basic goal is interoperability for all interactions providing a seamless communication system for the overall power system management. Another prerequisite for interoperability is a commonly defined method for time synchronization.

Standardizing application functions and their implementation is completely outside the scope of this document. Therefore, it cannot be assumed a single philosophy of allocating application functions to devices. To support the resulting request for free allocation of these functions, a proper breakdown of these functions into parts relevant for communication is defined. The exchanged data and their required performance are defined.

The same or similar IEDs from substations like protective and control devices are found in other domains like power plants also. Using this document for such devices in these plants facilitates the system integration e.g. between the power plant control and the related substation automation system. For some of such other application domains like wind power plants, hydro power plants and distributed energy resources specific standard parts according to the IEC 61850 series have been already defined and published.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60617, Graphical symbols for diagrams – 12-month subscription to regularly updated online database comprising parts 2 to 13 of IEC 60617

IEC 60834-1:1999, Teleprotection equipment of power systems – Performance and testing – Part 1: Command systems

IEC 60834-2:1993, Performance and testing of teleprotection equipment of power systems – Part 2: Analogue comparison systems

IEC 60870-4:1990, Telecontrol equipment and systems. Part 4: Performance requirements

IEC 60870-5 (all parts), Telecontrol equipment and systems – Part 5: Transmission protocols

IEC 61000-4-15:2010, Electromagnetic compatibility (EMC) – Part 4-15: Testing and measurement techniques – Flickermeter – Functional and design specifications

IEC 61000-4-30:2015, Electromagnetic compatibility (EMC) – Part 4-30: Testing and measurement techniques – Power quality measurement methods

IEC 61508 (all parts), Functional safety of electrical/electronic/programmable electronic safety-related systems

IEC TR 61850-1:2013, Communication networks and systems for power utility automation – Part 1: Introduction and overview

IEC TS 61850-2:2019, Communication networks and systems for power utility automation – Part 2: Glossary

IEC 61850-3:2013, Communication networks and systems for power utility automation – Part 3: General requirements

IEC 61850-4:2011, Communication networks and systems for power utility automation – Part 4: System and project management

IEC 61850-6:2009, Communication networks and systems for power utility automation – Part 6: Configuration description language for communication in electrical substations related to IEDs IEC 61850-6:2009/AMD1:2018

IEC 61850-7-1:2011, Communication networks and systems for power utility automation – Part 7-1: Basic communication structure – Principles and models IEC 61850-7-1:2011/AMD1:2020

IEC 61850-7-2:2010, Communication networks and systems for power utility automation – Part 7-2: Basic information and communication structure – Abstract communication service interface (ACSI)

IEC 61850-7-2:2010/AMD1:2020

IEC 61850-7-3:2010, Communication networks and systems for power utility automation – Part 7-3: Basic communication structure – Common data classes IEC 61850-7-3:2010/AMD1:2020

IEC 61850-7-4:2010, Communication networks and systems for power utility automation – Part 7-4: Basic communication structure – Compatible logical node classes and data object classes

IEC 61850-7-4:2010/AMD1:2020

IEC TR 61850-7-5, Communication networks and systems for power utility automation – Part 7-5: IEC 61850 modelling concepts

IEC TR 61850-7-500:2017, Communication networks and systems for power utility automation – Part 7-500: Basic information and communication structure – Use of logical nodes for modeling application functions and related concepts and guidelines for substations

– 14 –

IEC TR 61850-7-510:2012, Communication networks and systems for power utility automation – Part 7-510: Basic communication structure – Hydroelectric power plants – Modelling concepts and guidelines

IEC TR 61850-7-6:2019, Communication networks and systems for power utility automation – Part 7-6: Guideline for definition of Basic Application Profiles (BAPs) using IEC 61850

IEC TS 61850-7-7:2018, Communication networks and systems for power utility automation – Part 7-7: Machine-processable format of IEC 61850-related data models for tools

