

Engineering data exchange format for use in industrial automation systems engineering - Automation Markup Language - Part 3: Geometry and kinematics

EESTI STANDARDI EESSÕNA

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English Version

Engineering data exchange format for use in industrial
automation systems engineering - Automation markup language -
Part 3: Geometry and kinematics
(IEC 62714-3:2017)

Format d'échange de données techniques pour une
utilisation dans l'ingénierie des systèmes d'automatisation
industrielle - Automation markup language - Partie 3:
Géométrie et cinématique
(IEC 62714-3:2017)

Datenaustauschformat für Planungsdaten industrieller
Automatisierungssysteme - Automation markup language -
Teil 3: Geometrie und Kinematik
(IEC 62714-3:2017)

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European foreword

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Annex ZA

(normative)

Normative references to international publications with their corresponding European publications

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE 1 When an International Publication has been modified by common modifications, indicated by (mod), the relevant EN/HD applies.

NOTE 2 Up-to-date information on the latest versions of the European Standards listed in this annex is available here: www.cenelec.eu.

<u>Publication</u>	<u>Year</u>	<u>Title</u>	<u>EN/HD</u>	<u>Year</u>
IEC 62714-1	2014	Engineering data exchange format for use in industrial automation systems engineering - Automation markup language - Part 1: Architecture and general requirements	EN 62714-1	2014
IEC 62714-2	2015	Engineering data exchange format for use in industrial automation systems engineering - Automation markup language - Part 2: Role class libraries	EN 62714-2	2015
ISO/PAS 17506	-	Industrial automation systems and integration - COLLADA digital asset schema specification for 3D visualization of industrial data	-	-
W3C XML 1.0	2004	Extensible Markup Language (XML) 1.0	-	-

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INTRODUCTION

The data exchange format defined in IEC 62714 (Automation Markup Language, AML) is an XML schema based data format and has been developed in order to support the data exchange between engineering tools in a heterogeneous engineering tool landscape. IEC 62714-1 gives an overview about the format.

The goal of AML is to interconnect engineering tools from the existing heterogeneous tool landscape in their different disciplines, e.g. mechanical plant engineering, electrical design, process engineering, process control engineering, HMI development, PLC programming, robot programming etc.

AML stores engineering information following the object oriented paradigm and allows modelling of physical and logical plant components as data objects encapsulating different aspects. An object may consist of other sub-objects and may itself be part of a larger composition or aggregation. Typical objects in plant automation comprise information on topology, geometry, kinematics and logic, whereas logic comprises sequencing, behaviour and control.

AML combines existing industry data formats that are designed for the storage and exchange of different aspects of engineering information. These data formats are used on “as-is” basis within their own specifications and are not branched for AML needs.

The core of AML is the top-level data format CAEX that connects the different data formats. Therefore, AML has an inherent distributed document architecture.

Figure 1 illustrates the basic AML architecture and the distribution of topology, geometry, kinematic and logic information.

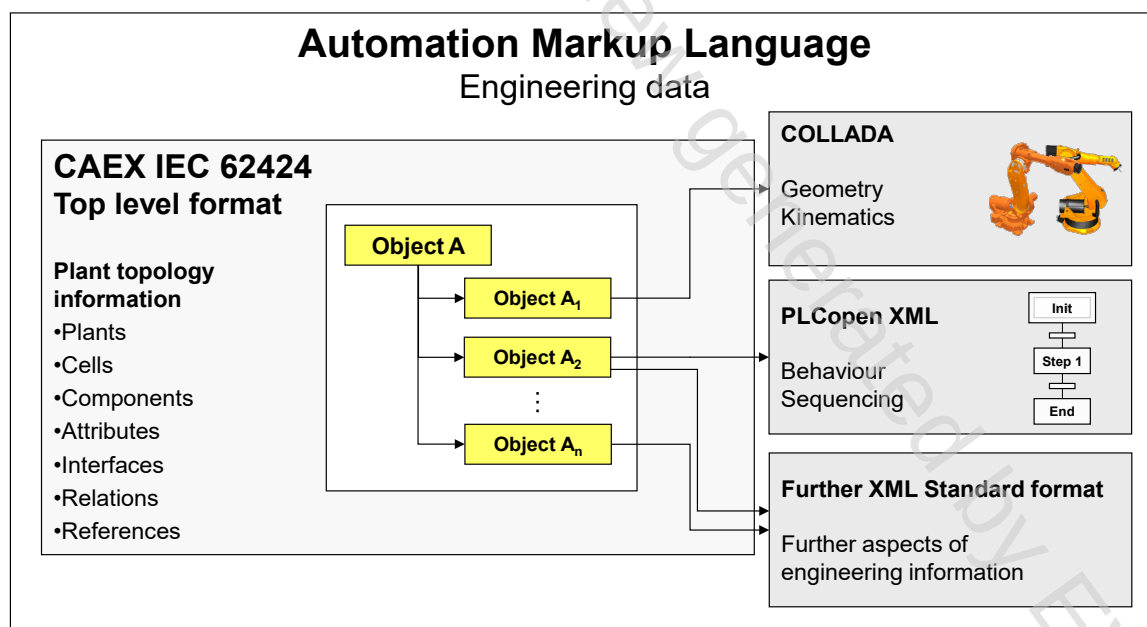


Figure 1 – Overview of the engineering data exchange format AML

Due to the different aspects of AML, IEC 62714 consists of different parts focussing on different aspects.

- IEC 62714-1: Architecture and general requirements

This part specifies the general AML architecture, the modelling of engineering data, classes, instances, relations, references, hierarchies, basic AML libraries and extended AML concepts.

- IEC 62714-2: Role class libraries

This part specifies additional AML libraries.

- IEC 62714-3: Geometry and kinematics

This part specifies the modelling of geometry and kinematics information.

Further parts may be added in the future in order to interconnect further data standards to AML.

Clause 5 describes the geometry related extensions of the role class libraries.

Clause 6 describes the frame attribute which can be used to represent the geometric position of an InternalElement, InstanceHierarchy, SystemUnitClass, or SystemUnitClassLibrary with respect to another CAEX Object.

Clause 7 gives a normative description regarding referencing COLLADA documents.

Clause 8 specifies the normative provisions for the attachment of two geometric AML objects.

Clause 9 defines how to store meta informations about the source tool directly into the COLLADA document.

Annex A describes the referencing methods for geometric and kinematic models.

Annex B provides an example for modelling of kinematic systems and their combination in AML.

Annex C gives an informative XML representation of the libraries defined in this part of IEC 62714.