## INTERNATIONAL STANDARD

### ISO 21940-12

First edition 2016-04-01

# **Mechanical vibration** — **Rotor balancing** —

Part 12:

## Procedures and tolerances for rotors with flexible behaviour

Vibrations mécaniques — Équilibrage des rotors — Partie 12: Modes opératoires et tolérances pour les rotors à comportement flexible





© ISO 2016, Published in Switzerland

roduced or utilized c te internet or an 'nr ISO's memb All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office Ch. de Blandonnet 8 • CP 401 CH-1214 Vernier, Geneva, Switzerland Tel. +41 22 749 01 11 Fax +41 22 749 09 47 copyright@iso.org www.iso.org

4.1       General       2         4.2       Unbalance distribution       2         4.3       Mode shapes of rotors with flexible behaviour       2         4.4       Response of a rotor with flexible behaviour to unbalance       3         4.5       Aims of balancing rotors with flexible behaviour       4         4.6       Provision for correction planes       5         4.7       Coupled rotors       5         5       Rotor configurations       5         6       Procedures for balancing rotors with flexible behaviour at low speed       7         6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure A — Single-plane balancing       8         6.5.1       Procedure B — Two-plane balancing prior to assembly       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9	Co	ntent	is a second of the second of t	Page
1         Scope         1           2         Normative references         1           3         Terms and definitions         1           4         Fundamentals of dynamics and balancing of rotors with flexible behaviour         2           4.1         General         2           4.2         Unbalance distribution         2           4.3         Mode shapes of rotors with flexible behaviour to unbalance         3           4.5         Alms of balancing rotors with flexible behaviour         4           4.6         Provision for correction planes         5           4.7         Coupled rotors         5           5         Rotor configurations         5           6         Procedures for balancing rotors with flexible behaviour at low speed         7           6.1         General         7           6.2         Selection of correction planes         8           6.3         Service speed of the rotor         8           6.4         Initial unbalance         8           6.5         Low-speed balancing procedures         8           6.5.1         Procedure Balancing is a procedure and balancing procedures         8           6.5.2         Procedure Balancing is a procedure balancing procedure and balancing	For	eword		<b>v</b>
1	Intr	oductio	on	vii
1	1	Scon	ie	1
Terms and definitions				
Fundamentals of dynamics and balancing of rotors with flexible behaviour				
4.1       General       2         4.2       Unbalance distribution       2         4.3       Mode shapes of rotors with flexible behaviour to unbalance       3         4.5       Aims of balancing rotors with flexible behaviour       4         4.6       Provision for correction planes       5         4.7       Coupled rotors       5         5       Rotor configurations       5         6       Procedures for balancing rotors with flexible behaviour at low speed       7         6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure B — Two-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure B — Two-plane balancing prior to assembly       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in stages during assembly       9 <t< td=""><td>3</td><td></td><td></td><td></td></t<>	3			
4.2       Unbalance distribution       2         4.3       Mode shapes of rotors with flexible behaviour to unbalance       3         4.5       Aims of balancing rotors with flexible behaviour       4         4.6       Provision for correction planes       5         4.7       Coupled rotors       5         5       Rotor configurations       5         6       Procedures for balancing rotors with flexible behaviour at low speed       7         6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single plane balancing       8         6.5.1       Procedure B — Two-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       9         6.5.3       Procedure E — Balancing subsequent to controlling initial unbalance       9         6.5.4       Procedure E — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       11         7.	4		damentals of dynamics and balancing of rotors with flexible behaviour	2
4.3       Mode shapes of rotors with flexible behaviour to unbalance       3         4.4       Response of a rotor with flexible behaviour to unbalance       3         4.5       Aims of balancing rotors with flexible behaviour       4         4.6       Provision for correction planes       5         4.7       Coupled rotors       5         5       Rotor configurations       5         6       Procedures for balancing rotors with flexible behaviour at low speed       7         6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure E — Balancing in subsequent to controlling initial unbalance       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure F — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in its stages during assembly       9         7.1       <				
