
UAS traffic management (UTM) —
Part 5:
UTM functional structure

Gestion du trafic des aéronefs sans pilote (UTM) —
Partie 5: Structure fonctionnelle de l'UTM



This document is a preview generated by ELS



COPYRIGHT PROTECTED DOCUMENT

© ISO 2023

All rights reserved. Unless otherwise specified, or required in the context of its implementation, no part of this publication may be reproduced or utilized otherwise in any form or by any means, electronic or mechanical, including photocopying, or posting on the internet or an intranet, without prior written permission. Permission can be requested from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office
CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva
Phone: +41 22 749 01 11
Email: copyright@iso.org
Website: www.iso.org

Published in Switzerland

Contents

	Page
Foreword	iv
Introduction	v
1 Scope	1
2 Normative references	1
3 Terms and definitions	1
3.1 UTM constituent related terms.....	1
3.2 UA operation related terms.....	2
4 General recommendations	2
5 Classification of UTM functionalities	3
5.1 Functional categories.....	3
5.2 UTM functions.....	4
5.2.1 General.....	4
5.2.2 Registration function.....	4
5.2.3 Flight information management function.....	4
5.2.4 Operation plan management function.....	5
5.2.5 Position data management function.....	6
5.2.6 Reporting function.....	6
5.2.7 Supplemental data supply function.....	6
6 UTM functional structure	7
6.1 Functional structure and configuration.....	7
6.2 Relationships and interactions among UTM functions.....	8
Annex A (informative) Design models comparison of UTM frameworks and approach to determining UTM functions	10
Bibliography	14

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO document should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

ISO draws attention to the possibility that the implementation of this document may involve the use of (a) patent(s). ISO takes no position concerning the evidence, validity or applicability of any claimed patent rights in respect thereof. As of the date of publication of this document, ISO had not received notice of (a) patent(s) which may be required to implement this document. However, implementers are cautioned that this may not represent the latest information, which may be obtained from the patent database available at www.iso.org/patents. ISO shall not be held responsible for identifying any or all such patent rights.

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 20, *Aircraft and space vehicles*, Subcommittee SC 16, *Unmanned aircraft systems*.

A list of all parts in the ISO 23629 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

The market expects rapid growth of civil unmanned aircraft system (UAS) operations in the near future. To manage growing operations, several states are making an effort to develop UAS traffic management (UTM). However, this can cause a lack of harmonization among countries and affect safety, security, the environment, system reliability and economic efficiency.

Some organizations have already created models and references of UTM functional structure, for example, existing documents and ongoing discussion in other organizations such as ASTM to create the UTM functional structure. These models are recognised to share a lot of common aspects.

To avoid discordance, the creation of a generic UTM functional structure as a basis of further developments is needed. The reference functional structure can serve as a mechanism to evaluate and compare different UTM systems and can foster adoption of better technologies and solutions.

The UTM structure and core functions are to be harmonized with the following perspectives:

- creating terms and definitions related to core functions of UTM referencing existing international standards;
- listing existing documents and ongoing discussion related to UTM functional structure;
- creating a common UTM structure;
- checking contradiction and inconsistency between terms and definition and UTM structure.

UAS traffic management (UTM) —

Part 5: UTM functional structure

1 Scope

This document is dedicated to establishing a common understanding of UTM core functions and functional structure. It provides a detailed description of the UTM system layer given in the UTM Framework.

This document excludes:

- role-sharing among entities constituting UTM, which is left to implementations;
- technical methodology of communication or data transaction among core functions;
- business model of players engaging in a function of UTM.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 21384-4, *Unmanned aircraft systems — Part 4: Vocabulary*

ISO 23629-12, *UAS traffic management (UTM) — Part 12: Requirements for UTM service providers*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 21384-4, ISO 23629-12 and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

3.1 UTM constituent related terms

3.1.1

UTM function

function which constitutes UTM and contributes to safe UA operation

3.1.2

UTM functional structure

UTM structure in functional perspective which consists of mutual complementary and interacting *UTM functions* ([3.1.1](#))