# **INTERNATIONAL STANDARD**



Second edition 2013-07-15

# Safety devices for protection against excessive pressure —

Si e Part 5: Controlled safety pressure relief systems (CSPRS)

sécurite positifs de s. Dispositifs de sécurité pour protection contre les pressions excessives — Partie 5: Dispositifs de sécurité asservis (CSPRS)

Reference number ISO 4126-5:2013(E)



© ISO 2013

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office Case postale 56 • CH-1211 Geneva 20 Tel. + 41 22 749 01 11 Fax + 41 22 749 09 47 E-mail copyright@iso.org Web www.iso.org

Published in Switzerland

# Contents

Page

Fore	word		iv
1	Scope	P	1
2	Norm	native references	1
3	Term	s and definitions	1
4	Symb	Symbols and units	
5	<b>Desig</b> 5.1 5.2 5.3 5.4	gn General Valve end connections Minimum requirements for springs Materials	<b>7</b> 7 9 10 10
6	Produ 6.1 6.2 6.3 6.4 6.5 6.6 6.7	uction testing   Purpose   General   Hydrostatic testing   Pneumatic testing   Adjustment of set or cold differential test pressure   Seat leakage test   Pressure seals	10 10 10 11 11 11 12 12 12 12
7	<b>Type</b> 7.1 7.2 7.3 7.4 7.5 7.6	testing General Tests to determine operating characteristics Tests to determine flow characteristics Determination of the coefficient of discharge Certification of coefficient of discharge Certification of CSPRS	12 12 14 15 17 17 17
8	Deter	rmination of CSPRS performance	
9	Sizing	g of CSPRS	
10	<b>Mark</b> 10.1 10.2	ing and sealing Marking Sealing of a CSPRS	<b>18</b> 
Bibliography		y	

# Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 4126-5 was prepared by Technical Committee ISO/TC 185, *Safety devices for protection against excessive pressure.* 

This second edition cancels and replaces the first edition (ISO 4126-5:2004), which has been technically revised. It also incorporates the Technical Corrigenda ISO 4126-5:2004/Cor 1:2006 and ISO 4126-5:2004/Cor 2:2007.

ISO 4126 consists of the following parts, under the general title *Safety devices for protection against excessive pressure*:

- Part 1: Safety valves
- Part 2: Bursting disc safety devices
- Part 3: Safety valves and bursting disc safety devices in combination
- Part 4: Pilot operated safety valves
- Part 5: Controlled safety pressure relief systems (CSPRS)
- Part 6: Application, selection and installation of bursting disc safety devices
- Part 7: Common data
- Part 9: Application and installation of safety devices excluding stand-alone bursting disc safety devices
- Part 10: Sizing of safety valves for gas/liquid two-phase flow
- Part 11: Performance testing<sup>1)</sup>

Part 7 contains data that is common to more than one of the parts of ISO 4126 to avoid unnecessary repetition.

<sup>1)</sup> Under development.

# Safety devices for protection against excessive pressure —

# Part 5: Controlled safety pressure relief systems (CSPRS)

# 1 Scope

This part of ISO 4126 specifies the requirements for controlled safety pressure relief systems (CSPRS) irrespective of the fluid for which they are designed.

It is applicable for main valves having a flow diameter of 4 mm and above which are for use at pressures of 0,1 bar gauge and above. No limitation is placed on temperature.

This is a product standard and is not applicable to applications.

# 2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 4126-7:2013, Safety devices for protection against excessive pressure — Part 7: Common data

# 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

#### 3.1

# controlled safety pressure relief system

### CSPRS

system consisting of a main valve in combination with a control unit

Note 1 to entry: See <u>Figure 1</u> for the components of a CSPRS.

Note 2 to entry: On reaching the set pressure, the operating forces on the main valve are by means of the control unit automatically applied, released or so reduced that a main valve discharges a specified quantity of the fluid so as to prevent the predetermined pressure being exceeded. The system is so designed that the main valve re-closes and prevents a further flow of fluid after normal pressure conditions of service have been restored.