4.4       Response of a rotor with flexible behaviour to unbalance.       3         4.5       Aims of balancing rotors with flexible behaviour.       4         4.6       Provision for correction planes.       5         5       Rotor configurations.       5         6       Procedures for balancing rotors with flexible behaviour at low speed.       7         6.1       General.       7         6.2       Selection of correction planes.       8         6.3       Service speed of the rotor.       8         6.4       Initial unbalance.       8         6.5       Low-speed balancing procedures.       8         6.5.1       Procedure A — Single-plane balancing.       8         6.5.2       Procedure B — Two-plane balancing.       8         6.5.3       Procedure C — Individual component balancing prior to assembly.       9         6.5.5       Procedure E — Balancing is ubsequent to controlling initial unbalance.       9         6.5.5       Procedure E — Balancing in stages during assembly.       9         6.5.6       Procedure F — Balancing in optimum planes.       10         7       Procedures for balancing rotors with flexible behaviour at high speed.       10         7.1       General.       11         7.3.1				
4.5         Aims of balancing rotors with flexible behaviour         4           4.6         Provision for correction planes         5           4.7         Coupled rotors         5           5         Rotor configurations         5           6         Procedures for balancing rotors with flexible behaviour at low speed         7           6.1         General         7           6.2         Selection of correction planes         8           6.3         Service speed of the rotor         8           6.4         Initial unbalance         8           6.5         Low-speed balancing procedures         8           6.5.1         Procedure A — Single-plane balancing         8           6.5.2         Procedure B — Two-plane balancing         8           6.5.3         Procedure B — Two-plane balancing prior to assembly         9           6.5.4         Procedure D — Balancing in stages during assembly         9           6.5.5         Procedure E — Balancing in optimum planes         10           7         Procedures for balancing rotors with flexible behaviour at high speed         10           7.1         General         10           7.3         Procedure G — Multiple speed balancing         11           7.3.1			Response of a rotor with flexible behaviour to unbalance	3
4.6       Provision for correction planes       5         4.7       Coupled rotors       5         5       Rotor configurations       5         6       Procedures for balancing rotors with flexible behaviour at low speed       7         6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure B — Two-plane balancing       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure I — Multiple speed balancing       11         7.3.1			Aims of balancing rotors with flexible behaviour	4
5         Rotor configurations         5           6         Procedures for balancing rotors with flexible behaviour at low speed         7           6.1         General         7           6.2         Selection of correction planes         8           6.3         Service speed of the rotor         8           6.4         Initial unbalance         8           6.5         Low-speed balancing procedures         8           6.5.1         Procedure B — Two-plane balancing         8           6.5.2         Procedure B — Two-plane balancing grior to assembly         9           6.5.4         Procedure D — Balancing subsequent to controlling initial unbalance         9           6.5.5         Procedure E — Balancing in stages during assembly         9           6.5.6         Procedure F — Balancing in optimum planes         10           7         Procedures for balancing rotors with flexible behaviour at high speed         10           7.1         General         10           7.2         Installation for balancing         10           7.3         Procedure G — Multiple speed balancing         11           7.3.1         General         11           7.3.2         Initial low-speed balancing         11           7.5.1 <td></td> <td>4.6</td> <td>Provision for correction planes</td> <td>5</td>		4.6	Provision for correction planes	5
6         Procedures for balancing rotors with flexible behaviour at low speed         7           6.1         General         7           6.2         Selection of correction planes         8           6.3         Service speed of the rotor         8           6.4         Initial unbalance         8           6.5         Low-speed balancing procedures         8           6.5.1         Procedure A — Single-plane balancing         8           6.5.2         Procedure B — Two-plane balancing         8           6.5.3         Procedure C — Individual component balancing prior to assembly         9           6.5.4         Procedure D — Balancing subsequent to controlling initial unbalance         9           6.5.5         Procedure E — Balancing in optimum planes         10           7         Procedures for balancing rotors with flexible behaviour at high speed         10           7.1         General         10           7.2         Installation for balancing         10           7.3         Procedure G — Multiple speed balancing         11           7.3.1         General         11           7.3.2         Initial low-speed balancing         11           7.4         Procedure H — Service speed balancing         13		4.7	Coupled rotors	5
6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.4       Procedure E — Balancing in stages during assembly       9         6.5.5       Procedure E — Balancing in optimum planes       10         7.1       General       10         7.2       Installation for balancing notors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14 <td< td=""><td>5</td><td>Roto</td><td>or configurations</td><td>5</td></td<>	5	Roto	or configurations	5
6.1       General       7         6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.4       Procedure E — Balancing in stages during assembly       9         6.5.5       Procedure E — Balancing in optimum planes       10         7.1       General       10         7.2       Installation for balancing notors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14 <td< td=""><td>6</td><td>Proc</td><td>edures for halancing rotors with flexible behaviour at low speed</td><td>7</td></td<>	6	Proc	edures for halancing rotors with flexible behaviour at low speed	7