IEC 61850-8-1:2011, Communication networks and systems for power utility automation – Part 8-1: Specific communication service mapping (SCSM) – Mappings to MMS (ISO 9506-1 and ISO 9506-2) and to ISO/IEC 8802-3 IEC 61850-8-1:2011/AMD1:2020

IEC 61850-8-2:2018, Communication networks and systems for power utility automation – Part 8-2: Specific communication service mapping (SCSM) – Mapping to Extensible Messaging Presence Protocol (XMPP)

IEC 61850-9-2:2011, Communication networks and systems for power utility automation – Part 9-2: Specific communication service mapping (SCSM) – Sampled values over ISO/IEC 8802-3

IEC 61850-9-2:2011/AMD1:2020

IEC/IEEE 61850-9-3:2016, Communication networks and systems for power utility automation – Part 9-3: Precision time protocol profile for power utility automation

IEC 61850-10:2012, Communication networks and systems for power utility automation – Part 10: Conformance testing

IEC TR 61850-80-3:2015, Communication networks and systems for power utility automation – Part 80-3: Mapping to web protocols – Requirements and technical choices

IEC TR 61850-90-1:2010, Communication networks and systems for power utility automation – Part 90-1: Use of IEC 61850 for the communication between substations

IEC TR 61850-90-2:2016, Communication networks and systems for power utility automation – Part 90-2: Using IEC 61850 for communication between substations and control centres

IEC TR 61850-90-4:2020, Communication networks and systems for power utility automation – Part 90-4: Network engineering guidelines

IEC TR 61850-90-5:2012, Communication networks and systems for power utility automation – Part 90-5: Use of IEC 61850 to transmit synchrophasor information according to IEEE C37.118

IEC TR 61850-90-12:2020, Communication networks and systems for power utility automation – Part 90-12: Wide area network engineering guidelines

IEC 61869 (all parts), Instrument transformers

IEC TR 62357-1:2016, Power systems management and associated information exchange – Part 1: Reference architecture

IEC 81346 (all parts), Industrial systems, installations and equipment and industrial products – Structuring principles and reference designations

IEC 61850-5:2013+AMD1:2022 CSV - 15 - © IEC 2022

IEEE Std C37.2-2008, Electrical Power System Device Function Numbers, Acronyms and Contact Designations

3 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC TS 61850-2, as well as the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at http://www.electropedia.org/
- ISO Online browsing platform: available at http://www.iso.org/obp

3.1 General

3.1.1

application function

task which is performed in or by power utility automation systems

Note 1 to entry: Generally, an application function consists of subparts which may be distributed to different IEDs, which exchange data with each other. More precisely these sub-functions implemented in the IEDs exchange data. Also, between different functions data are exchanged. The exchanged data exposed to the communication system shall be standardized based on the semantic content to be understandable by the receiving function. For this purpose, the standard groups the exchanged data in objects called Logical Nodes which refer to the name of the allocated functions by their mnemonic name.

3.1.2

local function

application function which is performed by sub-functions in one physical device

Note 1 to entry: If the performance of the functions is not depending on functions in other devices no standardized link is needed. Sometimes, functions with a weak dependency only from other ones are also called local functions. The loss of such links should not result in blocking these functions but in worst case to some graceful degradation.

3.1.3

distributed function

application function which is performed by sub-functions in two or more different physical devices

Note 1 to entry: The exchanged data is contained in Logical Nodes having a common semantic reference to the distributed function. Since all functions communicate in some way, the definition of a local or a distributed function is not unique but depends on the definition of the functional steps to be performed until the function is defined as complete. In case of losing the data of one Logical Node or losing one included communication link the function may be blocked completely or show a graceful degradation if applicable.

3.1.4

system

set of interacting entities which perform a common functionality

Note 1 to entry: The backbone of the system is the data exchange.

3.1.5

logical system

communicating set of all application functions performing some overall task like "management of a substation" or "management of a plant"

Note 1 to entry: The boundary of a logical system is given by its logical interfaces. The backbone of the logical system is the communication relationship between its functions and sub-functions. The exchanged data are grouped in Logical Nodes.