PUBLICLY AVAILABLE SPECIFICATION

ISO/PAS 19295

First edition 2016-04-01

Electrically propelled road vehicles — Specification of voltage sub-classes for voltage class B

cules sses de t. Véhicules routiers à propulsion électrique — Spécification de sous-





© ISO 2016, Published in Switzerland

aroduced or utilized c
te internet or an '
or ISO's memb All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office Ch. de Blandonnet 8 • CP 401 CH-1214 Vernier, Geneva, Switzerland Tel. +41 22 749 01 11 Fax +41 22 749 09 47 copyright@iso.org www.iso.org

Contents	Page
Foreword	iv
Introduction	
1 Scope	1
2 Terms and definitions	1
3 Voltage sub-classes	2
© ISO 2016 - All rights reserved	iii

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: Foreword - Supplementary information

The committee responsible for this document is ISO/TC 22, Road vehicles, Subcommittee SC 37, Electrically propelled vehicles.

Introduction

Electric systems operating at voltage class B are efficient systems for electrically propelled road vehicles. The requirements for voltage class B electric circuits that are used for electric power transfer for the propulsion of electric road vehicles are significantly different to those of voltage class A electric circuits used for powernets at, for example, 12 V d.c. or 24 V d.c.

This PAS provides definition of voltage sub-classes for rechargeable energy storage system (RESS) and electric propulsion system and lists up specified values based on maximum working voltage. Voltage sub-classes listed in this PAS are used for voltage class B systems of all kinds of current or future electrically propelled road vehicles. It enables vehicles manufacturers and automotive supply industry to evaluate the characteristics of a component according to the specified sub-class.

The voltage sub-class itself and the component characteristics have large cost impact on the component design and the overall design of the electric system. A high variety of different voltage sub-class and operating conditions hinders the use of an existing component in different vehicle models.

Today, a huge variety of different RESS and electric propulsion system maximum working voltages are used for electrically propelled road vehicles on the market. Because some systems use voltage boost converters, maximum working voltage of electric propulsion system can be different from that of RESS. This variety of maximum working voltages often results from different numbers of cells in the design of the electrical energy source, e.g. battery stack or variety of power requirement by each vehicle. As a consequence, many system or component designs of a voltage class B electric circuit are currently related to one specific working voltage. When a maximum working voltage is selected for the design, often only one supplier for a component is available. Hence, a change to another component supplier or a change of the dedicated maximum working voltage is not possible, when the system design is finished. It is necessary to reduce the variety of maximum working voltages in order to

- lower the component and system costs by limiting the variety of maximum working voltages,
- decouple the system or component designs of a voltage class B electric circuit from the design of the electric energy source,
- enable an exchange of components from different suppliers during and after the system development and to enable competition and access to the worldwide market for component suppliers, and
- support the system design by specifying basic voltage sub-classes for automotive propulsion systems within voltage class B.

This PAS lists only those RESS and electric propulsion system voltage sub-classes which are used or will be used in current or planned vehicle models and for which electronic parts, e.g. semiconductor switches, are currently available without any restrictions on the market.

The range of voltage class B is too wide to be used for a component design referring to voltage. Therefore, this PAS divides voltage class B in a set of voltages sub-classes, which enable a component design referring to voltage for each voltage sub-class.

This specification is not intended to restrict the development of component performance or technology. It does not exclude the use of other maximum operating voltages for an individual system design.

This document is a preview general ded by tills

Electrically propelled road vehicles — Specification of voltage sub-classes for voltage class B

1 Scope

This PAS provides specification of voltage sub-classes for electric propulsion systems and conductively connected auxiliary electric systems of electrically propelled road vehicles.

The voltage sub-classes are related to d.c. electric circuits.

It applies only to electric circuits and components with maximum working voltages according to voltage class B.

This PAS provides specifications of characteristics which are relevant for design and operation of components and systems for the standardized voltage sub-classes.

It enables vehicle manufacturers and supply industry to evaluate the characteristics of components or systems for their specific vehicle applications.

2 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

2.1

component operating status

describes the general functional behaviour of components which depend directly on the voltage in voltage class B electric circuits

2.2

customer

party that is interested in using voltage class B component or system

2.3

DUT

device under test

2.4

electric circuit

entire set of interconnected live parts through which electrical current is designed to flow under normal operating conditions

2.5

electric propulsion system maximum working voltage

highest value of d.c. voltage that can occur in an electric propulsion system under any normal operating conditions according to the customer's specifications, disregarding transients

2.6

maximum working voltage

highest value of a.c. voltage (rms) or of d.c. voltage that can occur in an electric system under any normal operating condition according to the customer's specifications, disregarding transients

Note 1 to entry: In this definition taken from ISO 6469-3, transients include ripple.