

CONSOLIDATED VERSION

VERSION CONSOLIDÉE



Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

Sécurité des machines – Sécurité fonctionnelle des systèmes de commande électriques, électroniques et électroniques programmables relatifs à la sécurité



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Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

**SAFETY OF MACHINERY –
FUNCTIONAL SAFETY OF SAFETY-RELATED ELECTRICAL,
ELECTRONIC AND PROGRAMMABLE ELECTRONIC
CONTROL SYSTEMS**

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This Consolidated version of IEC 62061 bears the edition number 1.2. It consists of the first edition (2005-01) [documents 44/460/FDIS and 44/470/RVD], its amendment 1 (2012-11) [documents 44/655/CDV and 44/663/RVC] and its amendment 2 (2015-06) [documents 44/718/CDV and 44/725/RVC]. The technical content is identical to the base edition and its amendments.

In this Redline version, a vertical line in the margin shows where the technical content is modified by amendments 1 and 2. Additions and deletions are displayed in red, with deletions being struck through. A separate Final version with all changes accepted is available in this publication.

International Standard IEC 62061 has been prepared by IEC technical committee 44: Safety of machinery – Electrotechnical aspects.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

The committee has decided that the contents of the base publication and its amendments will remain unchanged until the stability date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- amended.

The contents of the corrigenda 1 (July 2005) and 2 (April 2008) have been included in this copy.

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INTRODUCTION

As a result of automation, demand for increased production and reduced operator physical effort, Safety-Related Electrical Control Systems (referred to as SRECS) of machines play an increasing role in the achievement of overall machine safety. Furthermore, the SRECS themselves increasingly employ complex electronic technology.

Previously, in the absence of standards, there has been a reluctance to accept SRECS in safety-related functions for significant machine hazards because of uncertainty regarding the performance of such technology.

This International Standard is intended for use by machinery designers, control system manufacturers and integrators, and others involved in the specification, design and validation of a SRECS. It sets out an approach and provides requirements to achieve the necessary performance.

This standard is machine sector specific within the framework of IEC 61508. It is intended to facilitate the specification of the performance of safety-related electrical control systems in relation to the significant hazards (see 3.8 of ISO ~~12100-1~~ 12100:2010) of machines.

This standard provides a machine sector specific framework for functional safety of a SRECS of machines. It only covers those aspects of the safety lifecycle that are related to safety requirements allocation through to safety validation. Requirements are provided for information for safe use of SRECS of machines that can also be relevant to later phases of the life of a SRECS.

There are many situations on machines where SRECS are employed as part of safety measures that have been provided to achieve risk reduction. A typical case is the use of an interlocking guard that, when it is opened to allow access to the danger zone, signals the electrical control system to stop hazardous machine operation. Also in automation, the electrical control system that is used to achieve correct operation of the machine process often contributes to safety by mitigating risks associated with hazards arising directly from control system failures. This standard gives a methodology and requirements to

- assign the required safety integrity level for each safety-related control function to be implemented by SRECS;
- enable the design of the SRECS appropriate to the assigned safety-related control function(s);
- integrate safety-related subsystems designed in accordance with ISO 13849 ;
- validate the SRECS.

This standard is intended to be used within the framework of systematic risk reduction described in ISO ~~12100-1~~ 12100 and in conjunction with risk assessment according to the principles described in ISO ~~14121 (EN 1050)~~ 12100. A suggested methodology for safety integrity level (SIL) assignment is given in informative Annex A.

Measures are given to co-ordinate the performance of the SRECS with the intended risk reduction taking into account the probabilities and consequences of random or systematic faults within the electrical control system.

Figure 1 shows the relationship of this standard to other relevant standards.