6.2       Selection of correction planes       8         6.3       Service speed of the rotor       8         6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing prior to assembly       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8.2       Vibration limits in the balancing machine<	3		General General	7
6.4       Initial unbalance       8         6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing prior to assembly       9         6.5.3       Procedure C — Individual component balancing prior to assembly       9         6.5.4       Procedure E — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General       11         7.4       Procedure H — Service speed balancing       13         7.5.1       General       14         7.5.2       Procedure I — Fixed speed balancing       14         7.5.2       Procedure I — Fixed speed balancing       14         8.2       Vibration limits in the balancing machine       15		6.2	Selection of correction planes	8
6.5       Low-speed balancing procedures       8         6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure E — Two-plane balancing       9         6.5.3       Procedure C — Individual component balancing prior to assembly       9         6.5.4       Procedure E — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in optimum planes       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       13         7.5.1       General       14         7.5.2       Procedure       14         7.5.2       Procedure       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine <t< td=""><td></td><td></td><td></td><td></td></t<>				
6.5.1       Procedure A — Single-plane balancing       8         6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure C — Individual component balancing prior to assembly       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in optimum planes       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure I — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.4       Factors influencing machine vibration <t< td=""><td></td><td></td><td></td><td></td></t<>				
6.5.2       Procedure B — Two-plane balancing       8         6.5.3       Procedure C — Individual component balancing prior to assembly       9         6.5.4       Procedure D — Balancing subsequent to controlling initial unbalance       9         6.5.5       Procedure E — Balancing in stages during assembly       9         6.5.6       Procedure F — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.4       Factors influencing m		6.5		
6.5.3 Procedure C — Individual component balancing prior to assembly 6.5.4 Procedure D — Balancing subsequent to controlling initial unbalance 9 6.5.5 Procedure E — Balancing in stages during assembly 9 6.5.6 Procedure F — Balancing in optimum planes 10 7. Procedures for balancing rotors with flexible behaviour at high speed 10 7.1 General 10 7.2 Installation for balancing 10 7.3 Procedure G — Multiple speed balancing 11 7.3.1 General 11 7.3.2 Initial low-speed balancing 11 7.3.2 Initial low-speed balancing 11 7.3.3 General procedure 11 7.4 Procedure H — Service speed balancing 11 7.5.1 General 14 7.5.1 General 14 7.5.2 Procedure I — Fixed speed balancing 14 7.5.1 General 14 7.5.2 Procedure I — Fixed speed balancing 14 7.5.1 General 14 7.5.2 Procedure I — Service Speed balancing 14 7.5.1 General 14 7.5.2 Procedure I — Service Speed balancing 14 7.5.3 Frocedure I — Fixed speed balancing 14 7.5.4 Factors influencing machine 15 8.2 Vibration limits in the balancing machine 15 8.2.1 Overview 15 8.2.2 General 15 8.2.3 Special cases and exceptions 15 8.2.4 Factors influencing machine vibration 15 8.2.5 Critical clearances and complex machine systems 16 8.2 Residual unbalance tolerances 17 8.3.1 Overview 17 8.3.2 General 17 8.3.3 Limits for low-speed balancing 17				
6.5.4 Procedure D — Balancing subsequent to controlling initial unbalance 9 6.5.5 Procedure E — Balancing in stages during assembly 9 6.5.6 Procedure F — Balancing in optimum planes 10  7 Procedures for balancing rotors with flexible behaviour at high speed 10 7.1 General 10 7.2 Installation for balancing 11 7.3 Procedure G — Multiple speed balancing 11 7.3.1 General 11 7.3.2 Initial low-speed balancing 11 7.3.3 General 11 7.3.3 General 11 7.3.3 General procedure 11 7.4 Procedure H — Service speed balancing 11 7.5 Procedure I — Fixed speed balancing 14 7.5 General 14 7.5 General 14 7.5 Procedure I — Fixed speed balancing 15 8.2 Vibration limits in the balancing machine 15 8.2 Vibration limits in the balancing machine 15 8.2 General 15 8.2 Special cases and exceptions 15 8.2 General 15 8.2 Critical clearances and complex machine systems 16 8.2 Permissible vibrations in the balancing machine 16 8.3 Residual unbalance tolerances 17 8.3 Critical clearances and complex machine systems 16 8.3 Residual unbalance tolerances 17 8.3 Ceneral 17 8.3 Limits for low-speed balancing 17				
6.5.5       Procedure F — Balancing in optimum planes       10         7       Procedures for balancing rotors with flexible behaviour at high speed       10         7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8.5       Vibration limits in the balancing       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.3       <			6.5.4 Procedure D — Balancing subsequent to controlling initial unbalance	9
10			6.5.5 Procedure E — Balancing in stages during assembly	9
7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8       Evaluation criteria       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17			6.5.6 Procedure F — Balancing in optimum planes	10
7.1       General       10         7.2       Installation for balancing       10         7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8       Evaluation criteria       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17	7	Proc	edures for balancing rotors with flexible behaviour at high speed	10
