Geometrical product specifications (GPS) - Filtration - Part 31: Robust profile filters: Gaussian regression filters (ISO 16610-31:2016)

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NATIONAL FOREWORD

See Eesti standard EVS-EN ISO 16610-31:2016 sisaldab Euroopa standardi EN ISO 16610-31:2016 ingliskeelset teksti.	This Estonian standard EVS-EN ISO 16610-31:2016 consists of the English text of the European standard EN ISO 16610-31:2016.
Standard on jõustunud sellekohase teate avaldamisega EVS Teatajas.	This standard has been endorsed with a notification published in the official bulletin of the Estonian Centre for Standardisation.
Euroopa standardimisorganisatsioonid on teinud Euroopa standardi rahvuslikele liikmetele kättesaadavaks 30.11.2016.	Date of Availability of the European standard is 30.11.2016.
Standard on kättesaadav Eesti Standardikeskusest.	The standard is available from the Estonian Centre for Standardisation.

Tagasisidet standardi sisu kohta on võimalik edastada, kasutades EVS-i veebilehel asuvat tagasiside vormi või saates e-kirja meiliaadressile standardiosakond@evs.ee.

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Geometrische Produktspezifikation (GPS) - Filterung - Teil 31: Robuste Profilfilter: Gaußsche Regressionsfilter (ISO 16610-31:2016)

This European Standard was approved by CEN on 22 October 2016.

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COMITÉ EUROPÉEN DE NORMALISATION
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European foreword

This document (EN ISO 16610-31:2016) has been prepared by Technical Committee ISO/TC 213 “Dimensional and geometrical product specifications and verification” in collaboration with Technical Committee CEN/TC 290 “Dimensional and geometrical product specification and verification” the secretariat of which is held by AFNOR.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by May 2017, and conflicting national standards shall be withdrawn at the latest by May 2017.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

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Endorsement notice

The text of ISO 16610-31:2016 has been approved by CEN as EN ISO 16610-31:2016 without any modification.

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

The committee responsible for this document is ISO/TC 213, *Dimensional and geometrical product specifications and verification*.

This first edition of ISO 16610-31 cancels and replaces ISO/TS 16610-31, which has been technically revised.

A list of all parts in the ISO 16610 series can be found on the ISO website.

Introduction

This document is a geometrical product specification (GPS) standard and is to be regarded as a general GPS standard (see ISO 14638). It influences the chain link C of all chains of standards.

For more detailed information of the relation of this document to the GPS matrix model, see Annex C.

The ISO/GPS matrix model given in ISO 14638 gives an overview of the ISO/GPS system of which this document is a part. The fundamental rules of ISO/GPS given in ISO 8015 apply to this document and the default decision rules given in ISO 14253-1 apply to specifications made in accordance with this document, unless otherwise indicated.

This document develops the concept of the discrete robust Gaussian regression filter. The robust process reduces the influence of the deep valleys and high peaks. The subject of this document is the robust Gaussian regression filter of degree $p = 2$, which has very good robust behaviour and form approximation for functional stratified engineering surfaces.

Geometrical product specifications (GPS) — Filtration —

Part 31:
Robust profile filters: Gaussian regression filters

1 Scope

This document specifies the characteristics of the discrete robust Gaussian regression filter for the evaluation of surface profiles with spike discontinuities such as deep valleys and high peaks.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 16610-1:2015, *Geometrical product specifications (GPS) — Filtration — Part 1: Overview and basic concepts*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO/IEC Guide 99, ISO 16610-1, ISO 16610-20, ISO 16610-30 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— IEC Electropedia: available at http://www.electropedia.org/

— ISO Online browsing platform: available at http://www.iso.org/obp

3.1
robust filter
filter that is insensitive to output data against specific phenomena in the input data

3.2
regression filter
M-estimator based on the local polynomial modelling of the profile

3.3
robust Gaussian regression filter
regression filter (3.2) based on the Gaussian weighting function and a *biweight influence function* (3.4)

3.4
biweight influence function
asymmetric function which is scale-invariant, expressed by

$$\psi\left(x\right)=\begin{cases} x\times\left(1-\left(\dfrac{x}{c}\right)^{2}\right)^{2} & \text{for} \quad \left|x\right|\le c \\ 0 & \text{for} \quad \left|x\right|>c \end{cases}$$

where c is the scale parameter.