~~Table 1 gives recommendations on the recommended application of this standard and the revision of ISO 13849-1.~~

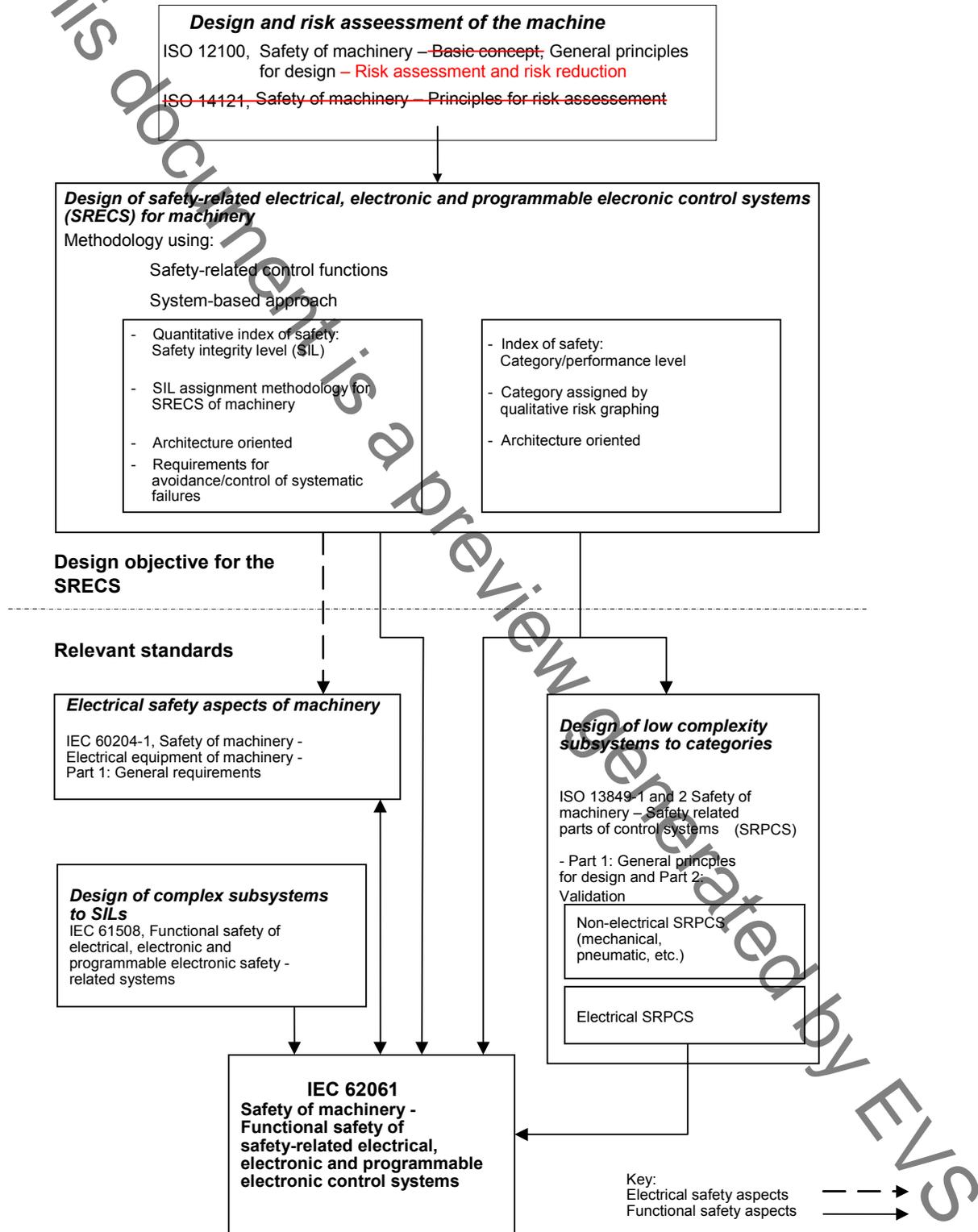


Figure 1 – Relationship of IEC 62061 to other relevant standards

~~Information on the recommended application of IEC 62061 and ISO 13849-1 (under revision)~~

IEC 62061 and ISO 13849-1 ~~(under revision)~~ specify requirements for the design and implementation of safety-related control systems of machinery. The use of either of these standards, in accordance with their scopes, can be presumed to fulfil the relevant essential safety requirements. ~~Table 1 summarises the scopes of IEC 62061 and ISO 13849-1 (under revision).~~ IEC/TR 62061-1 provides guidance on the application of IEC 62061 and ISO 13849-1 in the design of safety-related control systems for machinery.