7.3       Procedure G — Multiple speed balancing       11         7.3.1       General       11         7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8       Evaluation criteria       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17		7.1	General	10
7.3.1 General       11         7.3.2 Initial low-speed balancing       11         7.3.3 General procedure       11         7.4 Procedure H — Service speed balancing       13         7.5 Procedure I — Fixed speed balancing       14         7.5.1 General       14         7.5.2 Procedure       14         8 Evaluation criteria       14         8.1 Choice of criteria       14         8.2 Vibration limits in the balancing machine       15         8.2.1 Overview       15         8.2.2 General       15         8.2.3 Special cases and exceptions       15         8.2.4 Factors influencing machine vibration       15         8.2.5 Critical clearances and complex machine systems       16         8.2 Residual unbalance tolerances       16         8.3 Residual unbalance tolerances       17         8.3.1 Overview       17         8.3.2 General       17         8.3.3 Limits for low-speed balancing       17			Installation for balancing	10
7.3.2       Initial low-speed balancing       11         7.3.3       General procedure       11         7.4       Procedure H — Service speed balancing       13         7.5       Procedure I — Fixed speed balancing       14         7.5.1       General       14         7.5.2       Procedure       14         8       Evaluation criteria       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17		7.3	Procedure G — Multiple speed balancing	11
7.3.3 General procedure       11         7.4 Procedure H — Service speed balancing       13         7.5 Procedure I — Fixed speed balancing       14         7.5.1 General       14         7.5.2 Procedure       14         8 Evaluation criteria       14         8.1 Choice of criteria       14         8.2 Vibration limits in the balancing machine       15         8.2.1 Overview       15         8.2.2 General       15         8.2.3 Special cases and exceptions       15         8.2.4 Factors influencing machine vibration       15         8.2.5 Critical clearances and complex machine systems       16         8.2.6 Permissible vibrations in the balancing machine       16         8.3 Residual unbalance tolerances       17         8.3.1 Overview       17         8.3.2 General       17         8.3.3 Limits for low-speed balancing       17			7.3.1 General	11 11
7.4       Procedure H — Service speed balancing			7.3.2 General procedure	11
7.5       Procedure I — Fixed speed balancing.       14         7.5.1       General.       14         7.5.2       Procedure.       14         8       Evaluation criteria.       14         8.1       Choice of criteria.       14         8.2       Vibration limits in the balancing machine.       15         8.2.1       Overview.       15         8.2.2       General.       15         8.2.3       Special cases and exceptions.       15         8.2.4       Factors influencing machine vibration.       15         8.2.5       Critical clearances and complex machine systems.       16         8.2.6       Permissible vibrations in the balancing machine.       16         8.3       Residual unbalance tolerances.       17         8.3.1       Overview.       17         8.3.2       General.       17         8.3.3       Limits for low-speed balancing.       17		7.4	Procedure H — Service speed balancing	13
7.5.1 General       14         7.5.2 Procedure       14         8 Evaluation criteria       14         8.1 Choice of criteria       14         8.2 Vibration limits in the balancing machine       15         8.2.1 Overview       15         8.2.2 General       15         8.2.3 Special cases and exceptions       15         8.2.4 Factors influencing machine vibration       15         8.2.5 Critical clearances and complex machine systems       16         8.2.6 Permissible vibrations in the balancing machine       16         8.3 Residual unbalance tolerances       17         8.3.1 Overview       17         8.3.2 General       17         8.3.3 Limits for low-speed balancing       17				
8       Evaluation criteria       14         8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17			7.5.1 General	14
8.1       Choice of criteria       14         8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17				
8.2       Vibration limits in the balancing machine       15         8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17	8	Eval	uation criteria	14
8.2.1       Overview       15         8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17				
8.2.2       General       15         8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17		8.2		
8.2.3       Special cases and exceptions       15         8.2.4       Factors influencing machine vibration       15         8.2.5       Critical clearances and complex machine systems       16         8.2.6       Permissible vibrations in the balancing machine       16         8.3       Residual unbalance tolerances       17         8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17				
8.2.4 Factors influencing machine vibration				
8.2.5 Critical clearances and complex machine systems 16 8.2.6 Permissible vibrations in the balancing machine 16 8.3 Residual unbalance tolerances 17 8.3.1 Overview 17 8.3.2 General 17 8.3.3 Limits for low-speed balancing 17				15
8.2.6 Permissible vibrations in the balancing machine 16 8.3 Residual unbalance tolerances 17 8.3.1 Overview 17 8.3.2 General 17 8.3.3 Limits for low-speed balancing 17				
8.3.1       Overview       17         8.3.2       General       17         8.3.3       Limits for low-speed balancing       17				
8.3.2 General 17 8.3.3 Limits for low-speed balancing 17		8.3		
8.3.3 Limits for low-speed balancing				
1 0				
Olori Hilligo for migrepho duccu Dulumentilia minimum			1 0	

