INTERNATIONAL STANDARD



First edition 2023-01

R V **Road vehicles — Heavy commercial** vehicles and buses — Calculation method for steady-state rollover threshold

Véhicules routiers — Véhicules utilitaires lourds et bus — Méthode de



Reference number ISO 22135:2023(E)



© ISO 2023

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office CP 401 • Ch. de Blandonnet 8 CH-1214 Vernier, Geneva Phone: +41 22 749 01 11 Email: copyright@iso.org Website: www.iso.org

Published in Switzerland

Page

Contents

Fore	eword		iv
Intr	oduction		v
1	Scope	·	1
2	Norma	ative references	
3	Terms	s and definitions	
4	Prope 4.1 4.2	rties Vehicle properties used for calculation Required parameter accuracy	
5	Princi	iple	5
6	Calcul 6.1 6.2 6.3 6.4 6.5	lation method General Calculation of vehicle effective track Calculation of vehicle roll stiffness Calculation of vehicle effective tyre lateral stiffness Calculation of steady-state rollover threshold	6 6 7 7 7 7
Ann	ex A (info	ormative) Sample results	9
			Ś

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 33, *Vehicle dynamics and chassis components*.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at <u>www.iso.org/members.html</u>.

Introduction

The dynamic behaviour of a road vehicle is a most important aspect of active vehicle safety. Any given vehicle, together with its driver and the prevailing environment constitutes a closed-loop system which is unique. The task of evaluating the dynamic behaviour is therefore very difficult, since the significant interaction of these driver-vehicle road elements are each complex in themselves. A complete and accurate description of the behaviour of the road vehicle inevitably involves information obtained from a number of different tests.

Moreover, insufficient knowledge is available to correlate overall vehicle dynamic properties with aub seen a. accident prevention. A substantial amount of work is necessary to acquire sufficient and reliable data on the correlation between accident prevention and vehicle dynamic properties in general.

this document is a preview demendence of the document is a preview demendence of the document of the document

Road vehicles — Heavy commercial vehicles and buses — Calculation method for steady-state rollover threshold

1 Scope

This document describes a method for calculating steady-state rollover threshold of heavy commercial vehicles and buses, not considering the effects of active control systems. The calculation method considers the main factors that influence the rollover threshold, namely the height of centre of gravity, the track, the tyre lateral stiffness, and all factors that affect the vehicle roll stiffness. The considered compliances (e.g. tyre deformation) have a considerable influence on the effective track, and consequently on the steady-state rollover threshold.

NOTE As an alternative to the described calculation method standard, the steady-state rollover threshold can be measured on a test track or with a tilt-table test as described in ISO 16333.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 8855, Road vehicles — Vehicle dynamics and road-holding ability — Vocabulary

3 Terms and definitions

For the purposes of this document, the terms and definitions given in in ISO 8855 and the following shall apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <u>https://www.iso.org/obp</u>
- IEC Electropedia: available at <u>https://www.electropedia.org/</u>

3.1

steady-state rollover threshold

 $a_{\rm srt}$ maximum lateral acceleration that the vehicle can sustain in a steady state turn without rolling over

3.2

first lift-off lateral acceleration

 $a_{\rm yf}$

lateral acceleration, at which the first wheel lift-off occurs

3.3

total lift-off lateral acceleration

 $a_{\rm vt}$

lateral acceleration, at which theoretically all axles lift from the ground

5