~~NOTE—ISO 13849-1 is currently under preparation by ISO TC 199 and CEN TC 114.~~

Table 1—Recommended application of IEC 62061 and ISO 13849-1 ~~(under revision)~~

	Technology implementing the safety-related control function(s)	ISO-13849-1 (under revision)	IEC 62061
A	Non-electrical, e.g. hydraulics	X	Not covered
B	Electromechanical, e.g. relays, or non-complex electronics	Restricted to designated architectures (see Note 1) and up to PL=e	All architectures and up to SIL 3
C	Complex electronics, e.g. programmable	Restricted to designated architectures (see Note 1) and up to PL=d	All architectures and up to SIL 3
D	A combined with B	Restricted to designated architectures (see Note 1) and up to PL=e	X see Note 3
E	C combined with B	Restricted to designated architectures (see Note 1) and up to PL=d	All architectures and up to SIL 3
F	C combined with A, or C combined with A and B	X see Note 2	X see Note 3
<p>"X" indicates that this item is dealt with by the standard shown in the column heading.</p> <p>NOTE 1—Designated architectures are defined in Annex B of EN ISO 13849-1(rev.) to give a simplified approach for quantification of performance level.</p> <p>NOTE 2—For complex electronics: Use of designated architectures according to EN ISO 13849-1(rev.) up to PL=d or any architecture according to IEC 62061.</p> <p>NOTE 3—For non-electrical technology use parts according to EN ISO 13849-1(rev.) as subsystems.</p>			

SAFETY OF MACHINERY – FUNCTIONAL SAFETY OF SAFETY-RELATED ELECTRICAL, ELECTRONIC AND PROGRAMMABLE ELECTRONIC CONTROL SYSTEMS

1 Scope

This International Standard specifies requirements and makes recommendations for the design, integration and validation of safety-related electrical, electronic and programmable electronic control systems (SRECS) for machines (see Notes 1 and 2). It is applicable to control systems used, either singly or in combination, to carry out safety-related control functions on machines that are not portable by hand while working, including a group of machines working together in a co-ordinated manner.

NOTE 1 In this standard, the term “electrical control systems” is used to stand for “Electrical, Electronic and Programmable Electronic (E/E/PE) control systems” and “SRECS” is used to stand for “safety-related electrical, electronic and programmable electronic control systems”.

NOTE 2 In this standard, it is presumed that the design of complex programmable electronic subsystems or subsystem elements conforms to the relevant requirements of IEC 61508 and uses Route 1_H (see IEC 61508-2:2010, 7.4.4.2). It is considered that Route 2_H (see IEC 61508-2:2010, 7.4.4.3) is not suitable for general machinery. Therefore, this standard does not deal with Route 2_H. This standard provides a methodology for the use, rather than development, of such subsystems and subsystem elements as part of a SRECS.

This standard is an application standard and is not intended to limit or inhibit technological advancement. It does not cover all the requirements (e.g. guarding, non-electrical interlocking or non-electrical control) that are needed or required by other standards or regulations in order to safeguard persons from hazards. Each type of machine has unique requirements to be satisfied to provide adequate safety.

This standard:

- is concerned only with functional safety requirements intended to reduce the risk of injury or damage to the health of persons in the immediate vicinity of the machine and those directly involved in the use of the machine;
- is restricted to risks arising directly from the hazards of the machine itself or from a group of machines working together in a co-ordinated manner;

NOTE 3 Requirements to mitigate risks arising from other hazards are provided in relevant sector standards. For example, where a machine(s) is part of a process activity, the machine electrical control system functional safety requirements should, in addition, satisfy other requirements (e.g. IEC 61511) insofar as safety of the process is concerned.