#### ISO 21940-12:2016(E)

9.1 Evaluation procedures based on vibration limits 18 9.1.1 Vibration assessed in a high-speed balancing machine 18 9.1.2 Vibration assessed on a test facility 19 9.1.3 Vibration assessed on site 19 9.2 Evaluation based on residual unbalance tolerances 20 9.2.1 General 20 9.2.2 Evaluation at low speed 20 9.2.3 Evaluation at multiple speeds based on modal unbalances 20 9.2.4 Evaluation at multiple speeds based on modal unbalances 20 9.2.4 Evaluation at service speed in two specified test planes 21 1 Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23 Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 (informative) Method of computation of unbalance correction 32 (informative) Method of computation of unbalance correction 33 (informative) Method of computation of unbalance correction 33 (informative) Method of computation of unbalance correction 34 (informative) Method of computation of unbalance correction 35 (informative) Method of computation of unbalance correction 36 (informative) Method of computation of unbalance correction 36 (informative) Method of computation of unbalance correction 37 (informative) Method of computation of unbalance correction 36 (informative) Method of computation of unbalance correction 37 (informative) Method of computation of unbalance correction 37 (informative) Method of computation of unbalance correction 38 (informative) Method of computation of unbalance correction 39 (informative) Method of computation of unbalance correction 39 (informative) Method of computation of unbalance correction 30 (informative) Method of computation at correction 30 (in	9	Evaluation procedures	
9.1.2 Vibration assessed on a test facility 19.1.3 Vibration assessed on site 19.2.1 Vibration assessed on site 19.2.2 Evaluation based on residual unbalance tolerances 20.9.2.1 General 20.9.2.2 Evaluation at low speed. 20.9.2.3 Evaluation at multiple speeds based on modal unbalances 20.9.2.4 Evaluation at service speed in two specified test planes 21. Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23. Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24. Annex C (informative) Conversion factors 26. Annex D (informative) Example calculation of equivalent residual modal unbalances 27. Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30. Annex F (informative) Method of computation of unbalance correction 32. Bibliography 33.			
9.1.3 Vibration assessed on site			
9.2 Evaluation based on residual unbalance tolerances 20 9.2.1 General 20 9.2.2 Evaluation at low speed 20 9.2.3 Evaluation at multiple speeds based on modal unbalances 20 9.2.4 Evaluation at service speed in two specified test planes 21 Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23 Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Conversion factors 26 Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33		J Company of the Comp	
9.2.2 Evaluation at low speed 9.2.3 Evaluation at multiple speeds based on modal unbalances 9.2.4 Evaluation at service speed in two specified test planes 21 Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23 Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Conversion factors 26 Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33			
9.2.3 Evaluation at multiple speeds based on modal unbalances 20 9.2.4 Evaluation at service speed in two specified test planes 21 Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23 Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Conversion factors 26 Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33			
9.2.4 Evaluation at service speed in two specified test planes			
Annex A (informative) Cautionary notes concerning rotors when installed in-situ 23 Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Conversion factors 26 Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33			
Annex B (informative) Optimum planes balancing — Low-speed three-plane balancing 24 Annex C (informative) Conversion factors 26 Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33	Annos		
Annex C (informative) Conversion factors			
Annex D (informative) Example calculation of equivalent residual modal unbalances 27 Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33			
Annex E (informative) Procedures to determine whether a rotor shows rigid or flexible behaviour 30 Annex F (informative) Method of computation of unbalance correction 32 Bibliography 33			
Annex F (informative) Method of computation of unbalance correction 32  Bibliography 33		<b>E</b> (informative) <b>Procedures to determine whether a rotor shows rigid or</b>	
Bibliography 33	Annor		
O Dielien Gerage Grand G	Riblio	ography	33
			5

#### Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see <a href="https://www.iso.org/directives">www.iso.org/directives</a>).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see <a href="https://www.iso.org/patents">www.iso.org/patents</a>).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: Foreword - Supplementary information

The committee responsible for this document is ISO/TC 108, Mechanical vibration, shock and condition monitoring, Subcommittee SC 2, Measurement and evaluation of mechanical vibration and shock as applied to machines, vehicles and structures.

This first edition of ISO 21940-12 cancels and replaces ISO 11342:1998, which has been technically revised. The main changes are deletion of the terms and definitions which were transferred to ISO 21940-2 and deletion of former Annex F which is a duplication of a part of <u>D.1</u>. It also incorporates the Technical Corrigendum ISO 11342:1998/Cor.1:2000.

ISO 21940 consists of the following parts, under the general title *Mechanical vibration* — *Rotor balancing*:

- Part 11: Procedures and tolerances for rotors with rigid behaviour<sup>1)</sup>
- Part 12: Procedures and tolerances for rotors with flexible behaviour<sup>2</sup>
- Part 13: Criteria and safeguards for the in-situ balancing of medium and large rotors<sup>3)</sup>
- Part 14: Procedures for assessing balance errors<sup>4)</sup>
- Part 21: Description and evaluation of balancing machines<sup>5)</sup>

<sup>1)</sup> Revision of ISO 1940-1:2003 + Cor.1:2005, Mechanical vibration — Balance quality requirements for rotors in a constant (rigid) state — Part 1: Specification and verification of balance tolerances

<sup>2)</sup> Revision of ISO 11342:1998 + Cor.1:2000, Mechanical vibration — Methods and criteria for the mechanical balancing of flexible rotors

<sup>3)</sup> Revision of ISO 20806:2009, Mechanical vibration — Criteria and safeguards for the in-situ balancing of medium and large rotors

<sup>4)</sup> Revision of ISO 1940-2:1997, Mechanical vibration — Balance quality requirements of rigid rotors — Part 2: Balance errors

<sup>5)</sup> Revision of ISO 2953:1999, Mechanical vibration — Balancing machines — Description and evaluation

#### ISO 21940-12:2016(E)

- Part 23: Enclosures and other protective measures for the measuring station of balancing machines<sup>6)</sup>
- Part 31: Susceptibility and sensitivity of machines to unbalance<sup>7)</sup>
- Part 32: Shaft and fitment key convention<sup>8)</sup>

The following part is under preparation:

Part 2: Vocabulary<sup>9)</sup>

res and other pre Revision of ISO 7475:2002, Mechanical vibration — Balancing machines — Enclosures and other protective measures for the measuring station