Note 3 to entry: Specific types of CSPRS are installed to protect the downstream system by preventing further fluid input (safety shut-off valve). In this case the closing function shall meet the same requirements as the opening function of the relief valve (see <u>5.1.5</u>).

### 3.2

#### main valve

valve consisting of the parts of a CSPRS through which the discharge capacity is achieved, and the actuator

#### 3.3

#### relieving principle

principle in which a main valve opens when the operating force is released or reduced, and in which the main valve closes when the operating force is re-applied

Note 1 to entry: See Figure 2, Type 1.

#### 3.4

#### loading principle

principle in which a main valve opens when the operating force is applied, and in which the main valve closes when the operating force is removed

Note 1 to entry: See Figure 2, Type 2.

#### 3.5

#### control unit

unit which establishes the opening and closing of the main valve

Note 1 to entry: The arrangement shall consist of redundant individual control paths in operation (see 5.1.13 and 5.1.15). The individual control path may consist of pressure tapping line, pressure sensor, sensing line, control module and control line [see Figures 1 a), 1 b) and 1 c), principle for two control paths].

#### 3.6

#### pressure tapping line

line to the pressure sensor

#### 3.7

#### sensing line

line between the pressure sensor and control module

#### 3.8

#### control line

line between the control module and the main valve

#### 3.9

#### pressure sensor

comparator in which a predetermined adjustable value of pressure is compared with the actual system pressure

Note 1 to entry: On reaching the predetermined pressure, a signal is transmitted to the control unit. The signal to the control unit is removed when the system pressure has been lowered to a predetermined pressure.

#### 3.10

#### control module

module which transforms the signal from the pressure sensor into a force to operate the actuator of the main valve

#### 3.11

#### closed circuit principle

principle characterized by the fact that on failure of the external control energy, the control unit effects the loading or relief of the main valve

#### 3.12

#### open circuit principle

principle characterized by the fact that on failure of the external control energy the control unit does not change the loading or relief of the main valve

#### 3.13

#### operating force

force which causes the main valve to operate

#### 3.14

#### set pressure of a CSPRS

predetermined pressure at which a main valve disc under operating conditions commences to open

Note 1 to entry: It is the gauge pressure measured at the main valve inlet at which the pressure forces tending to open the main valve for specified service conditions are in equilibrium with the forces retaining the main valve disc on its seat.

### 3.15

# maximum allowable pressure

PS

maximum pressure for which the protected equipment is designed

### 3.16

### overpressure

pressure increase over the set pressure, usually expressed as a percentage of the set pressure

## 3.17

# reseating pressure

value of the inlet static pressure at which the main valve disc re-establishes contact with the seat or at which the lift becomes zero

### 3.18

### cold differential test pressure

inlet static pressure at which the main valve is set to commence to open on the test bench

Note 1 to entry: This test pressure includes corrections for service conditions, e.g. back pressure and/or temperature.

### 3.19

#### relieving pressure

pressure used for the sizing of a CSPRS which is greater than or equal to the set pressure plus overpressure

#### 3.20

#### blowdown

difference between set and reseating pressures, normally stated as a percentage of set pressure except for pressures of less than 3 bar when the blowdown is expressed in bar

#### 3.21

#### opening sensing pressure

predetermined pressure which activates the pressure sensor



a) Two control lines, relieving principle

52 112-5



### c) Two control lines, loading principle

3.1 pressure tapping line

3.2 pressure sensor

3.4 control module

control line

check valve

protected system

3.3 sensing line

#### Key

- 1 main valve
- 1.1 body
- 1.1.1 inlet port
- 1.1.2 outlet port
- 1.2 actuator
- 1.3 vent
- 2 control unit
- 3 individual control path

# Figure 1 — Typical examples of redundancy for two individual control paths

4

5

6

102 FZ-C