- does not specify requirements for the performance of non-electrical (e.g. hydraulic, pneumatic) control elements for machines;

NOTE 4 Although the requirements of this standard are specific to electrical control systems, the framework and methodology specified can be applicable to safety-related parts of control systems employing other technologies.

- does not cover electrical hazards arising from the electrical control equipment itself (e.g. electric shock – see IEC 60204–1).

The objectives of specific Clauses in IEC 62061 are as given in Table 2.

Table 2 – Overview and objectives of IEC 62061

Clause	Objective
4: Management of functional safety	To specify the management and technical activities which are necessary for the achievement of the required functional safety of the SRECS.
5: Requirements for the specification of safety-related control functions	To set out the procedures to specify the requirements for safety-related control functions. These requirements are expressed in terms of functional requirements specification, and safety integrity requirements specification.
6: Design and integration of the safety-related electrical control system	To specify the selection criteria and/or the design and implementation methods of the SRECS to meet the functional safety requirements. This includes: selection of the system architecture, selection of the safety-related hardware and software, design of hardware and software, verification that the designed hardware and software meets the functional safety requirements.
7: Information for use of the machine	To specify requirements for the information for use of the SRECS, which has to be supplied with the machine. This includes: provision of the user manual and procedures, provision of the maintenance manual and procedures.
8: Validation of the safety-related electrical control system	To specify the requirements for the validation process to be applied to the SRECS. This includes inspection and testing of the SRECS to ensure that it achieves the requirements stated in the safety requirements specification.
9: Modification of the safety-related electrical control system	To specify the requirements for the modification procedure that has to be applied when modifying the SRECS. This includes: modifications to any SRECS are properly planned and verified prior to making the change; the safety requirements specification of the SRECS is satisfied after any modifications have taken place.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60204–1, *Safety of machinery – Electrical equipment of machines – Part 1: General requirements*

IEC 61000-6-2, *Electromagnetic compatibility (EMC) – Part 6-2: Generic standards – Immunity for industrial environments*

IEC 61310 (all parts), *Safety of machinery – Indication, marking and actuation*

IEC 61508-2, *Functional safety of electrical/electronic/ programmable electronic safety-related systems – Part 2: Requirements for electrical/electronic/programmable electronic safety-related systems*

IEC 61508-3, *Functional safety of electrical/electronic/programmable electronic safety-related systems – Part 3: Software requirements*

~~ISO 12100-1:2003, Safety of machinery – Basic concepts, general principles for design – Part 1: Basic terminology, methodology~~

~~ISO 12100-2:2003, Safety of machinery – Basic concepts, general principles for design – Part 2: Technical principles~~

ISO 12100:2010, Safety of machinery – General principles for design – Risk assessment and risk reduction

ISO 13849-1:1999 2006, Safety of machinery – Safety-related parts of control systems – Part 1: General principles for design

ISO 13849-2:2003 2012, Safety of machinery – Safety-related parts of control systems – Part 2: Validation

~~ISO 14121, Safety of machinery – Principles of risk assessment~~

3 Terms, definitions and abbreviations

3.1 Alphabetical list of definitions

Term	Definition number
application software	3.2.46
architectural constraint	3.2.36
architecture	3.2.35
common cause failure	3.2.43
complex component	3.2.8
control function	3.2.14
dangerous failure	3.2.40
demand	3.2.25
diagnostic coverage	3.2.38
electrical control system	3.2.3
embedded software	3.2.47
failure	3.2.39
fault	3.2.30
fault tolerance	3.2.31
full variability language (FVL)	3.2.48
function block	3.2.32
function block element	3.2.33
functional safety	3.2.9
hardware safety integrity	3.2.20
hazard (from machinery)	3.2.10
hazardous situation	3.2.11
high demand or continuous mode	3.2.27
limited variability language (LVL)	3.2.49