Revision of ISO 10814:1996, Mechanical vibration — Susceptibility and sensitivity of machines to unbalance 7)

Revision of ISO 8821:1989, Mechanical vibration — Balancing — Shaft and fitment key convention 8)

Revision of ISO 1925:2001, Mechanical vibration — Balancing — Vocabulary 9)

#### Introduction

The aim of balancing any rotor is to achieve satisfactory running when installed *in-situ*. In this context, "satisfactory running" means that not more than an acceptable magnitude of vibration is caused by the unbalance remaining in the rotor. In the case of a rotor with flexible behaviour, it also means that not more than an acceptable magnitude of deflection occurs in the rotor at any speed up to the maximum service speed.

Most rotors are balanced in manufacture prior to machine assembly because afterwards, for example, there might be only limited access to the rotor. Furthermore, balancing of the rotor is often the stage at which a rotor is approved by the purchaser. Thus, while satisfactory running *in-situ* is the aim, the balance quality of the rotor is usually initially assessed in a balancing machine. Satisfactory running *in-situ* is, in most cases, judged in relation to vibration from all causes, while in the balancing machine, primarily, once-per-revolution effects are considered.

This part of ISO 21940 classifies rotors in accordance with their balancing requirements and establishes methods of assessment of residual unbalance.

This part of ISO 21940 also shows how criteria for use in the balancing machine can be derived from either vibration limits specified for the assembled and installed machine or unbalance limits specified for the rotor. If such limits are not available, this part of ISO 21940 shows how they can be derived from ISO 10816 and ISO 7919 if desired in terms of vibration, or from ISO 21940-11, if desired in terms of permissible residual unbalance. ISO 21940-11 is concerned with the balance quality of rotating rigid bodies and is not directly applicable to rotors with flexible behaviour because rotors with flexible behaviour can undergo significant bending deflection. However, in this part of ISO 21940, methods are presented for adapting the criteria of ISO 21940-11 to rotors with flexible behaviour.

There are situations in which an otherwise acceptably balanced rotor experiences an unacceptable vibration level *in situ*, owing to resonances in the support structure. A resonance or near resonance condition in a lightly damped structure can result in excessive vibratory response to a small unbalance. In such cases, it can be more practicable to alter the natural frequency or damping of the structure rather than to balance to very low levels, which might not be maintainable over time (see also ISO 21940-31).

This document is a previous general ded by tills

### Mechanical vibration — Rotor balancing —

### Part 12:

## Procedures and tolerances for rotors with flexible behaviour

#### 1 Scope

This part of ISO 21940 presents typical configurations of rotors with flexible behaviour in accordance with their characteristics and balancing requirements, describes balancing procedures, specifies methods of assessment of the final state of balance, and establishes guidelines for balance quality criteria.

This part of ISO 21940 can also serve as a basis for more involved investigations, e.g. when a more exact determination of the required balance quality is necessary. If due regard is paid to the specified methods of manufacture and balance tolerances, satisfactory running conditions can be expected.

This part of ISO 21940 is not intended to serve as an acceptance specification for any rotor, but rather to give indications of how to avoid gross deficiencies and unnecessarily restrictive requirements.

Structural resonances and modifications thereof lie outside the scope of this part of ISO 21940.

The methods and criteria given are the result of experience with general industrial machinery. It is possible that they are not directly applicable to specialized equipment or to special circumstances. Therefore, in some cases, deviations from this part of ISO 21940 are possible.

#### 2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 1925<sup>10)</sup>, Mechanical vibration — Balancing — Vocabulary

ISO 2041, Mechanical vibration, shock and condition monitoring — Vocabulary

ISO 21940-11 $^{11}$ ), Mechanical vibration — Rotor balancing — Part 11: Procedures and tolerances for rotors with rigid behaviour

ISO 21940-14, Mechanical vibration — Rotor balancing — Part 14: Procedures for assessing balance errors

ISO 21940-32, Mechanical vibration — Rotor balancing — Part 32: Shaft and fitment key convention

#### 3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 1925 and ISO 2041 apply.

<sup>10)</sup> To become ISO 21940-2 when revised.

<sup>11)</sup> To be published.